FURUNO

TECDIS

Installation Manual

A fully type approved Electronic Chart and Display Information System (ECDIS), certified by DNV.

Software edition: 4.7.x.x
Manual edition: 2.4

⚠ SAFETY INSTRUCTIONS

⚠ WARNING

Do not open the equipment unless totally familiar with electrical circuits and service manual.

ELECTRICAL SHOCK HAZARD

Only qualified personnel should work inside the equipment.

Turn off the power at the mains switch-board before beginning the installation.

Fire, electrical shock or serious injury can result if the power is left on or is applied while the equipment is being installed.

Do not install the monitor unit, processor unit or control unit where they may get wet from rain or water splash.

Water in the units can result in fire, electrical shock, or damage the equipment.

Be sure that the power supply is compatible with the voltage rating of the equipment.

Connection of an incorrect power supply can cause fire or damage the equipment .

Use only the specified power cable.

Fire or damage to the equipment can result if a different cable is used.

⚠ WARNING

The PC Main board is equipped with a litium battery. The lithium battery should be replaced only in the factory.

There is a danger of explosion if the wrong type of battery is used for replacement.

⚠ CAUTION

Attach securely protection earth to the ship's body.

The protection earth (grounding) is required to the AC power supply to prevent electrical shock.

Observe the following compass safe distances to prevent interference to a magnetic compass:

	Standard compass	Steering compass
HT405P4 TEL-A1	2.2m	1.5m
HT C01 TEL-A599	1.55m	0.95m
HT C01 TEL-A596	1.55m	0.95m
HT C01 TEL-D596	1.55m	0.95m
JH 19T14 MMD	0.85m	0.45m
JH 20T17 MMD	0.75m	0.35m
JH 23T12 MMD	1.6m	1.05m
JH 23T14 MMD	0.6m	0.25m
HD19T03	0.8m	0.5m
Furuno MU-201CE	2.25m	1.4m
Furuno MU-231CE	2.55m	1.55m
BTC5100C PS/2	0.3m	0.3m
G84-4100LCMGB-2	0.8m	0.6m
Keytouch Panels	0.2m	0.25m
DNH HP-6	1.5m	1.0m
DHN HPS-6	1.5m	1.0m
Furuno RCU-018	0.3m	0.3m

Table of contents

General introduction to the installation manual

This manual is describing the procedure to ensure a proper and safe installation of our TECDIS onboard a vessel. Please read carefully this manual before you start up the commissioning of the TECDIS.

The installation and commissioning of the TECDIS must be performed by an authorized service engineer, which has undertaken training or in other forms gained the required skills to perform an authorized installation of a TECDIS system onboard a vessel.

To ensure a professional after-sale service and a personal track-record of TECDIS installations, we recommend that the service engineer saves the default setup file to floppy disk or other media. He can then keep this file in his personal register of TECDIS installations.

The file is located at: C:\Program files\TECDIS\dta4.setup, or C:\Program files\TECDIS\Telchart.ini (if present).

Please note the following:

All position inputs to TECDIS from all external sensors must be in WGS-84 datum.

If connected to internet to provide C-Map Update Service functionality, a switch must be made available to disconnect TECDIS from internet when C-Map Update Service functionality is not in use.

Checklist to verify the proper installation of the TECDIS shall be filled in and filed onboard. For TECDIS TCS and TECDIS AW, a copy of this checklist shall be sent to Telko AS for full type approval compliance. For all versions of TECDIS, it is strongly recommended that a copy is stored in the installer's archives and that a copy is sent to Furuno Norway or Telko AS.

Refer to Chapter 1 and Chapter 2 for installation requirements and/or limitations for specific hardware components.

It is recommended that TECDIS is supplied by UPS (uninterrupted power supply) 220VAC or emergency power, this should include also TECDIS backup (if installed) and other hardware related to the TECDIS installation. A dedicated UPS should be supplied to each TECDIS (if dual installation). The UPS or emergency power should have sufficient capacity to supply all required equipment for a period of at least 60 seconds.

Standards Compliance

TECDIS conforms to the following standard(s) or other normative documents:

Version 4.7.1 and higher:

- Marine Equipment Directive, Module B (MED-B)
- IMO Resolution MSC.232(82)
- IMO Resolution MSC.191(79)
- IMO Resolution MSC.74(69) Annex 2,
- IMO Resolution A.694(17).

Version 4.6.0 to 4.7.0:

- Marine Equipment Directive, Module B (MED-B)
- IMO Resolution MSC.74(69) Annex 2,
- IMO Resolution A.817(19) as amended by MSC.64(67) Annex 5 and by MSC.86/70) Annex 4
- IMO Resolution A.694(17).

For a current overview of software versions, standards compliance and instructions for updating TECDIS software to comply with new standards and regulations, refer to the following web site:

http://www.telko.no/site/support/tecdis/compliance

Equipment lists

Standard Supply

Name	Type	Qty	Remarks
Computer (AC)	HT C01 TEL-A596	1	1,9 m power cable
Monitor	JH 20T17 MMD	1	2,0 m video cable 1,9 m power cable
Keyboard	Cherry G84-4100LCMGB-2	1	1,3 m cable
Mouse	Mouse-trak B-MPIND-XROHS	1	1,9 m cable

Optional Supply

Name	Type	Qty	Remarks
Computer (DC)	HT C01 TEL-D596	1	1,9 m power cable
Monitor	JH 19T14 MMD	1	2,0 m video cable 1,9 m power cable
Monitor	JH 23T14 MMD	1	2,0 m video cable 1,9 m power cable
Monitor	HD 19T03	1	2,0 m video cable 1,9 m power cable
Monitor	Furuno MU-201CE	1	2,0 m video cable 1,9 m power cable
Monitor	Furuno MU-231CE	1	2,0 m video cable 1,9 m power cable
Telko Alarm Interface	TEA-01	1	1,4 m cable
19" rack kit for computer	HT 00223 OPT-A1	1	
Bracket for monitor	JH MMD BR	1	
Audio amplifier PCI card	HT 00072 OPT-A1	1	
Speaker (bracket mount)	DNH HP-6 (See note 1)	1	0,5 m cable
Speaker (flush mount)	DNH HPS-6 (See note 1)	1	0,5 m cable
Control Unit	Furuno RCU-018	1	
Keyboard	Keytouch Panel QWERTY	1	1,9m USB cable
Keyboard	BTC-5100C	1	1,3 m cable
Trackball	Keytouch Panel Trackball	1	1,9m USB cable
Keyboard and trackball	Keytouch Panel Combo	1	1,9m USB cable

Note 1: Loudspeaker required when display unit or control unit does not contain a buzzer

Installation Overview
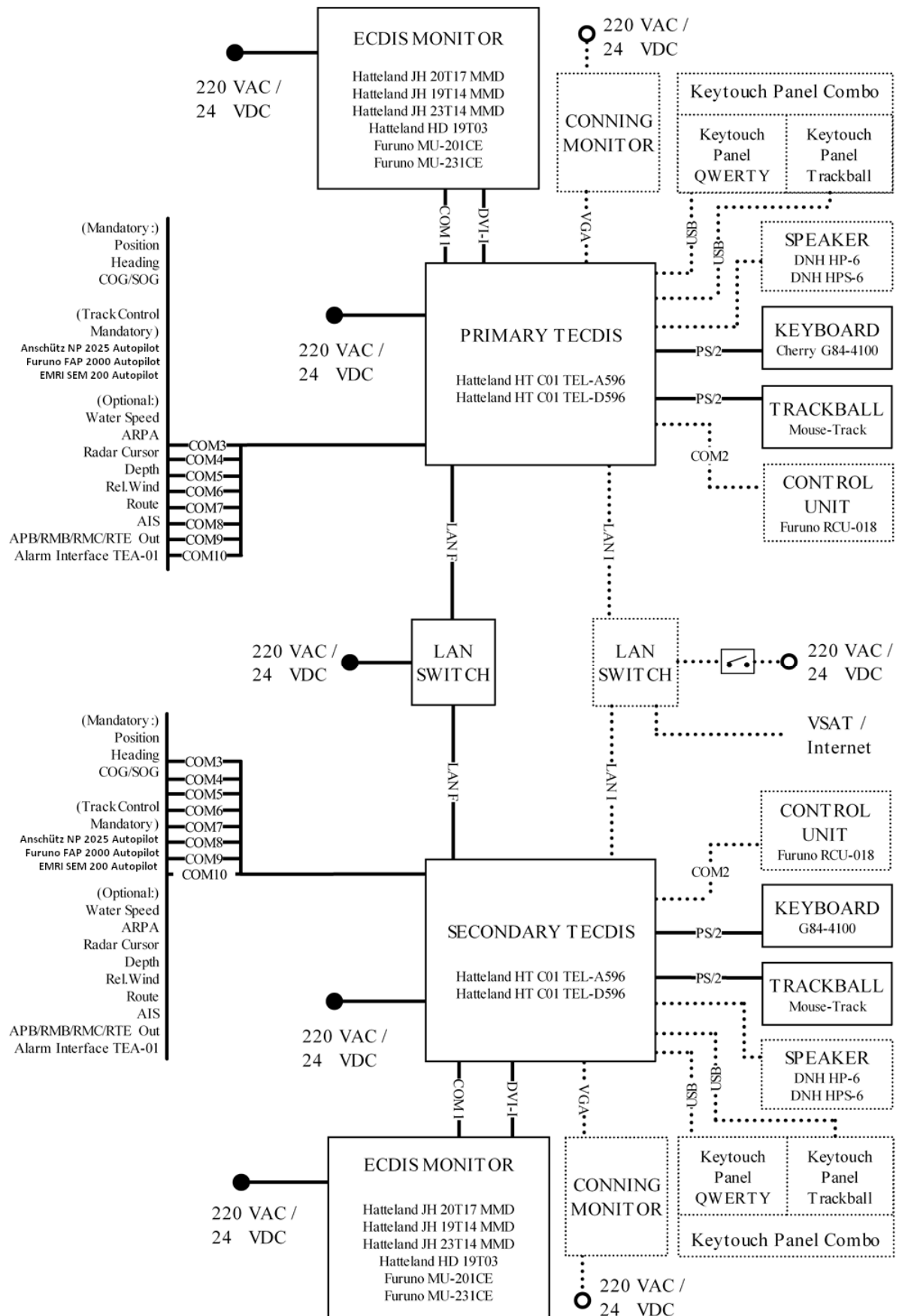
Specifications:

Processor HT C01 TEL-A596 / Processor HT C01 TEL-D596

• Compact high end industrial computer
• Intel Core 2 Duo E8400 – 3.0 GHz
• Dual Head integrated video card
  Intel GMA 3100
• 2GB RAM (8GB Max)
• Automotive 250 GB 2.5" Hard drive
• DVD/CD-R/W Dual (48x/16x/6x/8x)
• 4x 10/100/1000Mbps Ethernet LAN
• 1x RS-232 Serial Port
• 8 ports optoisolated RS-232 / RS-422
  serial interface MOXA CP118U-I
• 1x Furuno RCU-018 Connector
• 1x Parallel Port
• 10x USB 2.0 ports
• Standard PS/2 (keyboard & mouse)
• Dim: 345 (W) x 133 (H) x 390 (D) mm
• TEL-A596: 110/230V (330W) (70W typical)
• TEL-D596: 24 VDC (220W) (70W typical)

Monitor JH 19T14 MMD:

• 19,0 inch viewable image size
• Active matrix, Thin Film Transistor
• Pixel number: 1280 x 1024
• Pixel pitch (RGB): 0,294 mm H/V
• Response time: 12 ms
• Contrast ratio: 900:1
• Light intensity: 300 cd/m2
• Viewable angle: +- 85 deg. H/V/L/R
• Display area: 376.32x301.056 mm H/V
• Auto detects VGA to SXGA
• Optimum picture with 60 Hz
• Input signal: DVI-D, DVI-D input 24pin
• Input signal: RGB, 15pin HD D-SUB
• Input signal: Multifunction
• AC power: 115 VAC/ 60 Hz
  230 VAC/ 50 Hz (100 W max)
• Weight: 11,5 kg

Monitor JH 20T17 MMD:

• 20,1 inch viewable image size
• A-Si (Thin Film Transistor) Active matrix,
• Pixel number: 1600x1200
• Pixel pitch (RGB): 0,255 mm H/V
• Response time: 20 ms
• Contrast ratio: 700:1
• Light intensity: 300 cd/m2
• Viewable angle: +- 85 deg. H/V/L/R
• Active display area: 408x306 mm H/V
• Auto detects VGA to SXGA
• Optimum picture with 60 Hz
• Input signal: DVI-D, DVI-D input 24pin
• Input signal: RGB, 15pin mini D-SUB
• Input signal: Multifunction
• AC power: 115 VAC/ 60 Hz
  230 VAC/ 50 Hz (100 W max)
• Weight: 13,5 kg

Monitor JH 23T14 MMD:

• 23,1 inch viewable image size
• Thin Film Transistor Active matrix,
• Pixel number: 1600x1200
• Pixel pitch (RGB): 0,294 mm H/V
• Response time: 12 ms
• Contrast ratio: 600:1
• Light intensity: 400 cd/m2
• Viewable angle: +- 85 deg. H/V/L/R
• Active display area: 470.4x352.8 mm H/V
• Auto detects VGA to UXGA
• Optimum picture with 60 Hz
• Input signal: DVI-I, DVI-I input 29pin
• Input signal: RGB, 15pin mini D-SUB
• Input signal: Multifunction
• AC power: 115 VAC/ 60 Hz
  230 VAC/ 50 Hz + 24 VDC
  (95 W typ – 125 W max)
• Weight: 20 kg

Monitor HD 19T03:

- 19,0 inch viewable image size
- Active matrix, Thin Film Transistor
- Pixel number: 1280 x 1024
- Pixel pitch (RGB): 0,294 mm H/V
- Response time: 12 ms
- Contrast ratio: 600:1
- Light intensity: 450 cd/m2
- Viewable angle: +- 89 deg. H/V/L/R
- Display area: 376.32x301.056 mm H/V
- Auto detects VGA to XGA
- Optimum picture with 60 Hz
- Input signal: DVI-I, 24pin
- Input signal: RGB, 15pin HD D-SUB
- Input signal: Multifunction
- AC power: 115 VAC/ 60 Hz
  230 VAC/ 50 Hz (66 W max)
- Weight: 9 kg (approx)

Monitor Furuno MU-201CE:

- 20,0 inch viewable image size
- Active matrix, Thin Film Transistor
- Pixel number: 1280 x 1024
- Pixel pitch (RGB): 0,301 mm H/V
- Contrast ratio: 600:1
- Light intensity: 250 cd/m2
- Viewable angle: +- 85 deg. H/V/L/R
- Display area: 396.75x317.25 mm H/V
- Auto detects VGA to SXGA
- Optimum picture with 60 Hz
- Input signal: DVI-I, 29pin
- Input signal: RGB / DVI-A (DVI connector)
- Input signal: S-Video
- Control input / output: RS-232 D-sub 9pin
- Power: 90 - 265 VAC rms 50/60 Hz +- 5 Hz
  (55 W typical)
- Weight: 10 kg (approx)

Monitor Furuno MU-231CE:

- 23,1 inch viewable image size
- Active matrix, Thin Film Transistor
- Pixel number: 1600 x 1200
- Pixel pitch (RGB): 0,294 mm H/V
- Contrast ratio: 500:1
- Light intensity: 250 cd/m2
- Viewable angle: +- 80 deg. H/V/L/R
- Display area: 470.4x352.8 mm H/V
- Auto detects VGA to SXGA
- Optimum picture with 60 Hz
- Input signal: DVI-I, 29pin
- Input signal: RGB / DVI-A (DVI connector)
- Input signal: S-Video
- Control input / output: RS-232 D-sub 9pin
- Power: 90 - 265 VAC rms 50/60 Hz +- 5 Hz
  (60 W typical)
- Weight: 15 kg (approx)

Keytouch Panel Combo:

- Flush mount QWERTY keyboard and trackball
- 85 (+3) short travel switches
- Polyester with key embossing
- Key switch lifetime 200.000 operations
- IP22 protection level
- Connection: USB type B
- Dimmable backlight
- Light sensor for backlight and LED dimming
- Dim: 413 (W) x 196 (H) mm
- Cutout: 363 (W) x 177 (H) mm

Keytouch Panel QWERTY:

- Flush mount QWERTY keyboard
- 85 short travel switches
- Polyester with key embossing
- Key switch lifetime 200.000 operations
- IP22 protection level
- Connection: USB type B
- Dimmable backlight
- Light sensor for backlight and LED dimming
- Dim: 321,2 (W) x 196 (H) mm
- Cutout: 301 (W) x 176 (H) mm

Keytouch Panel Trackball:

- Flush mount trackball
- Ball diameter: 50mm
- Ball reading: Laser
- 3 short travel switches
- Polyester with key embossing
- Key switch lifetime 200.000 operations
- IP22-67 protection level
- Connection: USB
- Dim: 124 (W) x 196 (H) mm
- Cutout: 104 (W) x 176 (H) mm

Mouse-Trak B-MPIND-XROHS:

Functional Specifications:

Resolution:	192 to 576 pulses per revolution of the ball.
Input Switches:	Three (3)
Interface:	IBM PS/2
Connector:	6-Pin Mini-DIN Male
Pin Assignments:	Pin 1 = PS/2 Data Pin 2 = NC Pin 3 = Common Pin 4 = +5V Pin 5 = PS/2 clock Pin 6 = NC
Compatibility:	Microsoft PS/2 Mouse Protocol, Logitech PS/2 Mouse Protocol
Switches:	Mechanically limited, break resistant
Cable:	96"+-0.5"
Power Consumption:	Idle: 8mA Max: 12mA

Mechanical Specifications:

Dimensions:	Approximately 4"wide x 8"long
Weight:	1.3 lbs.
Body Material:	Glass filled Xenoy thermoplastic, black
Ball Material:	Cast Phenolic Resin
Ball Hardness:	Rockwell H 85
Tracking Force:	1.5 oz. maximum, 0.5 oz. typical (15g)
Ball Load:	250 lbs. maximum downward
Ball Speed:	500 RPM maximum
Hand Pad:	Injection-molded vinyl, black

Environmental Specifications:

Operating Temperature:	0 to +50 degrees Celsius
Storage Temperature:	-20 to +60 degrees Celsius
Humidity:	0 to 95% non condensing

Speaker HP-6/HPS-6:

Material/Color	Polyamide UL94 V0 / RAL 7035
Mounting	Bracket
Termination	Cable,0,5m
Weight	0.5 kg
IP-rating (UL Equivalent)	(-) 67
Max. / min. amb. Temp	90°C / -40 °C
Rated / max. power	6W / 15W
SPL 1W/1m	101 db
SPL rated power	108 db
Effective freq. range	500 – 7500 Hz
Dispersion (-6dB) 1kHz / 4kHz	170° / 70°
Directivity factor, Q	4,3

Telchart Alarm interface, TEA-01:

Outputs: (connector 1,2,3,4)
are a solid state relay LCA110E which has capabilities of max 50VDC, max 200mA.
Input: (connector 5,6)
uses a current limited (6.8 Kohm resistor) opto coupler MCT5211. Reset in at 10-30 VDC.
All input and outputs are electrically isolated.
Shield shall be connected at alarm central side.
Shield are connected in Dsubmin 9f. connector,
but are not cross connected in the interface box.
A 1.5 m Cable with Dsubmin 9p female (PC-serial port) in one end and an interface box with 7 screw terminal in the other end.

Wiring info:
(1)> Alarm Out - (NO)
(2)> Alarm Out + (NO)
(3)> Sound Alarm out reset - (NO)
(4)> Sound Alarm out reset + (NO)
(5)< Sound Alarm inp. Reset – (NO)
(6)< Sound Alarm inp. Reset + (NO)
(7)- Cable shield
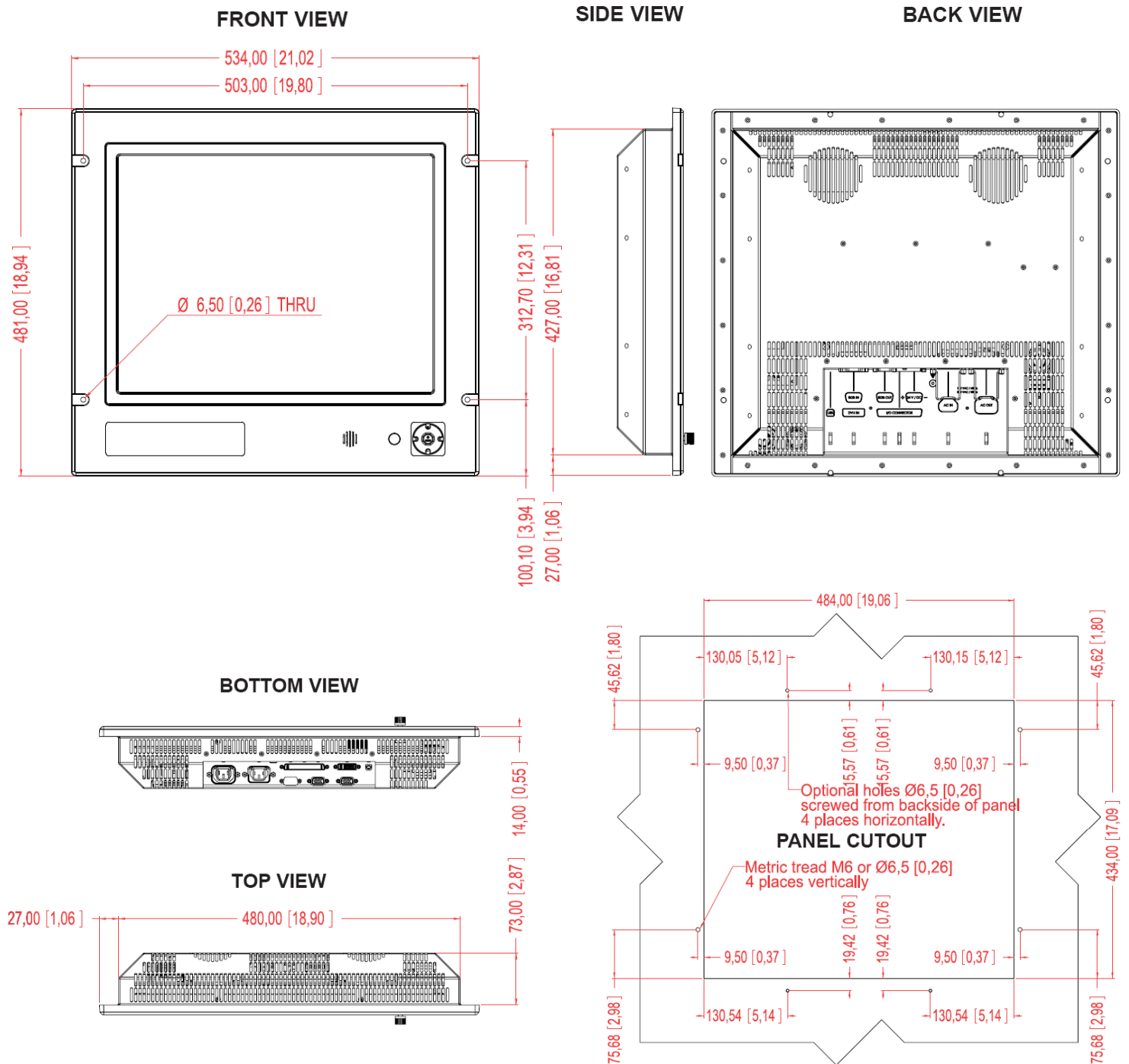
Chapter 1: Mounting

1.1 Monitor Unit

The monitor unit can be flush mounted in a console panel, or mounted on desktop using optional accessories.

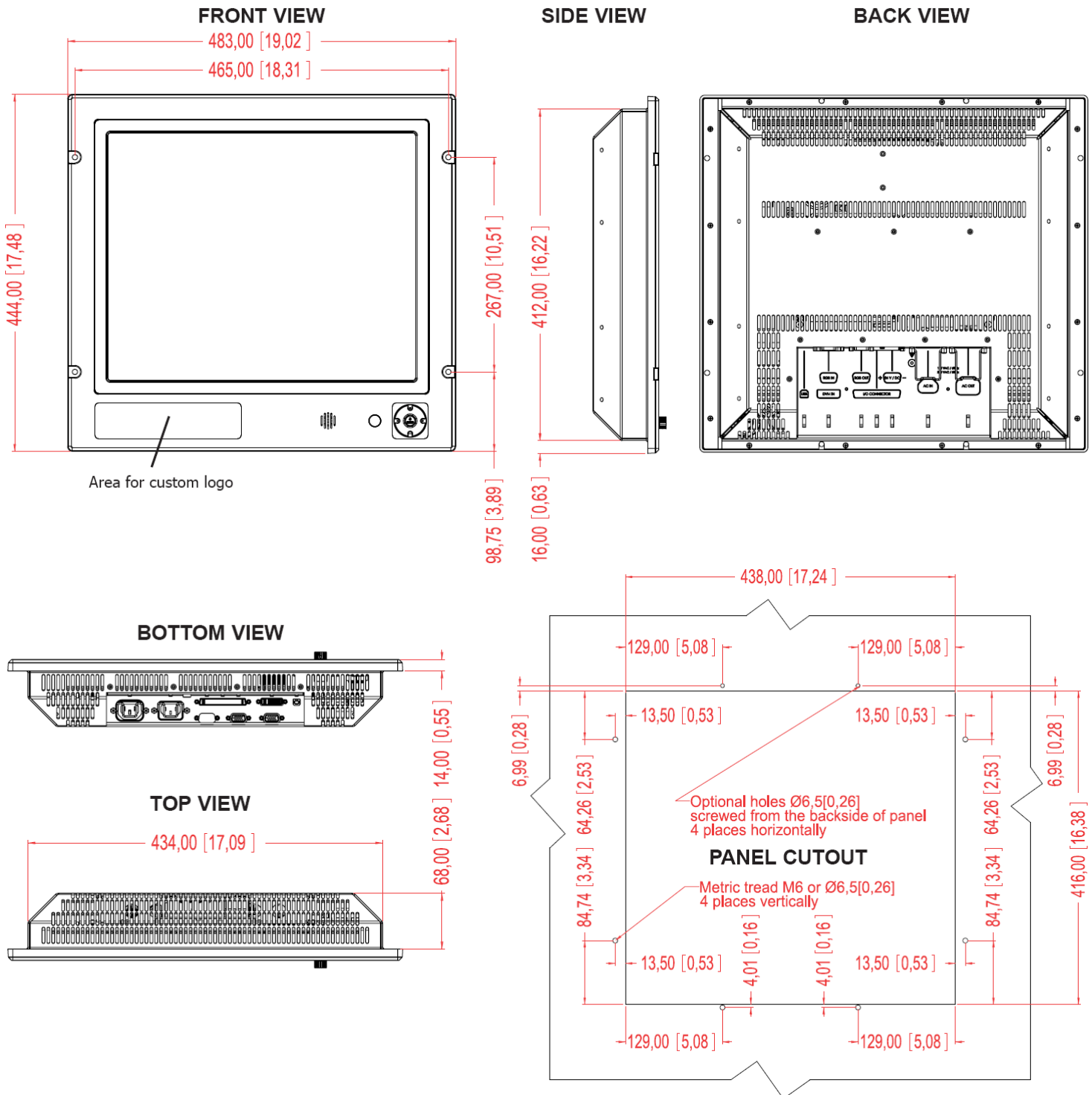When selecting a mounting location, keep in mind the following points:
1. Select a location where the display unit can be viewed conveniently and where the screen can be viewed while facing towards the bow.
2. Select a location where vibrations are down to a minimum, try to avoid vibrations by adding strength to console where monitor is about to be installed.
3. Locate the unit out of direct sunlight and away from heat sources because of heat that can build up inside the cabinet.
4. Locate the equipment away from places subject to water splash and rain.
5. Leave sufficient space on the sides and rear of the unit to facilitate maintenance.
6. A magnetic compass will be affected if the monitor unit is placed too close to the magnetic compass. Observe the compass safe distances to prevent deviation of a magnetic compass.
7. An optional monitor bracket can be supplied for tabletop installations.

Screws for mounting the monitor to the console are supplied. When bracket is used screws for attaching bracket and monitor together is supplied. Screws for mounting bracket to table are not supplied.

The buzzer in monitor HD19T03 is only approved for ECDIS alarm sound when the monitor is not flush mounted.

Outline dimensions for JH 20T17 MMD:

FRONT VIEW   **SIDE VIEW**   **BACK VIEW**

534,00 [21,02]
503,00 [19,80]
481,00 [18,94]
Ø 6,50 [0,26] THRU
312,70 [12,31]
427,00 [16,81]
100,10 [3,94]
27,00 [1,06]

BOTTOM VIEW

14,00 [0,55]

TOP VIEW

27,00 [1,06]
480,00 [18,90]
73,00 [2,87]

484,00 [19,06]
45,62 [1,80]
130,05 [5,12]
130,15 [5,12]
45,62 [1,80]
9,50 [0,37]
15,57 [0,61]
15,57 [0,61]
9,50 [0,37]
Optional holes Ø6,5 [0,26]
screwed from backside of panel
4 places horizontally.

PANEL CUTOUT

434,00 [17,09]
Metric tread M6 or Ø6,5 [0,26]
4 places vertically
19,42 [0,76]
19,42 [0,76]
9,50 [0,37]
9,50 [0,37]
75,68 [2,98]
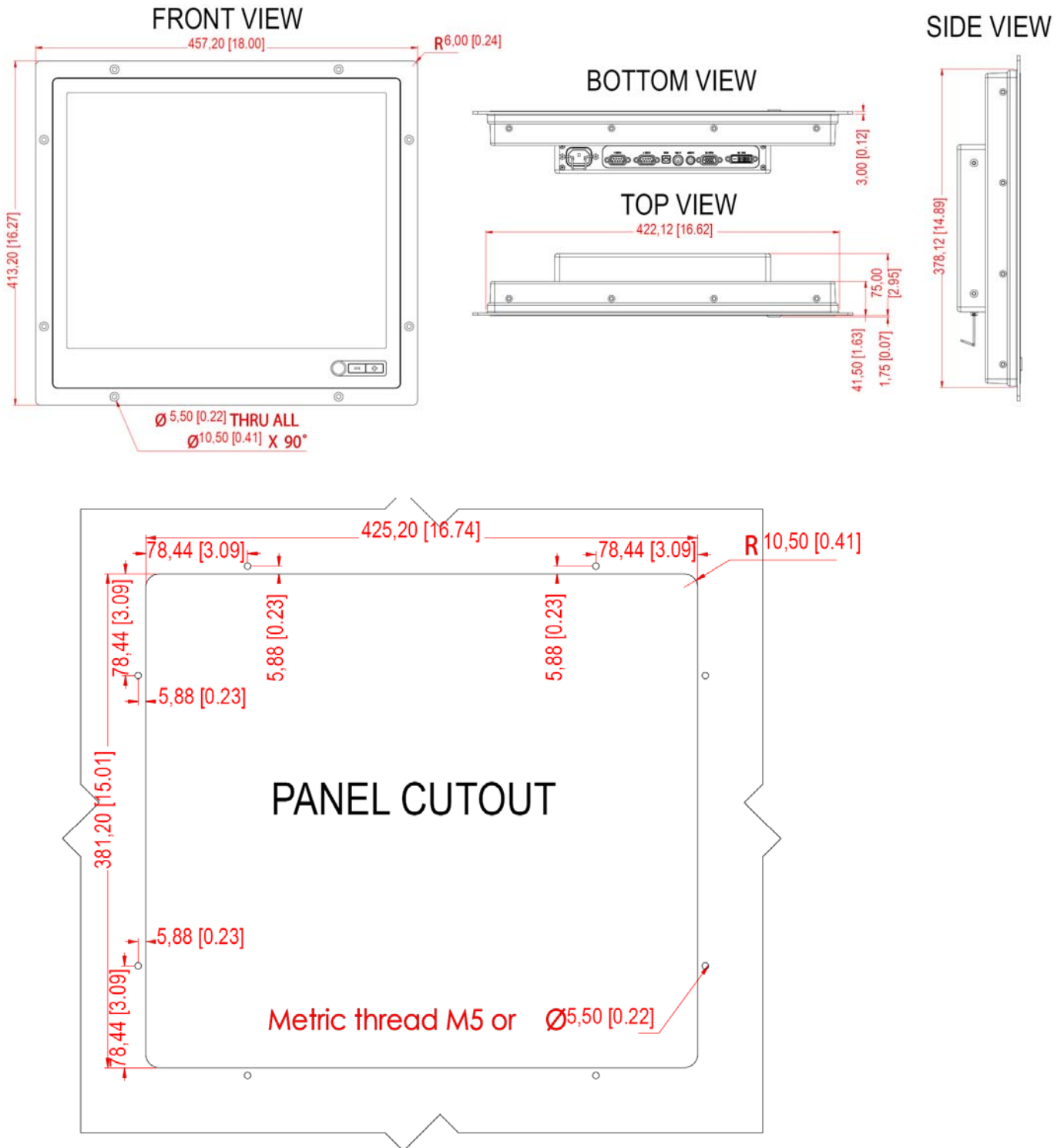130,54 [5,14]
130,54 [5,14]
75,68 [2,98]

Dimensions might be shown with or without decimals and indicated as mm [inches]. Tolerance on drawings is +/- 1mm. For accurate measurements, check relevant DWG file, as obtainable from http://www.hatteland-display.com/maritime_line_displays_series1.php.

Outline dimensions for JH 19T14 MMD:

FRONT VIEW

483,00 [19,02]
465,00 [18,31]
444,00 [17,48]
267,00 [10,51]

Area for custom logo

98,75 [3,89]

SIDE VIEW

412,00 [16,22]
16,00 [0,63]

BACK VIEW

BOTTOM VIEW

14,00 [0,55]

TOP VIEW

434,00 [17,09]
68,00 [2,68]

438,00 [17,24]
129,00 [5,08]   129,00 [5,08]
13,50 [0,53]   13,50 [0,53]
6,99 [0,28]
64,26 [2,53]

Optional holes Ø6,5[0,26]
screwed from the backside of panel
4 places horizontally

PANEL CUTOUT

Metric tread M6 or Ø6,5[0,26]
4 places vertically

84,74 [3,34]
13,50 [0,53]   13,50 [0,53]
4,01 [0,16]   4,01 [0,16]
129,00 [5,08]   129,00 [5,08]
6,99 [0,28]
64,26 [2,53]
84,74 [3,34]
416,00 [16,38]

Dimensions might be shown with or without decimals and indicated as mm [inches]. Tolerance on drawings is +/- 1mm. For accurate measurements, check relevant DWG file, as obtainable from http://www.hatteland-display.com/maritime_line_displays_series1.php.

Outline dimensions for JH 23T14 MMD:

FRONT VIEW   SIDE VIEW   BACK VIEW

BOTTOM VIEW

TOP VIEW

PANEL CUTOUT
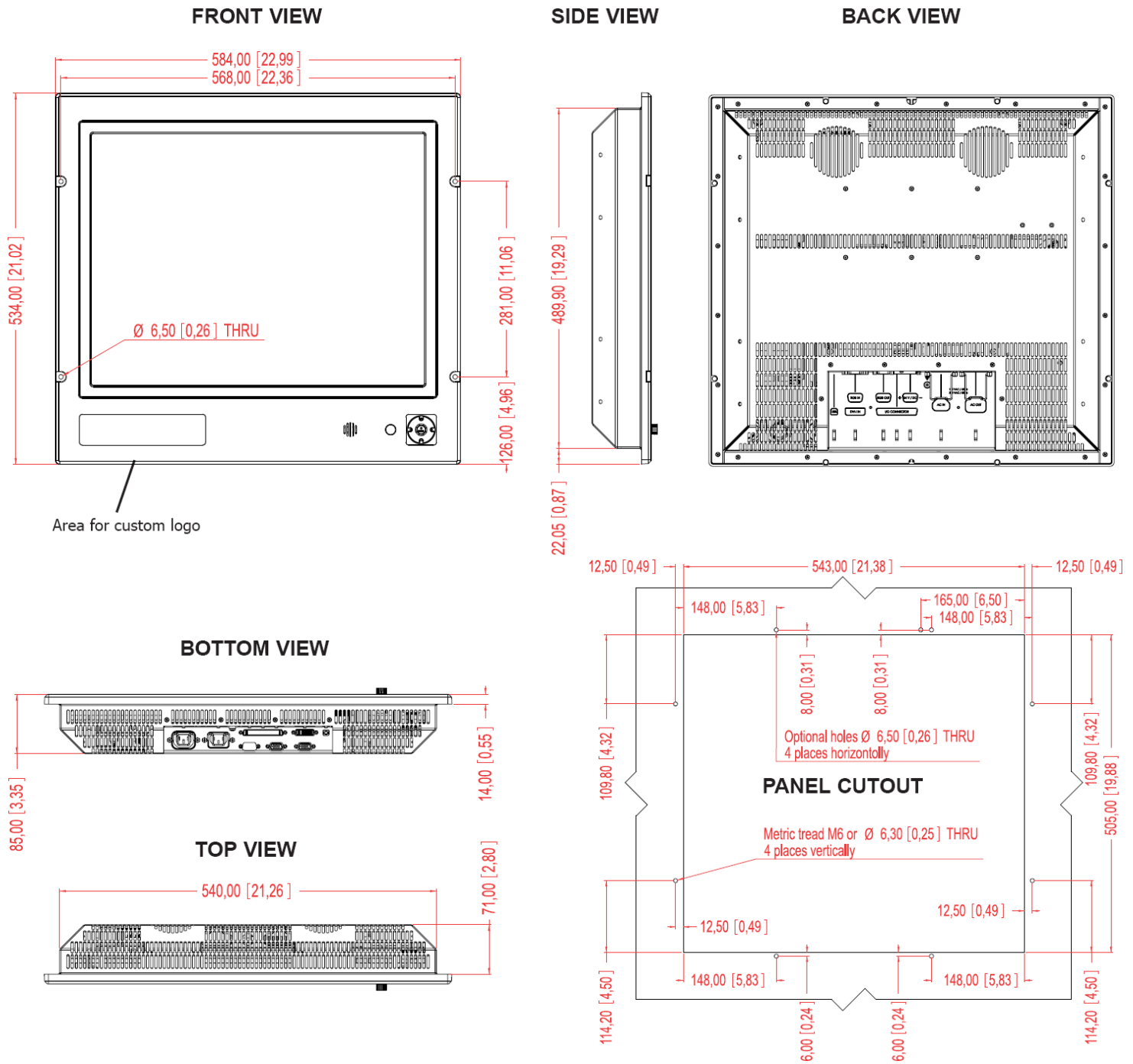
Dimensions might be shown with or without decimals and indicated as mm [inches]. Tolerance on drawings is +/- 1mm. For accurate measurements, check relevant DWG file, as obtainable from http://www.hatteland-display.com/maritime_line_displays_series1.php.

Outline dimensions for HD 19T03 (COBA model shown):

Dimensions might be shown with or without decimals and indicated as mm [inches]. Tolerance on drawings is +/- 1mm. For accurate measurements, check relevant DWG file, as obtainable from http://www.hatteland-display.com/portfolio_displays_series2.php.

Outline dimensions for Furuno MU-201CE:

Outline dimensions for Furuno MU-231CE:
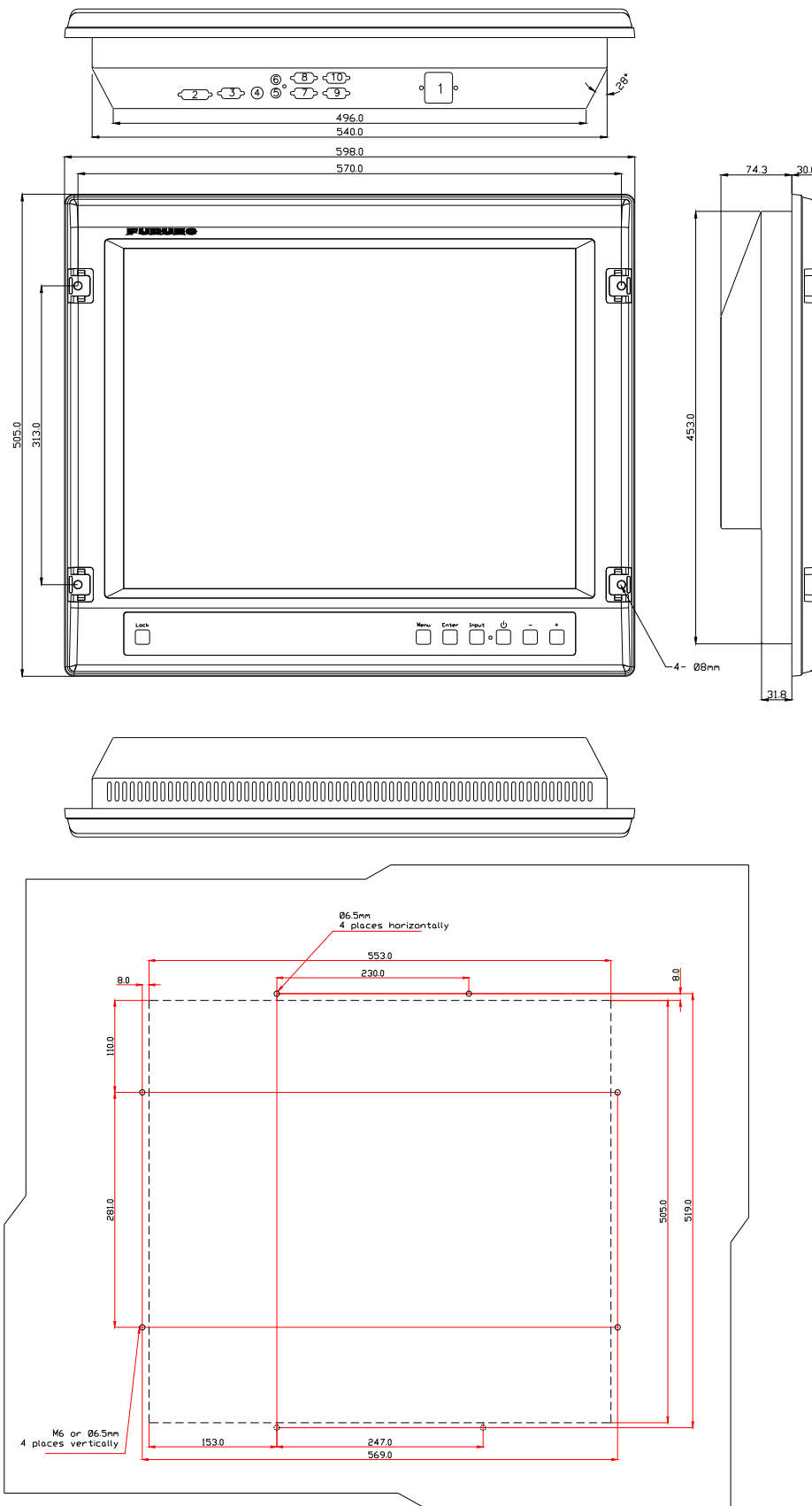
1.2   <u>Processor Unit</u>

The processor unit can be mounted inside on bridge console or other suitable space on the bridge.

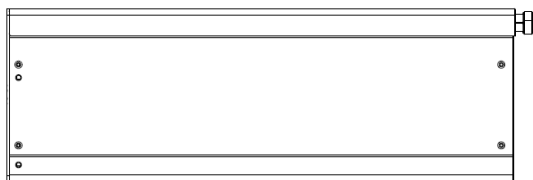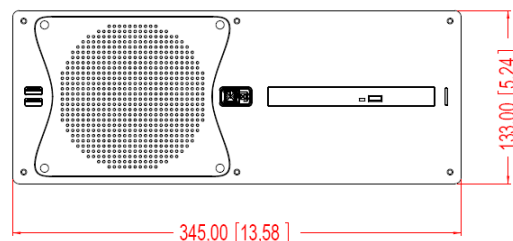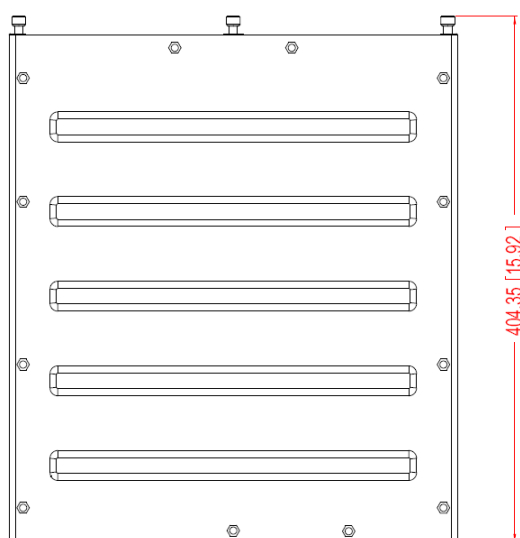When selecting a mounting location, keep in mind the following points:
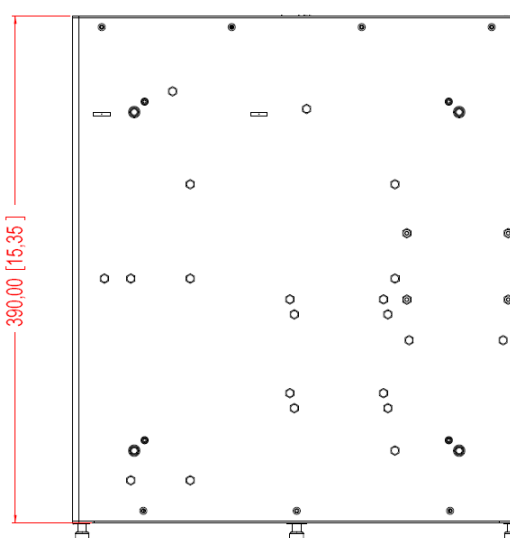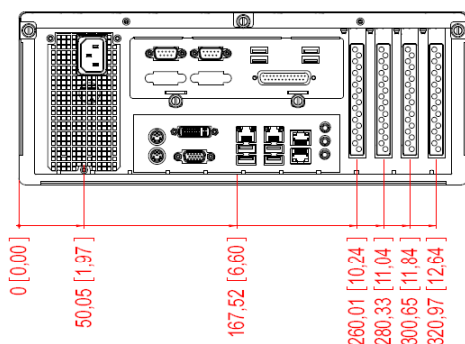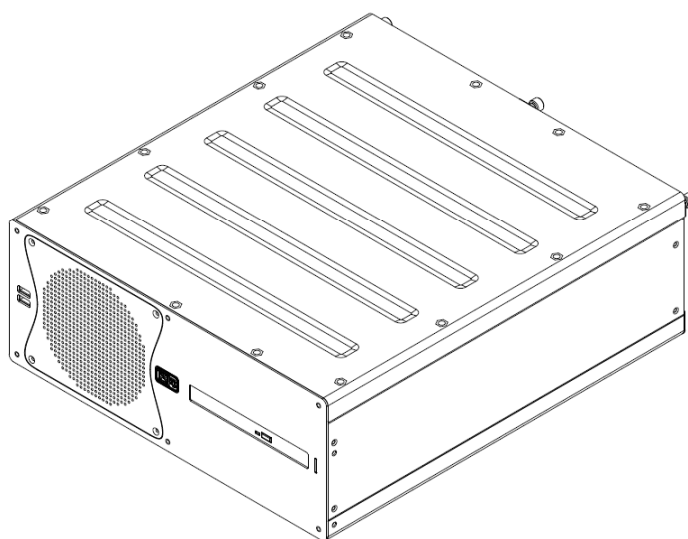1. Select a location where vibrations are down to a minimum, try to avoid vibrations by adding strength to console where the processor is about to be installed.
2. Locate the unit away from heat sources because of heat that can build up inside the cabinet.
3. Locate the equipment away from places subject to water splash and rain.
4. Leave sufficient space on the sides and rear of the unit to facilitate maintenance and interconnection cabling.
5. **Navigator shall update charts in the processor weekly. Mount the processor at a location that enables the navigator easy access to front doors of the processor. It must be possible to open CD drawer of processor without obstructions.**
6. **The power switch shall be easily to access, front of processor may be flush mounted in the console to enable access or other means to be provided for easy access.**
7. Service key dongle must be possible to remove and insert to enable service technician to enter service mode.
8. MOXA 8-port RS-422 connection box to be arranged close to processor to enable easy interconnection. MOXA is supplied with 1,5 m interface cable between processor and connection box.

Do not protrude the housing with screws to fasten the processor. Straps should be used to fasten the processor at its location, without protruding the housing. Straps are not supplied and must be arranged locally. Check that front doors of processor can easily be opened and that cables can easily arranged in the back of the processor.
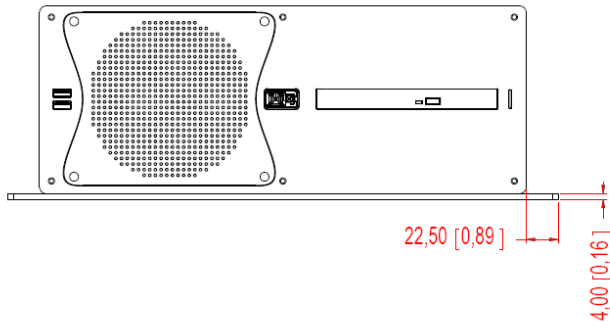
The processor is suitable for 19" rack-mounting with optional rack mounting kit. Height is 4U.
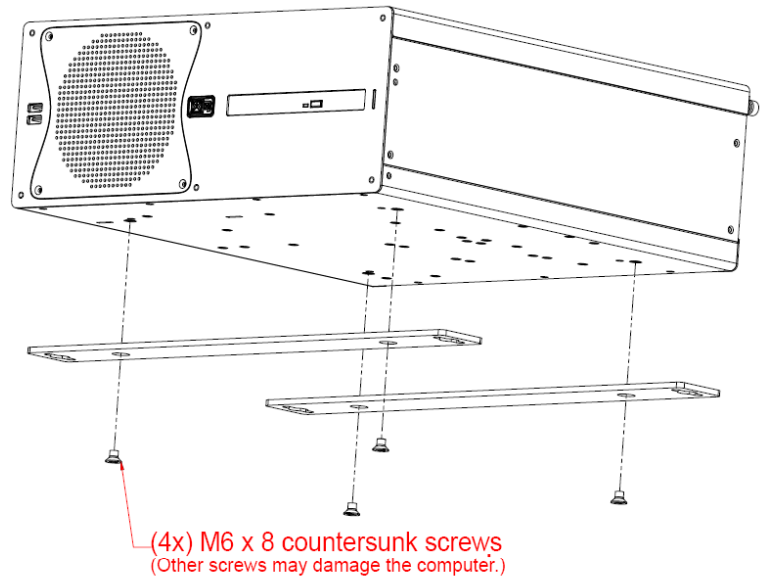
Outline dimensions for HT C01 TEL-A596 / D596:   All figures in mm [inches].

SIDE VIEW   FRONT VIEW

133,00 [5,24]

345,00 [13,58]

TOP VIEW   BOTTOM VIEW

404,35 [15,92]

390,00 [15,35]

BACK VIEW   DIMETRIC VIEW

0 [0,00]
50,05 [1,97]
167,52 [6,60]
260,01 [10,24]
280,33 [11,04]
300,65 [11,84]
320,97 [12,64]

Mounting bracket for HT C01 TEL-A596 / D596 (included):   All figures in mm [inches].

FRONT VIEW

22,50 [0,89]
4,00 [0,16]

EXPLODED VIEW

(4x) M6 x 8 countersunk screws
(Other screws may damage the computer.)

BOTTOM VIEW

74,60 [2,94]
260,00 [10,24]
69,75 [2,75]
364,00 [14,33]

2 x Ø 6,60[0,26] THRU ALL
Ø 12,60[0,50]   X 90°

R3,25 [0,13]
R7,00 [0,28]

24,00 [0,94]

250,00 [9,84]
364,00 [14,33]
390,00 [15,35]

22,50 [0,89]
45,00 [1,77]
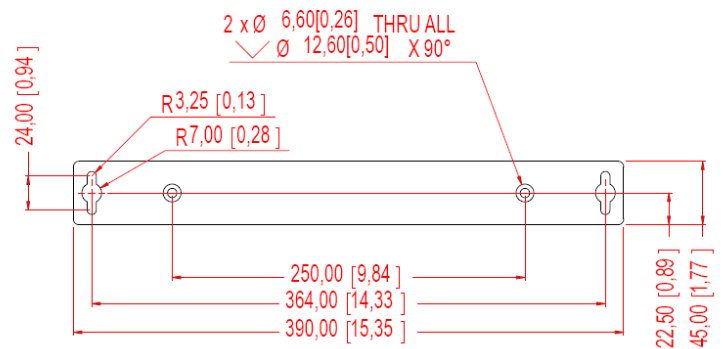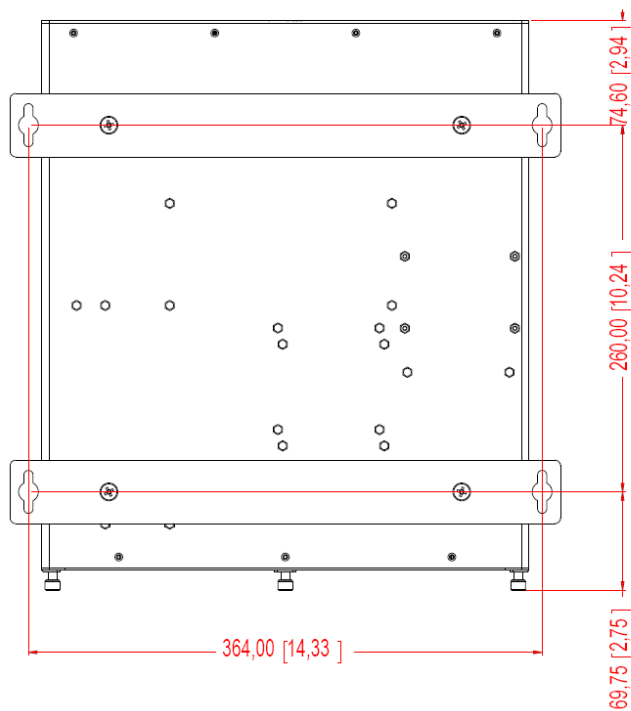
Other drawings, including 19" rack kit 4U (HT 00223 OPT-A1), are available from the following URL:

http://www.hatteland-display.com/computer_htc01.php

1.3   Control Unit Furuno RCU-018

The control unit may be mounted on a desktop, with or without the KB fixing metal (supplied), which mounts the control unit at an angle.

Mounting considerations

When selecting a mounting location, keep in mind the following points:
- Select a location where the control unit can be operated conveniently.
- Locate the unit away from heat sources because of heat that can build up inside the cabinet.
- Locate the equipment away from places subject to water splash and rain.
- Determine the mounting location considering the length of the signal cable between the control unit and the processor unit.
- A magnetic compass will be affected if the control unit is placed too close to the magnetic compass. Observe the compass safe distances specified at the start of this manual to prevent deviation of a magnetic compass.

Fixing with KB fixing plate

1. Fix the KB fixing plate to the bottom of the control unit.
2. Attach three cushions to the bottom of the control unit.
3. Fix it to a desired location with self-tapping screws (local supply).

Fixing without KB fixing metal

1. Drill four mounting holes of 5 mm diameter referring to the outline drawing.
2. Fix the control unit with four screws (M4) from under side of the desktop. (The M4 screws with a sufficient length for the thickness of the desktop should be provided locally.)

Flush mounting

Use the optional flush mount kit Furuno FP03-09870 to mount the control unit to a console panel.
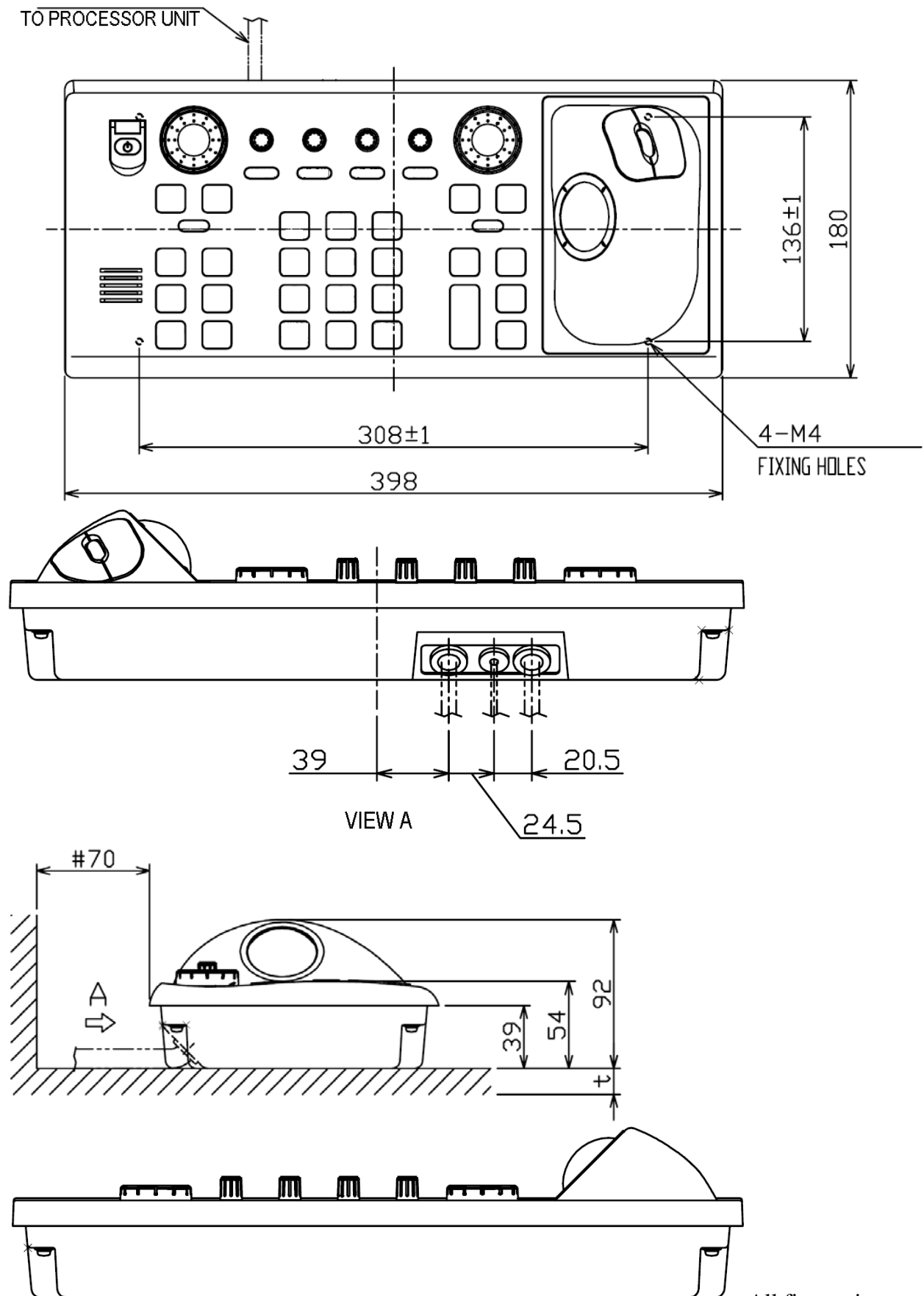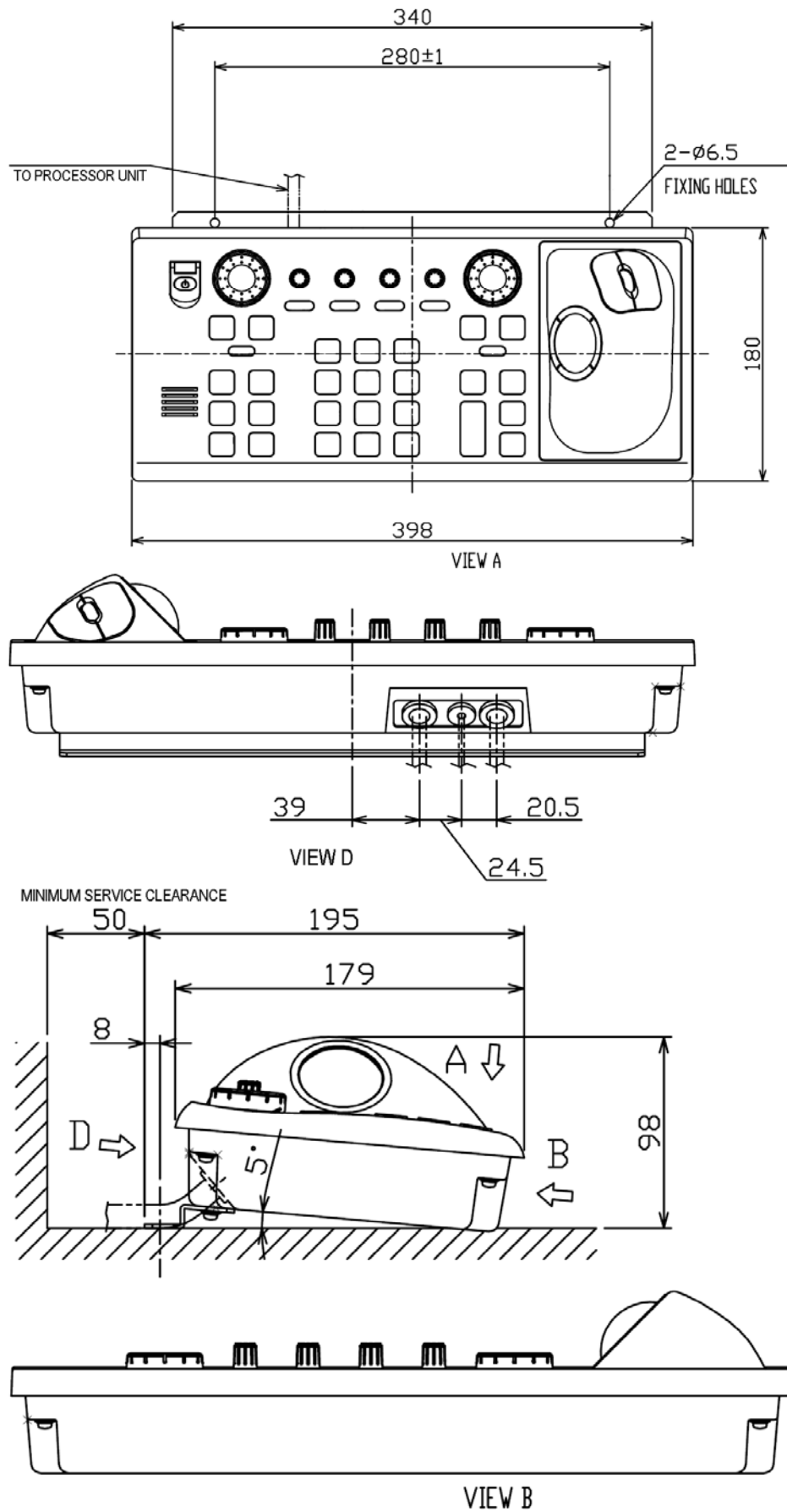
Name: Flush mount kit
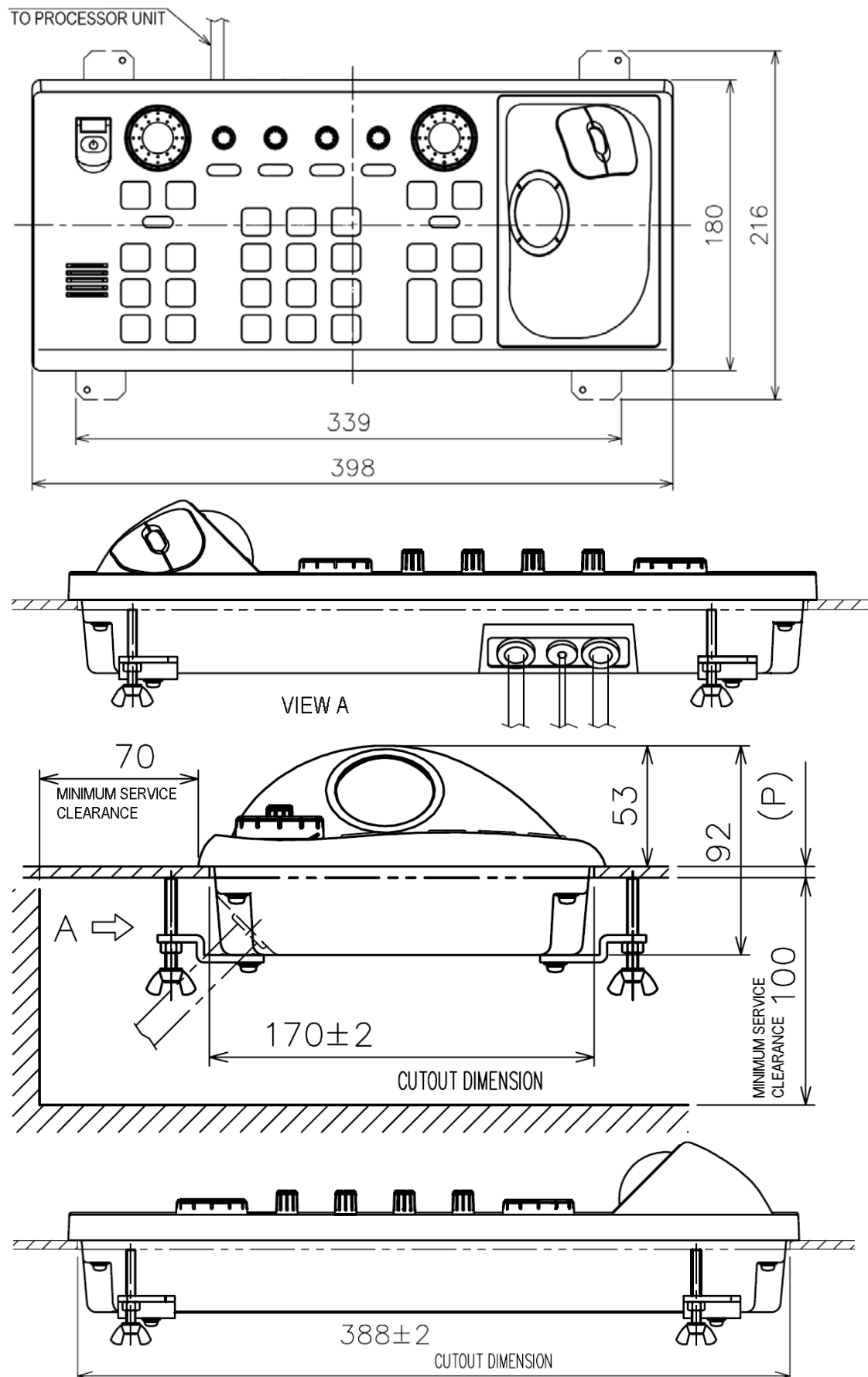Type: Furuno FP03-09870
Code No.: 008-535-630

No.	Name	Type	Qty
1	Mount plate	03-163-7531	4
2	Hex bolt	M4	4
3	Wing screw	M4X30	4

1. Prepare a cutout in the mounting location as shown in the outline figures.
2. Set the control unit to the cutout.
3. Attach the mounting plate to the control unit with four screws from the rear side.
4. Screw the wing screw to each mounting plate and then insert hex bolt to each wing screw.
5. Fasten each wing screw and then fasten the hex nuts as shown in the outline figures.

Furuno RCU-018 Control Unit outline (Desktop mount)

TO PROCESSOR UNIT

136±1
180

308±1
398

4-M4
FIXING HOLES

39
20.5
VIEW A
24.5

#70
92
54
39
t
A

All figures in mm.

Furuno RCU-018 Control Unit outline (Desktop mount with bracket)

All figures in mm

Furuno RCU-018 Control Unit outline (Flush mount)

TO PROCESSOR UNIT

180
216

339
398

VIEW A

70
MINIMUM SERVICE CLEARANCE

A ⇒

53
92
(P)

MINIMUM SERVICE CLEARANCE 100

170±2
CUTOUT DIMENSION

388±2
CUTOUT DIMENSION

1.4   <u>Keyboard and trackball</u>

Keyboard and trackball must be mounted close together, such that both can be operated simultaneously by one person.

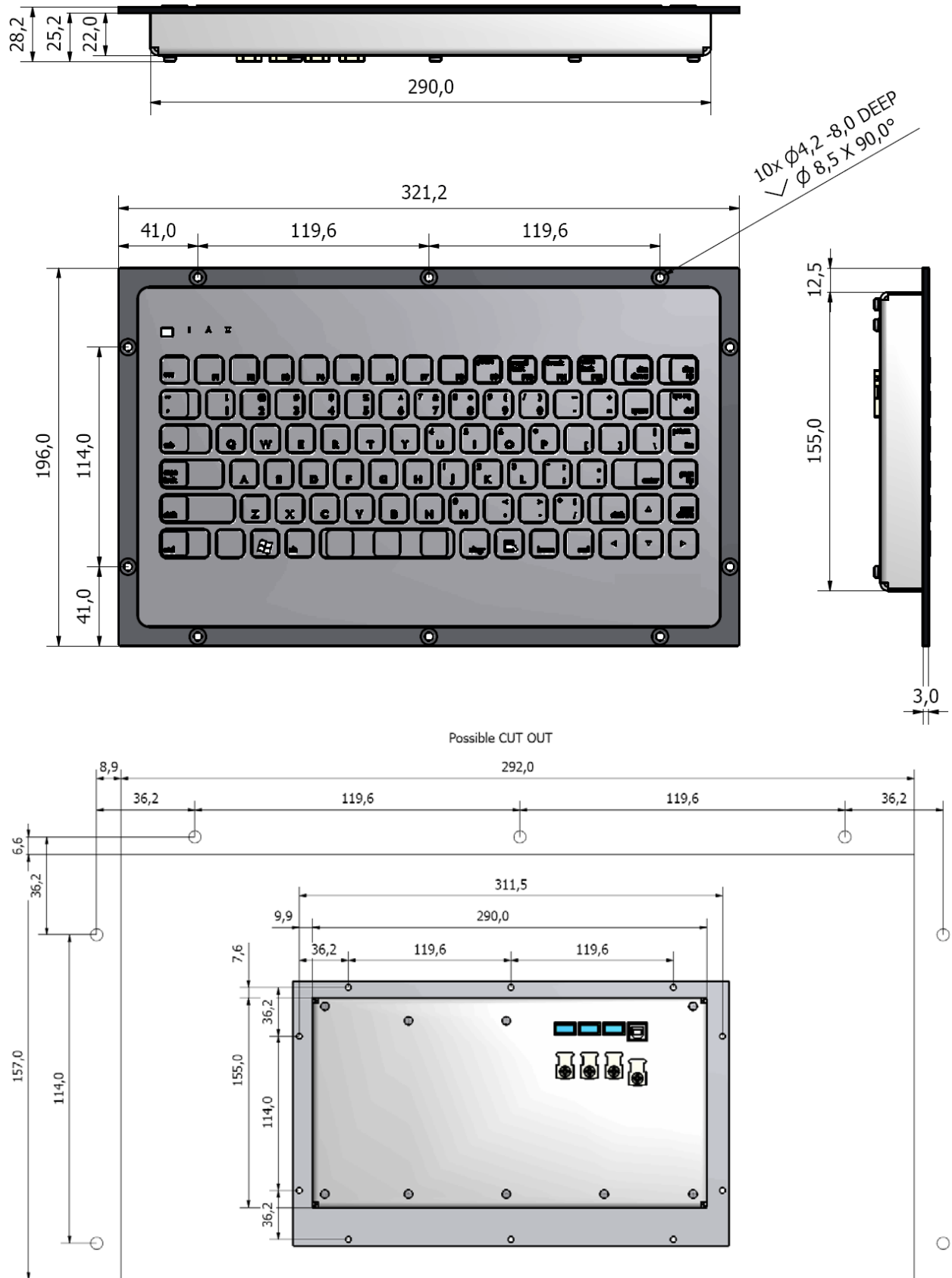When selecting a mounting location, keep in mind the following points:
1. Select a location where the control unit can be operated conveniently.
2. Locate the unit away from heat sources because of heat that can build up inside the cabinet.
3. Locate the equipment away from places subject to water splash and rain.
4. Determine the mounting location considering the length of the signal cable between the keyboard unit and the processor unit. (The length of the signal cable is 1,3 m).
5. Determine the mounting location considering the length of the signal cable between the trackball unit and the processor unit. (The length of the signal cable is 1,9 m).

When the combined keyboard and trackball "Keytouch Panel Combo" is installed, the keyboard and the trackball must be connected separately to the main processor unit using separate USB cables in order to fully comply with type approvals.
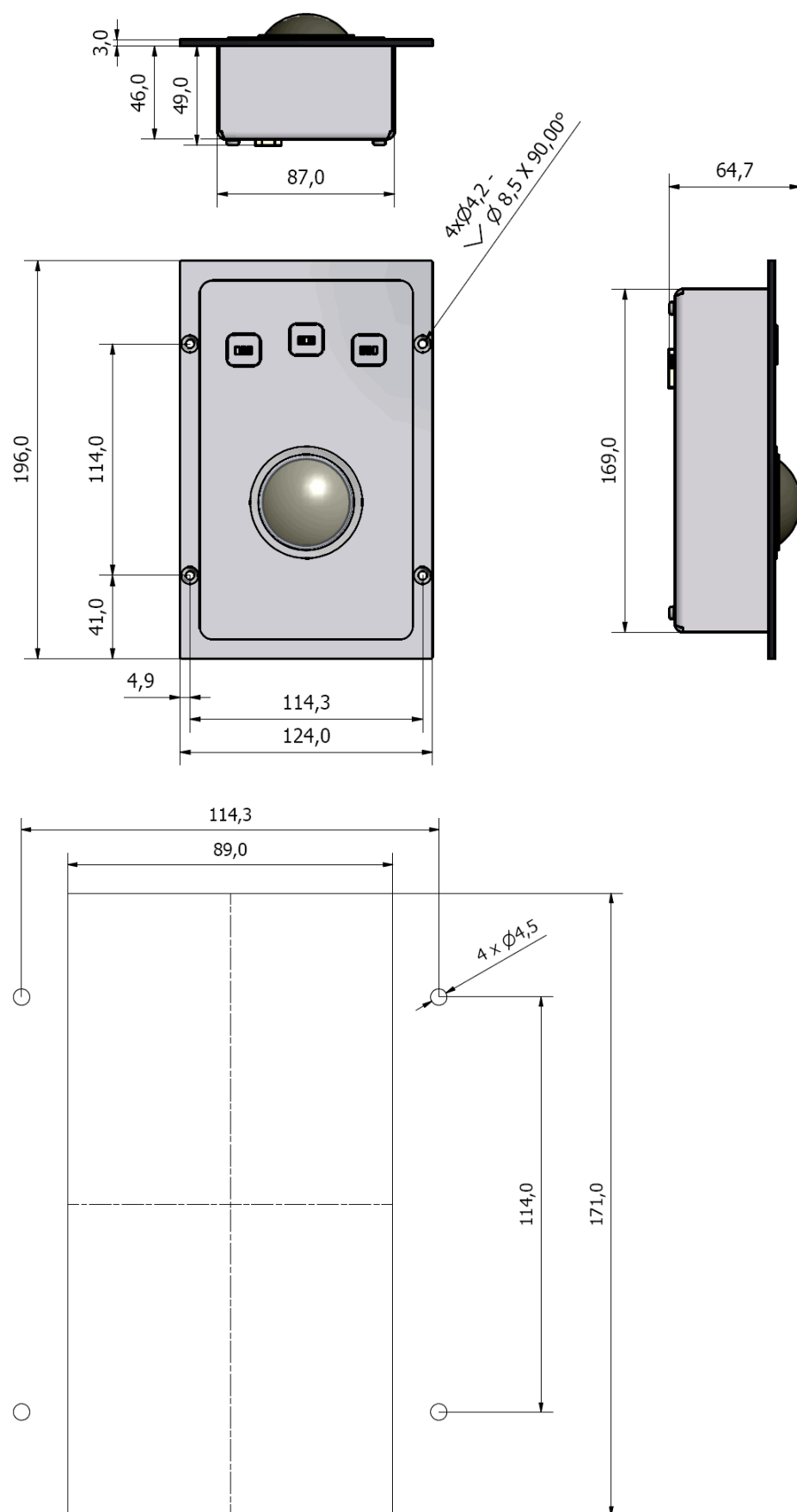
Outline dimensions for keyboard Cherry G84-4100:

Approx.175 mm (non-curled)

282

132

27
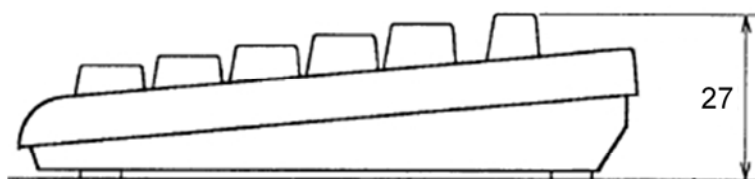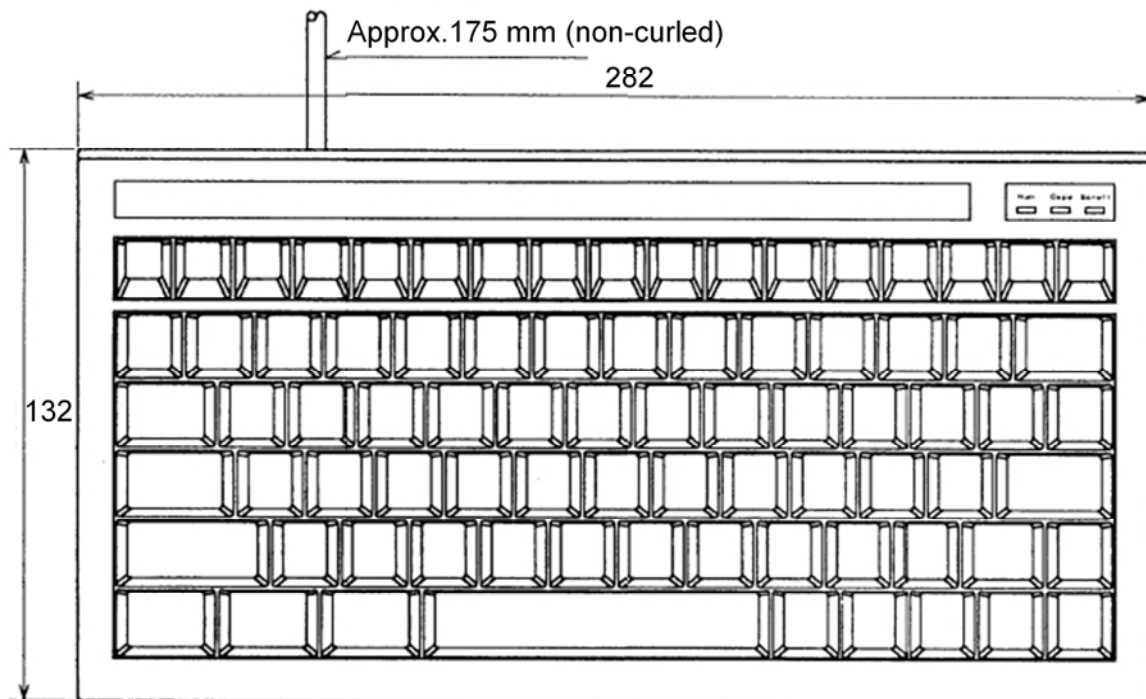
All dimensions in mm.

Outline dimensions for Trackball:

202 mm

101 mm

Outline dimensions and cutout for Keytouch panel QWERTY:

Outline dimensions and cutout for Keytouch panel Trackball:

3,0

46,0

49,0

87,0

4xØ4,2 -
Ø 8,5 X 90,00°

64,7

196,0

114,0

41,0

169,0

4,9

114,3

124,0

114,3

89,0

4 x Ø4,5

114,0

171,0

Possible CUT OUT.

Outline dimensions for Keytouch panel Combo:
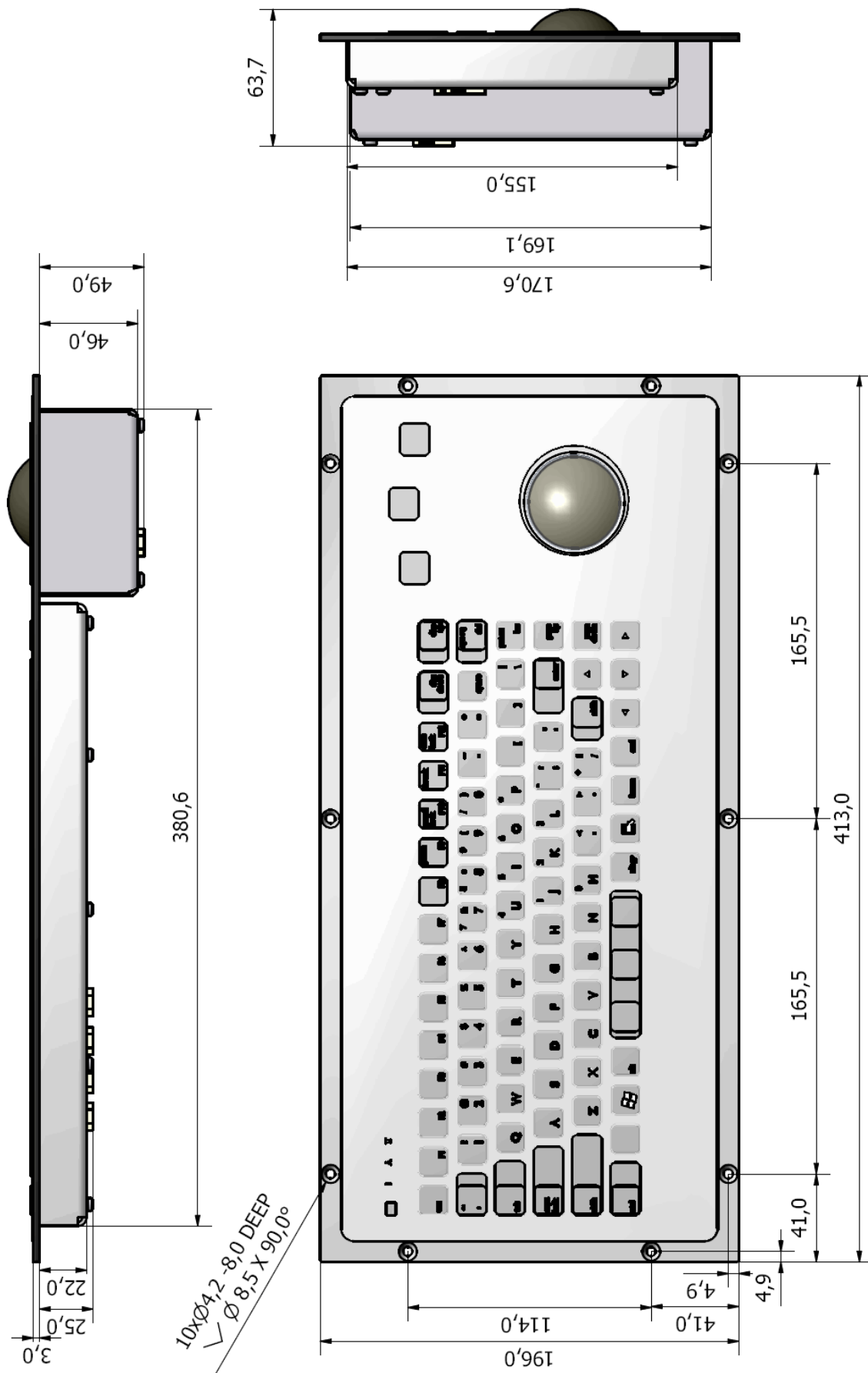
1.5   Additional units

When mounting additional units such as, loudspeaker, analogue alarm units, MOXA interface and other peripheral equipment, general considerations should be taken to ensure proper functions of respective equipment.

When selecting a mounting location, keep in mind the following points:

1. Select a location where vibrations are down to a minimum, try to avoid vibrations by adding strength to console where the processor is about to be installed.
2. Locate the unit away from heat sources because of heat that can build up inside the cabinet.
3. Locate the equipment away from places subject to water splash and rain.
4. Leave sufficient space on the sides and rear of the unit to facilitate maintenance and interconnection cabling.
5. Mount the loudspeaker such that audible sound level is not seriously degraded.

Do not protrude the housing with screws to fasten the units. Straps should be used to fasten the units at its location, without protruding the housing. Straps are not supplied and must be arranged locally.

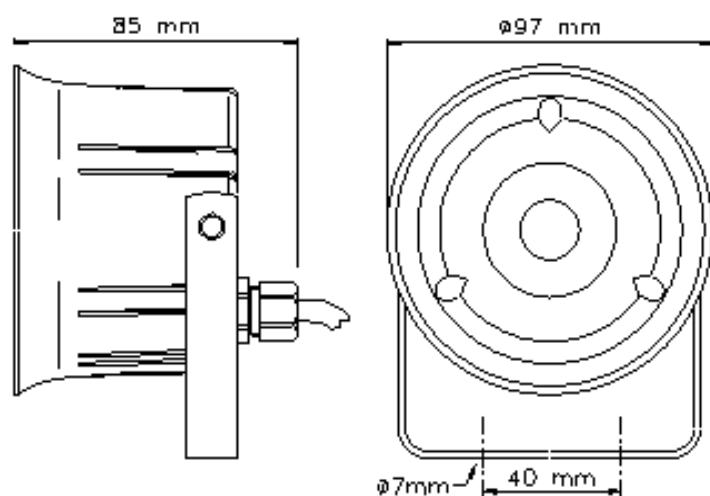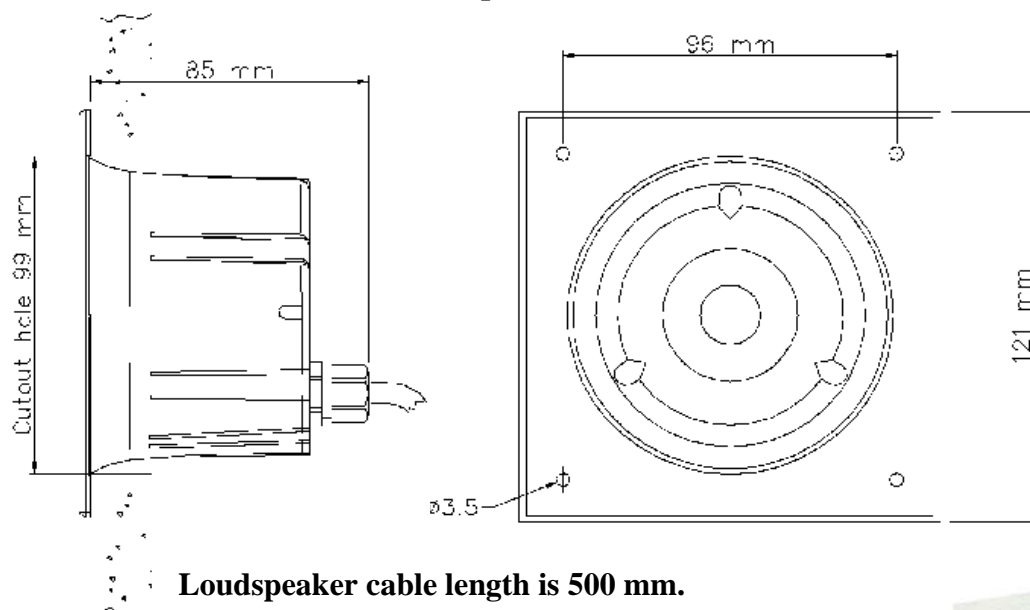**Outline dimensions for alarm interface TEA-01:**

Length: 125 mm
Width: 55 mm
Heigth: 40 mm

Cable length: 1400 mm

Outline dimensions for loudspeaker DNH HP6, with bracett:

Loudspeaker cable length is 500 mm.

Outline dimensions for loudspeaker DNH HPS6, for flush mount:

Loudspeaker cable length is 500 mm.

1.6   <u>Track Control: Anschütz NP 2025 PLUS</u>

Refer to Anschütz NP 2025 PLUS installation manual for installation of the autopilot. All applicable procedures and guidelines are to be followed.

⚠️ **For valid installation and operation of Track Control functionality, TECDIS must be as a minimum be connected to the following:**
- **Two Independent position sensors**
- **Two Independent heading sensors**
- **Speed sensor**
- **Alarm System for transfer of back-up navigator alarm**

⚠️ **TECDIS and the NP 2025 PLUS must be supplied with the same set of heading and log sensor inputs.**

⚠️ **On vessels where the steering system does not provide a "freeze rudder function" and maintained voltage is required for maintaining rudder angle, provisions must be made on installation of Anschütz NP 2025 PLUS to maintain steering voltage output on power loss to the NP 2025 PLUS.**

<u>Location of change over controls</u>

The steering mode selector switch or override facility, if installed, shall be located at or in the immediate vicinity of the main conning position.

<u>Connection to TECDIS</u>

The serial transfer module (NB05-343) on the Anschütz NP 2025 PLUS must be connected to a TECDIS serial port and configured in TECDIS SETUP (See chapter 3.7).

1.7   Track Control: Furuno FAP 2000- and EMRI SEM 200 Autopilot

Refer to Furuno FAP 2000 Autopilot "*Instruction Manual 8395-2*" or EMRI SEM 200 Autopilot "*Instruction Manual 8380-2*" for installation of the autopilot. All applicable procedures and guidelines are to be followed.

⚠ **For valid installation and operation of Track Control functionality, TECDIS must be as a minimum be connected to the following:**
- **Two Independent position sensors**
- **Two Independent heading sensors**
- **Speed sensor**
- **Alarm System for transfer of back-up navigator alarm**

⚠ **TECDIS and the Furuno FAP 2000 Autopilot or EMRI SEM 200 Autopilot must be supplied with the same set of heading and log sensor inputs.**

⚠ **On vessels where the steering system does not provide a "*freeze rudder function*" and maintained voltage is required for maintaining rudder angle, provisions must be made on installation of Furuno FAP 2000 Autopilot and/or EMRI SEM 200 Autopilot to maintain steering voltage output on power loss to the Furuno FAP 2000 Autopilot or EMRI SEM 200 Autopilot.**

Location of change over controls

The steering mode selector switch or override facility, if installed, shall be located at or in the immediate vicinity of the main conning position.

Connection to TECDIS

The Furuno FAP 2000 Autopilot's or EMRI SEM 200 Autopilot's, Electronic Unit AEU 511, ETS1 Connector Module, must be connected to a TECDIS serial port and configured in TECDIS SETUP (See chapter 3.7).

1.8   NAUT AW: Gyro Sensor Input Requirements

For vessels with class notation NAUT AW, the gyro sensor input to TECDIS AW must satisfy the following requirements:

1. The GAS must be supplied with a redundant gyro system including:
    1.1.   Heading monitoring function
    1.2.   Automatic correction for speed and latitude error
    1.3.   Automatic switching to back-up gyro when selected gyro fails
    1.4.   Compliance with requirements to gyro system information, "system in use" as stated in DNV rules Pt.6 Ch.8 Sec.6 H 600
        1.4.1. Scope of paragraph 1.4 is to enable conning system to display which gyro is presently in use.

2.   All equipment with gyro input must be supplied by the same gyro at any given time to ensure a common reference point regarding heading information.

Chapter 2:   Wiring and signal distribution

On the following pages wiring and signal distribution diagrams are shown. Signal distribution diagram is an indication of possible means of signal distribution. During installation actual need for signal distribution must be verified by installer, depending on signals available and actual hardware installation on the specific vessel.

Most sensors will be connected using the RS-232/ RS-422 Serial Split cable with 8xDB9 connectors attached to the computer's Moxa Connector. This cable provides COM ports 3 to 10 (labeled on the connectors as 1 to 8). The pin assignments for these connectors are as follows:

Moxa serial split cable DB9 (male) pin assignments:

Pin No.	RS-422	RS-232
1	TxD-(A)	DCD
2	TxD+(B)	RxD
3	RxD+(B)	TxD
4	RxD-(A)	DTR
5	GND	GND
6		DSR
7		RTS
8		CTS
9		RI
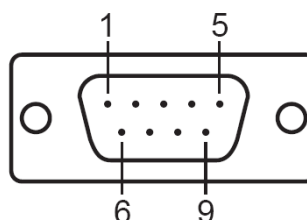
Each serial port from COM 3 to COM 10 is optoisolated, and can be individually configured to RS-232 or RS-422. Per default, COM 3 will be set to RS-232 and COM 4 to 10 will be set to RS-422.

The serial ports can be reconfigured by opening the computer and setting DIP switches on the Moxa serial port PCI card as specified below.

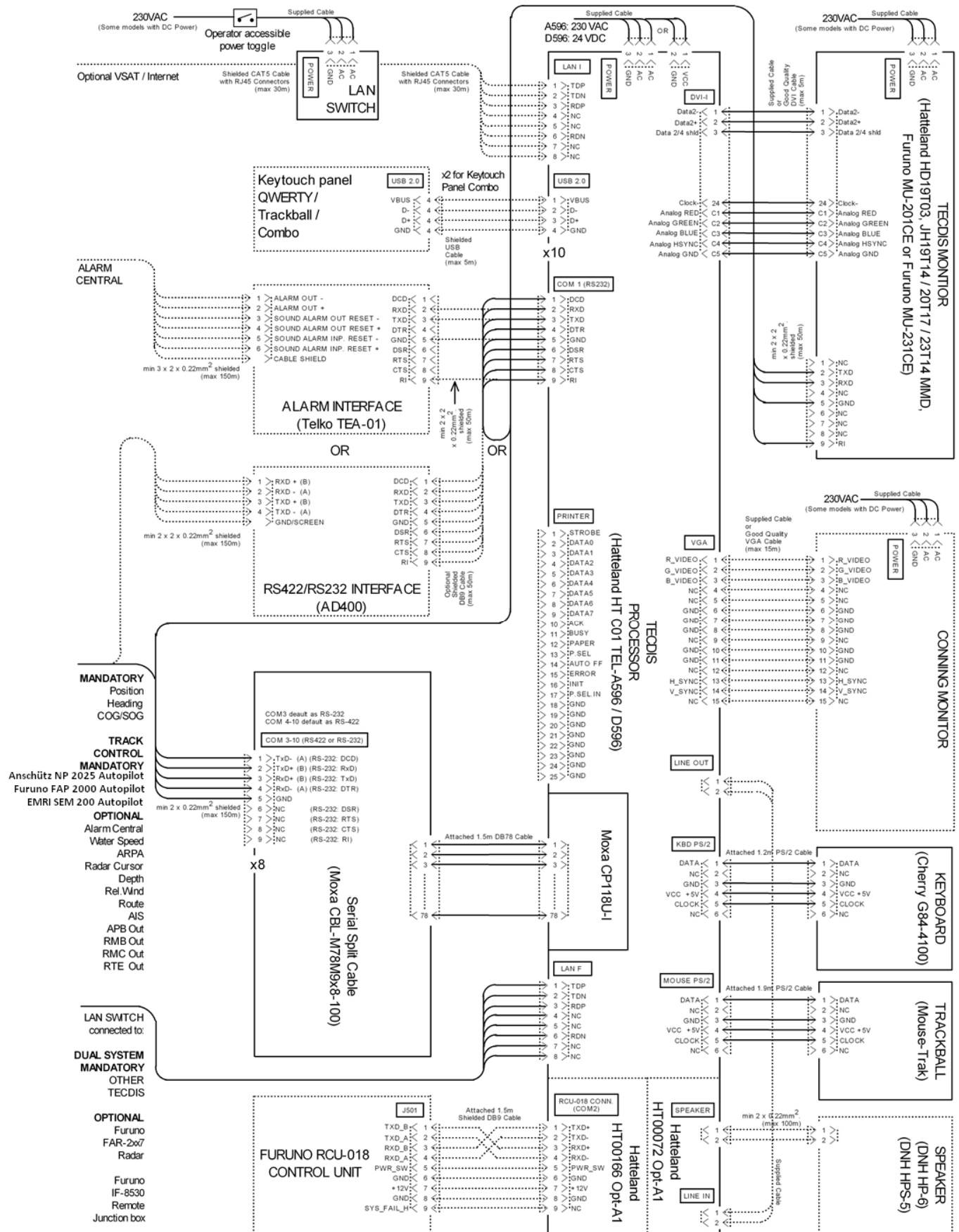**DIP switches on Moxa CP118U-I (default configuration shown):**
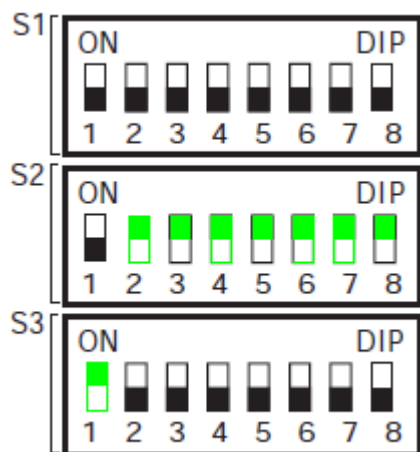
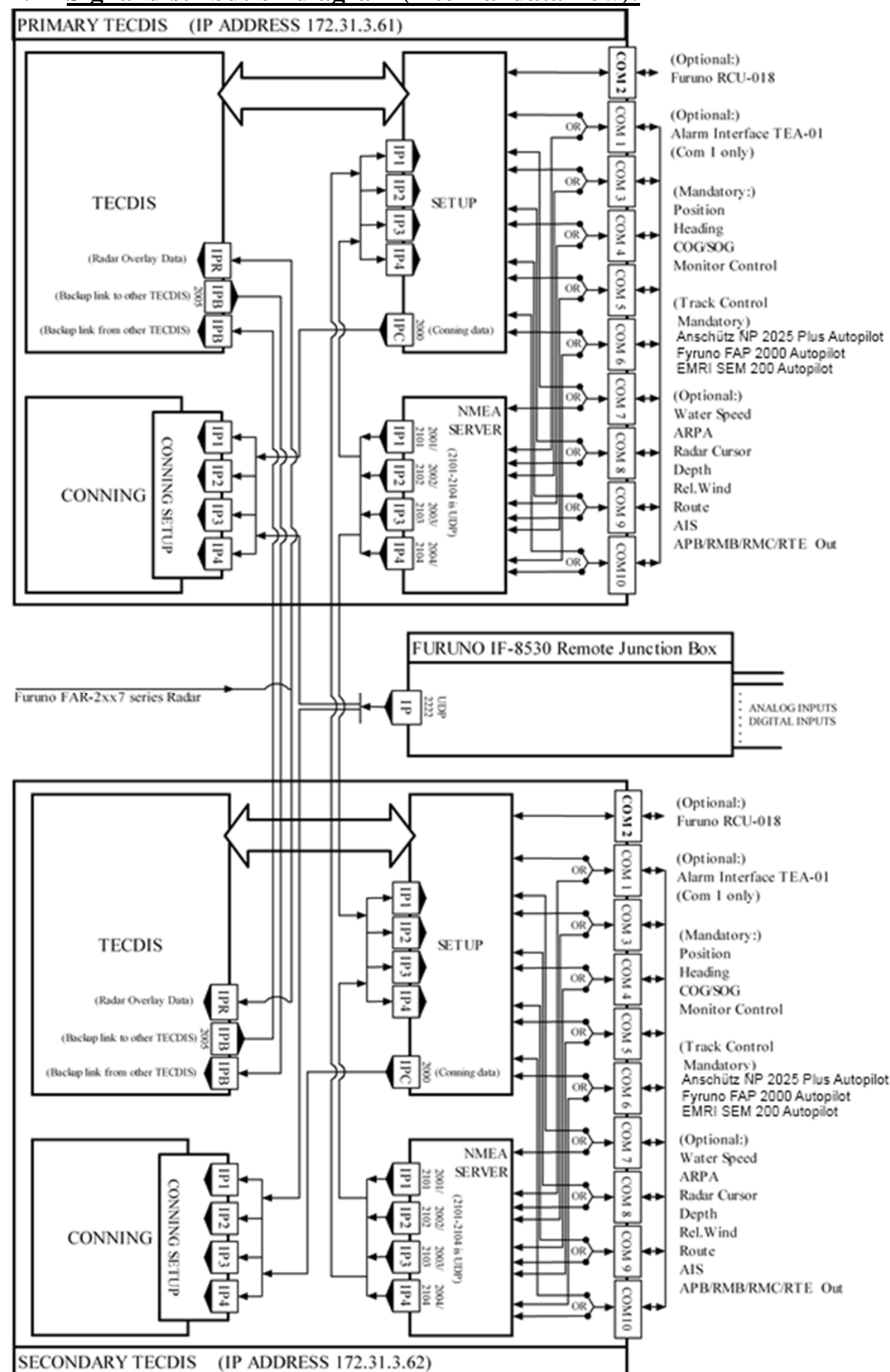| Mode	S1	S2	S3
RS-232			ON
RS-422		ON	OFF
4-wire RS-485	ON	OFF	OFF
2-wire RS-485	OFF	OFF	OFF

Jumpers JP1 to JP8 activate onboard termination resistors for each serial port individually.

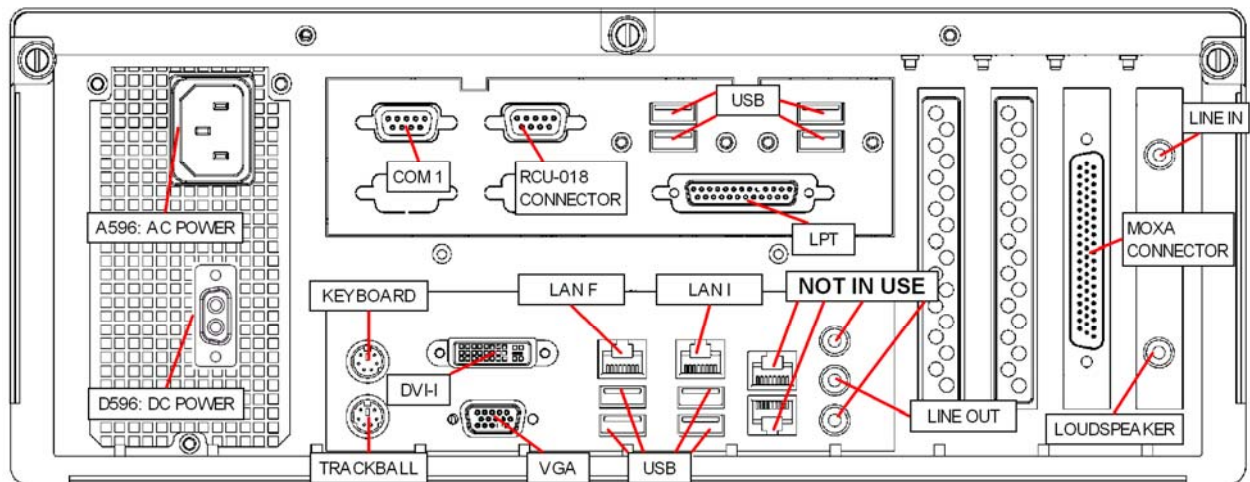These jumpers should not be activated on a normal installation.

2.1   Wiring diagram (HT C01 TEL-A596 / D596):

2.2   Signal distribution diagram (internal data flow):

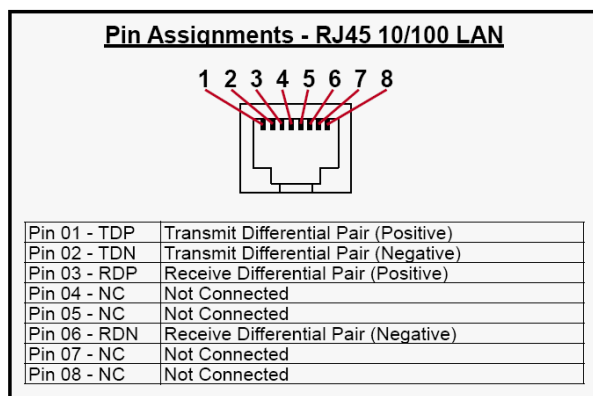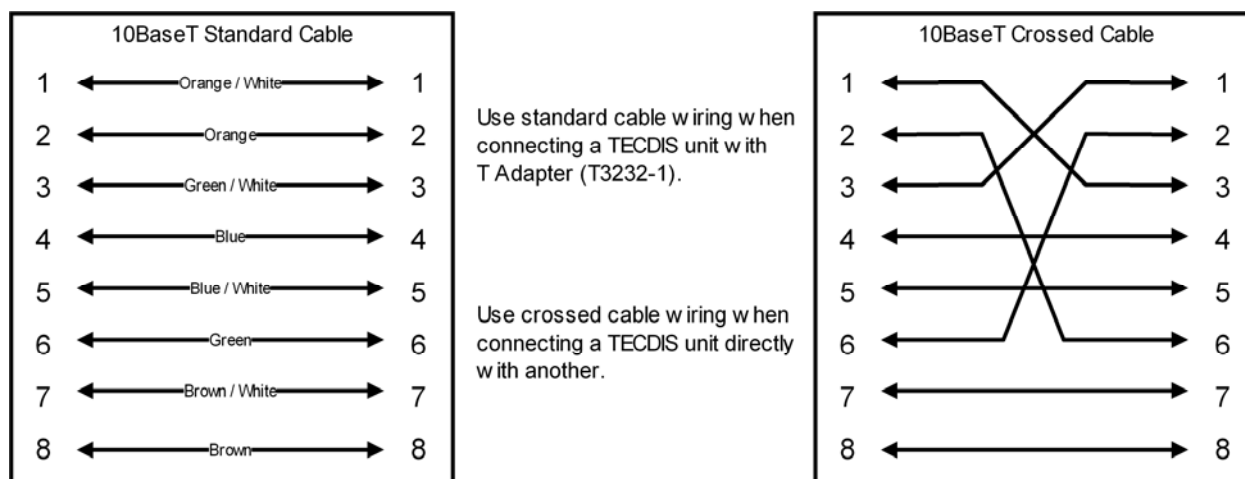## 2.3   Processor connectors, HT C01 TEL-A596 / D596

- **NB! Only connect Furuno RCU-018 to RCU-018 connector. Proprietary connector supplies live 12V DC current and may damage any other equipment connected!**

- COM1 is to be used for TEA-01 Alarm central interface. ECDIS monitor control may be connected to COM 1 directly. Other sensors may be connected to COM1 via an RS232/RS422 interface (such as AD400).

- Connect ECDIS monitor using the DVI-I connector.

- If optional speaker connectors HT00072 Opt-A1 are used, LINE OUT and LINE IN are to be connected using the supplied cable.

- LAN connector LAN "F" is to be used when connecting the TECDIS unit to other TECDIS units, Furuno VDR Adapter or Furuno FAR-2xx7 series radar.

- LAN connector LAN "I" can optionally be used for connecting the TECDIS unit to other networks or internet. **To fully comply with type approvals when connected to internet, a switch must be made available to disconnect TECDIS from internet when the connection is not in use.**

- HT C01 TEL-D596: Refer to computer user guide (supplied) page 14 for correct wiring of DC power connector.
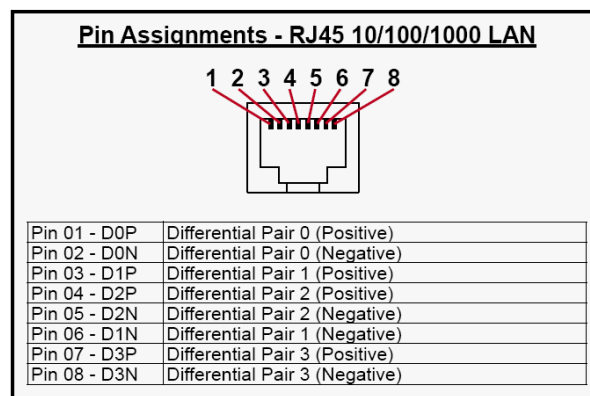
2.4   Other notes regarding connectors and wiring

- **When the combined keyboard and trackball "Keytouch Panel Combo" is installed, the keyboard and the trackball must be connected separately to the main processor unit using separate USB cables in order to fully comply with type approvals.**
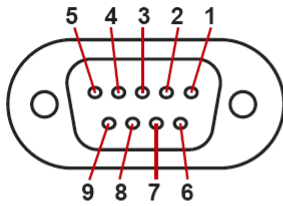
## 2.5   Ethernet connectors and cable

10BaseT Standard Cable

1	←— Orange / White —→	1
2	←— Orange —→	2
3	←— Green / White —→	3
4	←— Blue —→	4
5	←— Blue / White —→	5
6	←— Green —→	6
7	←— Brown / White —→	7
8	←— Brown —→	8

Use standard cable wiring when connecting a TECDIS unit with T Adapter (T3232-1).

Use crossed cable wiring when connecting a TECDIS unit directly with another.

10BaseT Crossed Cable

Pin Assignments - RJ45 10/100 LAN

1 2 3 4 5 6 7 8

Pin 01 - TDP	Transmit Differential Pair (Positive)
Pin 02 - TDN	Transmit Differential Pair (Negative)
Pin 03 - RDP	Receive Differential Pair (Positive)
Pin 04 - NC	Not Connected
Pin 05 - NC	Not Connected
Pin 06 - RDN	Receive Differential Pair (Negative)
Pin 07 - NC	Not Connected
Pin 08 - NC	Not Connected

Use category 5 - twisted pair cable

Pin Assignments - RJ45 10/100/1000 LAN

1 2 3 4 5 6 7 8

Pin 01 - D0P	Differential Pair 0 (Positive)
Pin 02 - D0N	Differential Pair 0 (Negative)
Pin 03 - D1P	Differential Pair 1 (Positive)
Pin 04 - D2P	Differential Pair 2 (Positive)
Pin 05 - D2N	Differential Pair 2 (Negative)
Pin 06 - D1N	Differential Pair 1 (Negative)
Pin 07 - D3P	Differential Pair 3 (Positive)
Pin 08 - D3N	Differential Pair 3 (Negative)

2.6   Other connectors

Pin Assignments - 9P Serial COM RS422

Pin 01 - N/C	Not Connected
Pin 02 - TX-	Transmit Data -
Pin 03 - RX+	Receive Data +
Pin 04 - N/C	Not Connected
Pin 05 - GND	Ground
Pin 06 - N/C	Not Connected
Pin 07 - TX+	Transmit Data +
Pin 08 - RX-	Receive Data -
Pin 09 - N/C	Not Connected

Pin Assignments - 9P Serial COM RS485
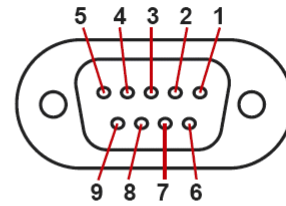
Pin 01 - N/C	Not Connected
Pin 02 - N/C	Not Connected
Pin 03 - DAT+	Data+
Pin 04 - N/C	Not Connected
Pin 05 - GND	Ground
Pin 06 - N/C	Not Connected
Pin 07 - N/C	Not Connected
Pin 08 - DAT-	Data-
Pin 09 - N/C	Not Connected

Pin Assignments - 9P Serial COM
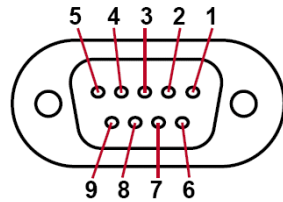
Pin 01 - DCD	Data Carry Detect
Pin 02 - SIN	Serial In or Receive Data
Pin 03 - SOUT	Serial Out or Transmit Data
Pin 04 - DTR	Data Terminal Ready
Pin 05 - GND	Ground
Pin 06 - DSR	Data Set Ready
Pin 07 - RTS	Request To Send
Pin 08 - CTS	Clear To Send
Pin 09 - RI	Ring Indicate

Pin Assignments - 15P HD RGB VGA
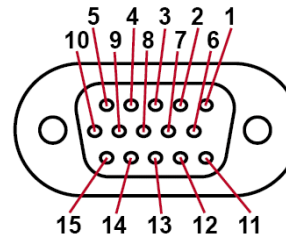
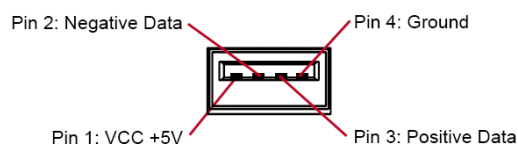| Pin 01	Red, analog
Pin 02	Green, analog
Pin 03	Blue, analog
Pin 04	Reserved for monitor ID bit 2 (grounded)
Pin 05	Digital ground
Pin 06	Analog ground red
Pin 07	Analog ground green
Pin 08	Analog ground blue
Pin 09	+5V power supply for DDC (optional)
Pin 10	Digital ground
Pin 11	Reserved for monitor ID bit 0 (grounded)
Pin 12	DDC serial data
Pin 13	Horizontal sync or composite sync, input
Pin 14	Vertical sync, input
Pin 15	DDC serial clock

Pin Assignments - 5P PS/2 MOUSE

Pin 6: Not Connected
Pin 5: Mouse Clock
Pin 4: Vcc +5V
Pin 3: Ground
Pin 2: Not Connected
Pin 1: Mouse Data

Pin Assignments - USB

Pin 2: Negative Data
Pin 4: Ground
Pin 1: VCC +5V
Pin 3: Positive Data
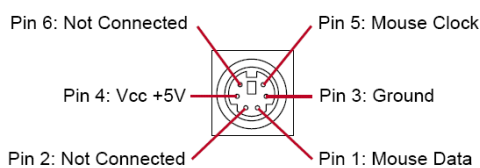
Pin Assignments - 5P PS/2 KEYBOARD

Pin 6: Not Connected
Pin 5: Keyboard Clock
Pin 4: Vcc +5V
Pin 3: Ground
Pin 2: Not Connected
Pin 1: Keyboard Data
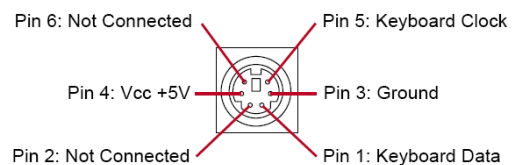
Chapter 3:   Parameter Setup

When you first starts the TECDIS computer it will automatically start up and enter the TECDIS program. Windows XP and TECDIS software are pre-installed. To exit TECDIS program for commissioning and installation setup procedures see chapter 3.1 for details.

3.1   Service mode (Windows)

When you exit TECDIS (using the button at the upper left corner), the chart plotter will automatically be turned off after you confirm that you want to exit. In order to exit TECDIS without turning the chart plotter off, you must insert the USB service key (memory dongle) *before* you exit TECDIS. When this service key is connected to the chart plotter, the chart plotter will not be turned off when you exit TECDIS and you will be able to work in Windows (service mode) and open the Setup program by double clicking on the Setup icon on the desktop. When service mode is available, a text indication is shown in the lower right corner of the chart.
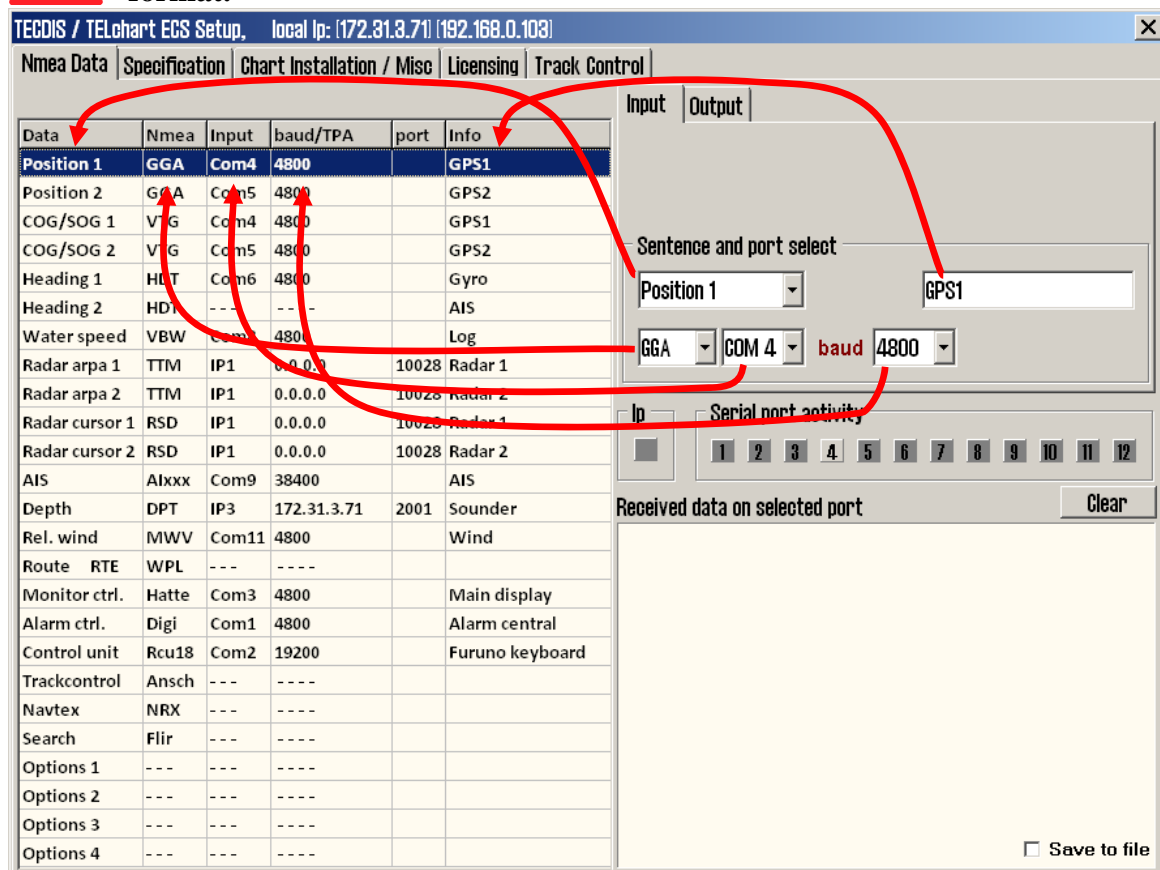
3.2   NMEA data setup

The "*NMEA Data*"-folder in the TECDIS Setup, constitutes all controls and settings for inputs and outputs, to and from TECDIS, are set. The table to the left (information field), shows the current settings and is instantly updated if changes are made by using the "*Input*"- and "*Output*"-folders at the upper right part of the window. The pull-down menu for "*Input*"-selection will open/close for other options to be selected as required, to assist in making correct settings.

3.2.1   The "*Input*"-folder

Note: All position inputs to TECDIS from all external sensors must be in WGS-84 format.

Use this tab of the setup program to configure input signals, by selecting the "*Data*"-type either by activating the desired line in the table to the left, or by selecting the "*Data*"-type from the pull-down menu in the "*Input*"-folder to the right. When "*Data*"-type is selected, the corresponding line in the information field to the left is shown as active in blue background color.

3.2.2   Info text

Then, type in a text description in the "*Info*"-field to identify the source instrument for the selected "*Data*"-type. This could be brand name for the sensor connected, as this field text will be visible in warnings and alerts in the TECDIS program.

3.2.3   NMEA sentence

In the pull-down menu for "*NMEA*"-sentence; select the type of "*NMEA*"-sentence for this input. For more information about the different NMEA sentences, see the table in paragraph 3.2.11 below. Available "*NMEA*"-sentences in the pull-down menu will change according to which "*Data*"-type is selected. When a given sensor provides more than one of the supported "*NMEA*"-sentences, the highest ranking option from the following lists (as applicable) should be used:

Position 1 and **Position 2**
1. $??GNS   GNSS fix data
2. $??GGA   GPS fix data
3. $??GLL   Geographic position lat/long
4. $??RMC   Recommended minimum specific GNSS data
5. !AIVDO[1]   AIS own ship position. UAIS VHF Data link own-vessel report

COG/SOG 1 and **COG/SOG 2**
1. $??VTG   Course and speed over ground
2. $??RMC   Recommended minimum specific GNSS data
3. $??OSD   Own ship data
4. !AIVDO   AIS own ship position. UAIS VHF Data link own-vessel report

Heading 1 and **Heading 2**
1. $??THS   True heading and status
2. $??HDT   Heading true
3. $??OSD   Own ship data
4. $??VHW   Water Speed and Heading
5. !AIVDO   AIS own ship position. UAIS VHF Data link own-vessel report

Radar ARPA 1 and **Radar ARPA 2**
$??TTM   Tracked Target Message

Radar Cursor 1 and **Radar Curson 2**
$??RSD   Radar System Data

AIS
!AI???   AIS UAIS VHF Data Link

---

[1] Position: !AIVDO may be used as a secondary position source whenever primary source is missing.

Depth
1. $??DPT   Depth
2. $??DBT   Depth below transducer

3.2.4   Input port

In the pull-down menu "*Input*"-port, select the physical serial port the selected sensor "*Data*"-type should be read from. If the "*Input*"-port field is set to same value as already set for; "*Monitor ctrl.*", "*Alarm ctrl.*" or "*Control unit*", the text of the corresponding lines in the information field will turn red. This indicates that the port selection is invalid, and that another COM port must be selected either for the sensor or the conflicting equipment.
The text of the corresponding line in the information field will turn green when valid "*NMEA*"-sentences is received on the specified "Input"-port.

3.2.5   IP-port

IP ports: TECDIS has 12 COM ports and 4 IP ports. For each IP port, the IP address and "*IP*"-port number must be entered. The "*Test*"-button establishes a connection to the IP server with the selected address/port number and the "*Received data on selected port*"-area will show any data that is received.

Example: In order to receive position data from a GPS, you need to:
1. Select "*Position 1*" or "*Position 2*" from the "*Data*"-type pull-down menu.
2. Optionally (but recommended) enter a description identifying the sensor as a GPS in the "*Info*" field. If the sensor signal is lost while the TECDIS is in operation, an alarm will be sounded. The alarm message will indicate the type of sensor lost as well as what port it is connected to and the sensor description from the "*Info*"-field. The failing instrument

(instead of having to refer to the configuration in the Setup program) is easily identified. NMEA Sensor inputs and status can also be displayed in TECDIS.

3. Select the "*NMEA*"-sentence from the "*NMEA*"-sentence pull-down menu.
4. Select the "*Input*"-port for the GPS from the "*Input*"-port pull-down menu.

3.2.6   The "*Baud/TPA*"-field

In the "*Baud/TPA*"-field the data speed to be used for the COM are set. The NMEA standard is 4800 (low speed). Be aware though that some instruments require a different data speed selection. There is also a NMEA high speed standard (38400). AIS units typically use high speed in order to transmit as much data as possible. (Select AIS in the "*Data*"-type field and check that the "*Baud/TPA*"-field indicates the high-speed setting). The speed is set by selection from this field's drop-down menu.

3.2.7   Port activity

In the "*Serial port activity*"-field the ports that are receiving data are shown. Whenever data is received on a COM port, the corresponding indicator in this area will flash green. The indicators are for COM ports 1-12 in increasing order from left to right.

3.2.8   Received data on selected port

In the "*Received data on selected port*"-field the data that are being received from the COM port that is marked with green in the "*Information*"-field and selected in the "*Data*"-type field. By changing the selected port in "*Data*"-type field by selecting one of the other "*Data*"-types, the data shown in the "*Received data on selected port*"-field will change correspondingly.

3.2.9   Other COM port connections

All "*Input*"-ports settings that is not used should be set to "----". Additionally there are some predefined in-/outputs that may have non-NMEA protocol. On the "*HT C01 TEL-A-596*" and "*HT C01 TEL-A-596*" computers used for "*TECDIS 2138AA*" and "*TECDIS 2138AD*" the serial ports COM 1 and 3 are set as RS232, COM 2 is proprietary and remaining COM-ports are RS 422 serial ports.

Monitor Ctrl: Select the COM port (RS232) that the monitor is connected to. This connection will control the monitor background light and calibration settings, as well as the alarm sounder in the screen unit (if used). Ensure that the power supplied to the monitor is from the same source (UPS, mains socket etc.) as for the TECDIS.

Alarm ctrl: Select the COM port that should be used for the alarm central interface (if used). In the "*NMEA*"-sentence pull-down menu there are two choices; "*Digi*" and "*ALR*". "*Digi*" will set the port up to serial NMEA communication with the alarm central. "*ALR*" option should be used when connected to a proprietary alarm interface TEA-01, which is an open/close relay contact.

Control unit (RCU-018): Set "*Input*"-port to "*COM 2*" if the Furuno RCU-018 is connected to the TECDIS. Physically, the "*COM 2*"-port provides live 12VDC power to the Control unit and thus this port cannot be used to any other equipment.

Search FLIR: Select the COM port where gyro-stabilized FLIR camera (if used) is connected.

3.2.10 The "*Output*"-folder

The "*Output*"-folder in the upper right corner of the "*NMEA Data*"-folder have settings for the following outputs: APB, RMB, RMC and WPL+RTE. For each of the outputs, there are choices of which of the physical COM-ports the output should be directed trough.

There is also a tick-box for activating IP-server on port 2000 on this folder.

3.2.11 Supported NMEA Sentences

TECDIS supports communication with external equipment using the following NMEA
sentences, as specified by the NMEA standard and IEC 61162-1 (Ed. 3.0):

NMEA sentence	Description	Send / Receive
ABK	(AIS) AIS addressed and binary broadcast acknowledgment	Receive
ABM	(AIS) AIS Addressed Binary and Safety Related Message	Send
ACK	Acknowledge Alarm	Send / Receive
ALR	Set Alarm State	Send / Receive
APB	Heading/Track Controller (Autopilot) Sentence "B"	Send
BBM	(AIS) AIS Broadcast binary message	Send
DBT	Depth Below Transducer	Receive
DPT	Depth	Receive
DTM	Datum reference	Receive
GGA	Global Positioning System (GPS) Fix Data	Receive
GLL	Geographic Position – Latitude / Longitude	Receive
GNS	GNSS Fix Data	Receive
HDT	Heading, True	Receive
MTW	Water temperature	Receive
MWV	Wind Speed and Angle	Receive
OSD	Own Ship Data	Receive
RMB	Recommended Minimum Navigation Information	Send
RMC	Recommended Minimum Specific GNSS Data	Send / Receive
ROT	Rate of Turn	Receive
RSA	Rudder Sensor Angle	Receive
RSD	Radar System Data	Receive
RTE	Routes	Send / Receive
THS	True Heading and Status	Receive
TTM	Tracked Target Message	Receive
VDM	(AIS) AIS VHF Data-link Message	Receive
VDO	(AIS) AIS VHF Data-link Own-vessel Report	Receive
VBW	Dual Ground/Water Speed	Receive
VHW	Water Speed and Heading	Receive
VSD	(AIS) AIS voyage static data	Send
VTG	Course Over Ground and Ground Speed	Receive
VWR	Relative (Apparent) Wind Speed and Angle	Receive
WPL	Waypoint Location	Send / Receive
ZDA	Time and date	Receive

NOTE: TECDIS also supports a number of proprietary protocols for specific application areas.
Contact your TECDIS supplier for details.

3.3 Specification

On this tab, the dimensions of the vessel and the placement of sensors on the vessel are specified. Specifying the position of the sensors is important in order to get the highest possible accuracy in position (GPS antenna) and other data as possible.

- In the "*Ship Size*"-field, enter the length, beam, draught and height of the vessel in meters.
  - o For "*Length*"- and "*Beam*"-fields the ship's largest dimension value for length and beam should be used.
  - o For "*Draught*" and "*Height*" the largest possible height and draught taking load conditions into consideration should be entered.

- When a second TECDIS unit is present in the installation (for example, backup unit). The IP address of the second TECDIS unit should be entered in the "*Data export IP*" field. This will activate automatic transfer of active routes to the second TECDIS, and it will be possible to transfer data (objects, tracks, routes) to the second unit. (See chapter 3.8 Route Synchronization for details).

⚠ **NOTE:** If the TECDIS unit is not to be connected to a second TECDIS unit, this value should be set to "*0.0.0.0*". For any other value in this field, TECDIS will generate an alarm if unable to connect to the other TECDIS unit.

- *"Radar use true EBL reference"*: When this checkbox is marked, it is assumed that bearings lines received from the radar(s) are true referenced. If this option is not marked, TECDIS will perform the necessary adjustments.

- *"Arpa is conning referenced"*: When this checkbox is marked, it is assumed that target information from Arpa radar is already adjusted to the navigator position. If it is not marked, TECDIS will perform the necessary adjustments.

- In the "*Monitor*"-field the following should be set:
    - *"Monitor inch diagonal"*: Specify the diagonal size of the monitor here.
    - *"Backward (gyro-180º)"*: Checking this box turns the heading value from gyro 180 degrees.

- In the *"Alarm"*-field, you can select whether sound alarms should sound through the PC speaker in the chart plotter, through the monitor buzzer or through the RCU-018 Control Unit.

    - *"Allow Standby Mode"*: When this option is activated, it will be possible to set TECDIS in "Standby Mode". In this mode, no audible alarms will be generated. Activating this option also allows CPA alarms to be disabled in TECDIS. NOTE: A prominent warning is displayed whenever the "Standby Mode" is active.
    - *"Alarm if HDT1-HDT2 > 2.5º"*: When this box is checked, an alarm will be given if the heading from the two sensors "Heading 1" and "Heading 2" deviates with more than 2.5 degrees. **Note:** If the TECDIS system has the option "*Track Control*" enabled, this box is inactivated as control for this alarm is set up in the "*Track Control*"-folder.
    - When selecting the "*Remote silence only*"-checkbox an acknowledgement made on an TECDIS alarm in an Alarm Central (not part of TECDIS system), only turns off the audible alarm signal. The TECDIS alarm situation must be solved in TECDIS.

- If two positioning methods are in use, the button *"Erase Secondary past track"* allows you to remove the past track line from the secondary position sensor.

- "*NAME*": The vessel name should be specified in this field.
- "*MMSI*": The MMSI number should be specified in this field
- "*Restore saved default values*"-button allows you to retrieve all settings made in the NMEA Server, Conning and TECDIS setup from the backup file that was saved in the "*Service key*" last time TECDIS Setup was closed. When "*Restore saved default values*"-button is clicked, a dialog window called "*Restore to xxxxx (eToken #): Locate the setup file to restore from, and click OPEN*" appears. Locate the file that contains all the settings, called "*T-setup xxxxx.tsz*" where xxxxx represents eToken serial number.
    - A "*T-setup xxxx.tsz*"-file is generated by TECDIS Setup every timer TECDIS Setup is started and stopped again. The file is created by setting the "*Service Key*" into the computer, stop TECDIS and start TECDIS Setup, stop TECDIS Setup, remove the "*Service Key*". "*T-setup xxxx.tsz*"-file is saved to the "*Service Key*" automatically, where "*xxxxx*" represents the unit's eToken serial number. Repeat for TECDIS No. 2. "*T-setup xxxx.tsz*"-file can be used by TELKO for an analysis of the setup, installation and other settings.

3.4 <u>TECDIS NMEA and TCP/IP server</u>
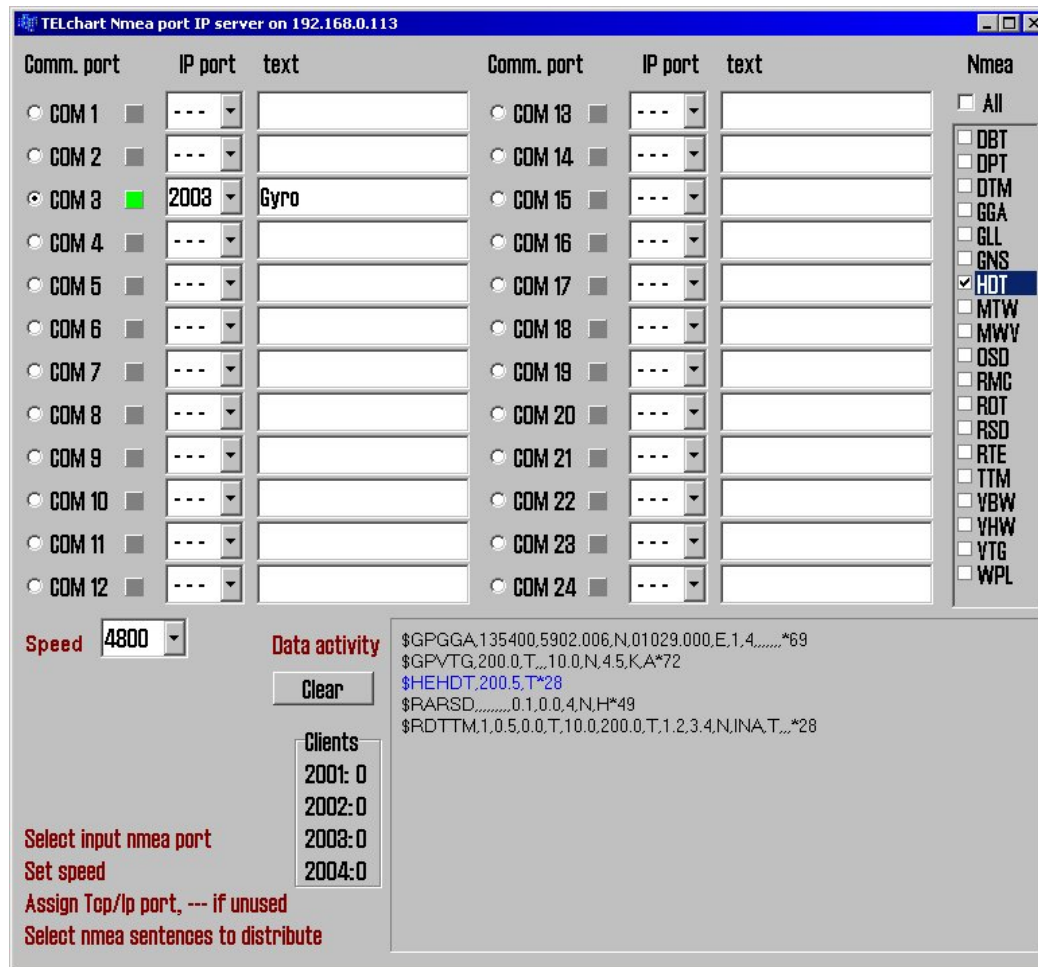
TECDIS NMEA and TRP/IP server allows distribution of selected comport data out through a TCP/IP network. This way one sensor can be shared by multiple users in a TCP/IP network.

As shown above, "HDT sentence", is received on comport 3 and is retransmitted on port 2003 through TCP/IP address 192.168.0.113. This means that backup ECDIS (or other connected computers to the LAN network) can receive "HDT" data through TCP/IP by selecting correct IP address (192.168.0.113 port 2003).

Setup procedure:
1. Select appropriate comport with desired data
2. Select appropriate baud rate on receiving comport, by using "**Speed**" dialog box
3. Select to which TCP/IP "port" it shall retransmit data (from the selected comport), for example 2003
4. Describe with text connected device to TCP/IP port (backup station, conning PC etc.)
5. Select which NMEA sentences you which to send (you may select one, multiple or all on one TDP/IP port)

"**Data activity**"   shows activity on selected (monitored) comport. HDT is marked in blue due to it is selected for output to TCP/IP.

"**Clients**" shows how many listeners (connections) there are on each connected TCP/IP port.

3.5   Chart Installation / Misc
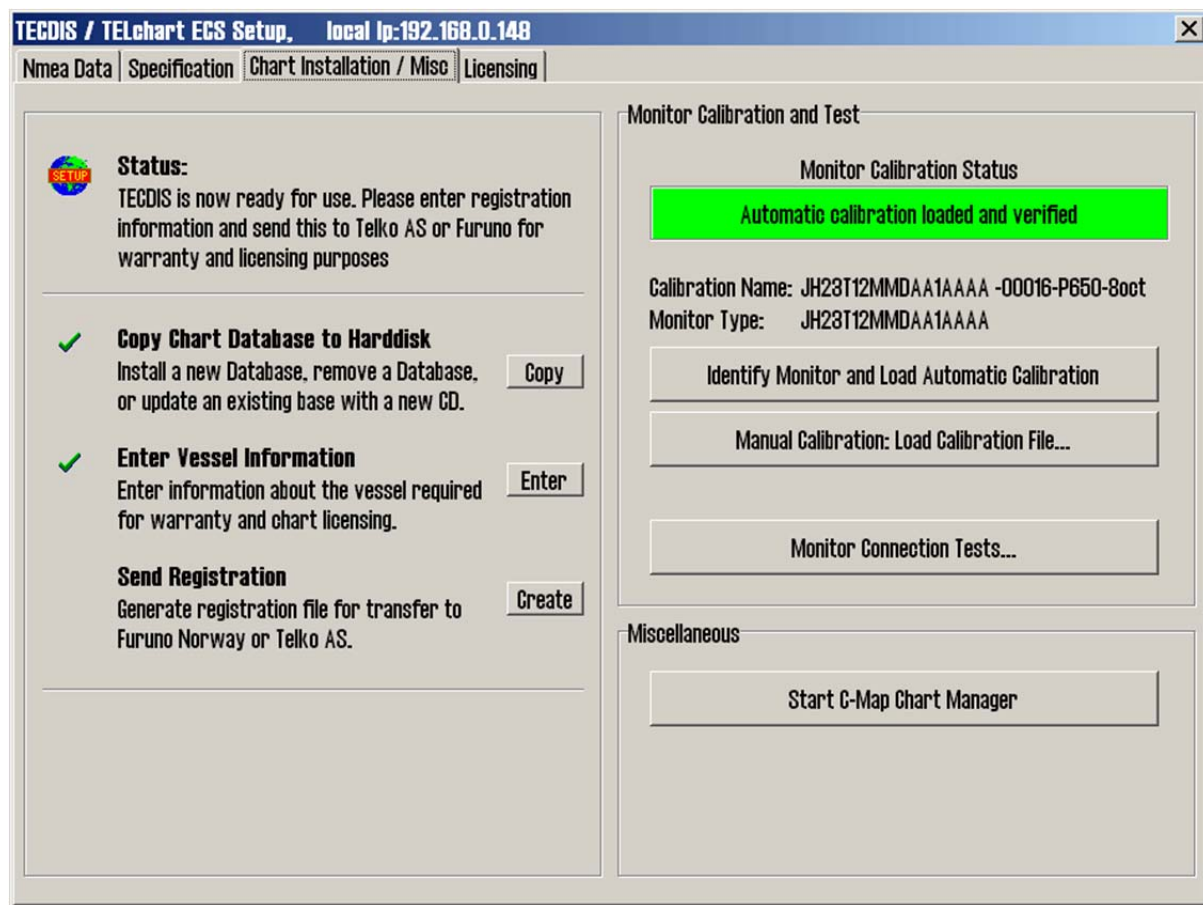
3.5.1   Install, update or remove chart databases

By clicking "Copy", a new area with an overview of installed chart databases is opened. Insert the CD for the chart database that is to be operated on and select the CD-ROM drive from the drop down menu below the database list. The Setup program will read the CD and display the available actions for the chart database. (Install, Update, Remove and 'Set as Default').

Important: 'Purchase' chart licenses are locked to a specific edition of the chart database. If a different edition of the database is installed, new licenses must be acquired. 'Subscription' licenses remain valid when newer chart database editions are installed.
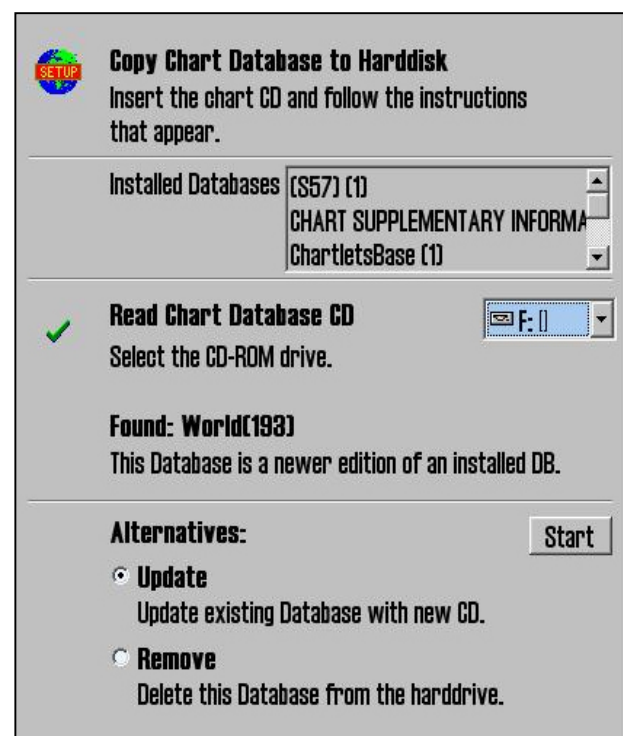
If a CD is not available for the chart database (As would be the case for databases containing imported S57 data), these databases can be selected for modification by choosing a drive *other than the CD-ROM drive* from the drive drop down menu. (For example D:\). When Setup is unable to find a chart database on the selected drive, you get the option to manually select an installed database by pressing the button "Select an Installed DB".

You will get two options for the database you select from the list of installed databases: "Remove" and "Set as Default". We recommend that the "World" database should be set as default, if installed.

Important: Some chart databases are protected and cannot be removed unless you have a CD for the database available.

The option 'Remove Licenses' will also be displayed in some instances. Selecting this option and pressing 'Start' will allow you to remove all chart licenses for the specified database. Make sure you have new valid chart licenses available before starting this option!

3.5.2   Enter vessel information:

In this area, information about the vessel and owner should be entered. This information is needed for chart licensing and warranty purposes.

3.5.3   Send registration

When the vessel information has been entered and stored, the option to send registration will be enabled on the main area of this part of the Setup program. If "Send on Diskette" is selected, the registration file will be saved to an inserted diskette. If "Send Manually" is selected, the registration file will be saved on the hard drive and a message informing you about the file name and location of the file. Send this file to the specified email address whenever the "Vessel information" data is changed.

3.5.4   Start C-Map Chart Manager

The "Start C-Map Chart Manager" button provides access to the C-Map chart database, licensing and diagnostics interface.
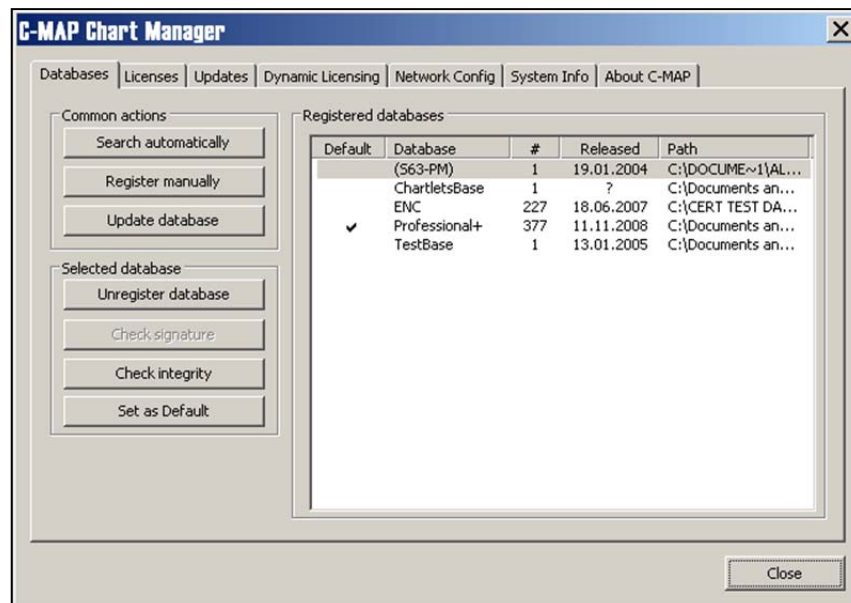
This can be useful when Jeppesen Marine support needs to make adjustments to the system.

By selecting a chart database and clicking "Check Signature", it is possible to verify that the database has not been corrupted and is in the same state as when provided by C-Map.

3.5.5   Monitor Calibration and Test

This area provides information on the current monitor calibration status, means to update the monitor calibration and diagnostics for testing the serial connection to the monitor.

Proper monitor calibration is needed to ensure correct chart colors and symbols.

To calibrate the monitor first attempt automatic calibration by pressing the "Identify Monitor and Load Automatic Calibration" button. If this is not successful, calibrate manually by pressing the "Manual Calibration: Load Calibration File…" button and selecting the correct calibration file matching the monitor. If such a file cannot be located, this can be obtained from your TECDIS support provider.
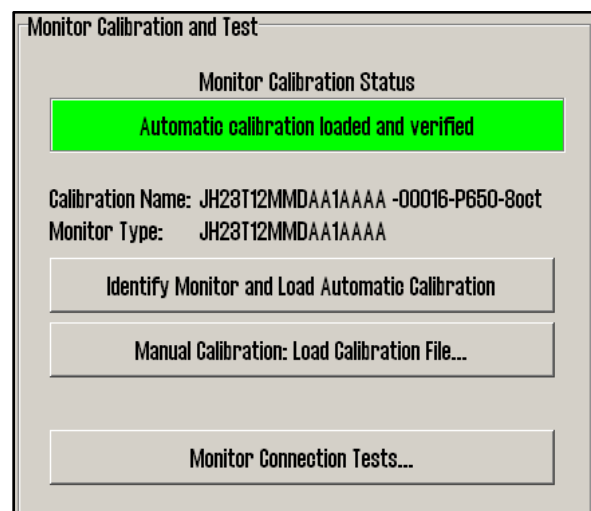
Monitor Calibration Status: Indicates the current status of monitor calibration. The possible values seen here and steps to rectify any problems are as follows:

Status	Tiltak
No serial line to monitor!	Connect the monitor to a serial port in accordance with Chapter 2: and 3.2.9.
Calibration not performed!	Perform automatic or manual calibration as outlined below.
Wrong manual calibration file loaded!	The manual calibration file loaded does not match the connected monitor. Obtain the correct calibration file from your TECDIS support provider and repeat manual calibration.
Monitor contains wrong automatic calibration!	The monitor does not contain the correct monitor calibration files. Contact your TECDIS support provider.
Automatic calibration loaded but not verified Manual calibration loaded but not verified	Calibration has been successfully performed. Verify correct calibration by comparing the monitor model specified in "*Calibration Name*" to the monitor model label.
Automatic calibration loaded and verified Manual calibration loaded and verified	Calibration has been successfully performed and verified.

Calibration Name: Indicates the name of the currently loaded manual or automatic calibration.

Monitor Type: Indicates the monitor model name as reported by the monitor during the last automatic calibration process.

Identify Monitor and Load Automatic Calibration: Initiates automatic identification of monitor type and attempts to load automatic calibration data from the monitor.

Manual Calibration: Load Calibration File…: Allows the operator to manually load a monitor calibration file.

Monitor Connection Tests…: Provides access to tests to verify correct monitor serial connection (buzzer test, backlighting adjustment tests and monitor identification test).

3.6   Licensing
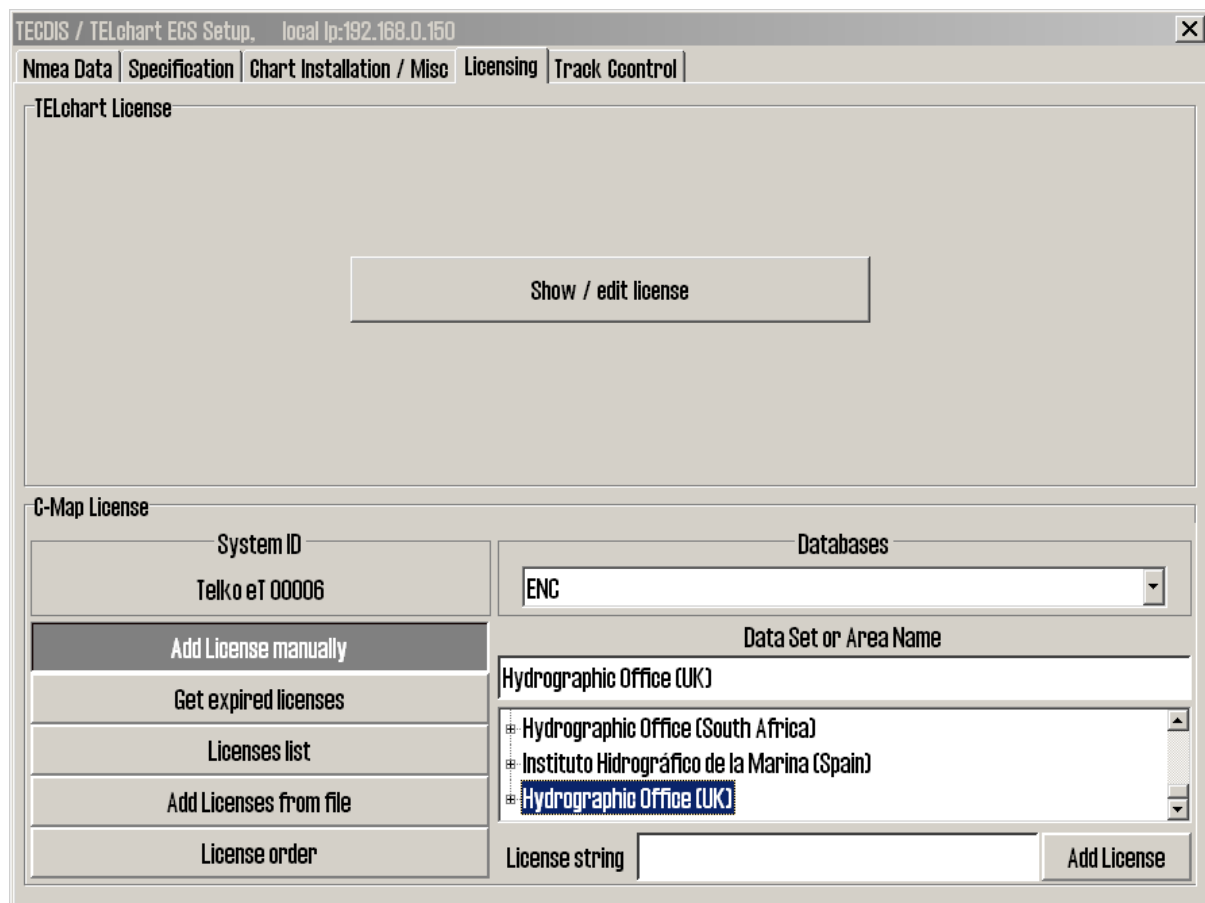
3.6.1   TECDIS license

By clicking "Show / edit license" information about the current system license is shown as illustrated below. This information includes the license number and version information, and a list of installed optional components in blue in the right part of the area. In order to activate additional optional components, a password for this should be entered in the "Password" field and the "Program" button should be clicked.
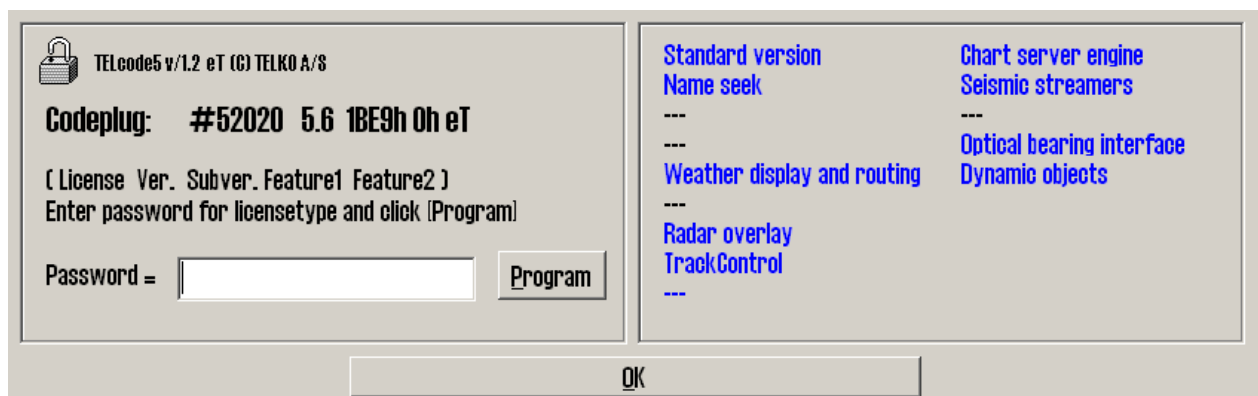
3.6.2   C-MAP License

Add licenses manually: Select the zone or area you have received a license for in the window to the right (under "Data set or Area name"). The 16-character license code is entered in the "License string" field. Finally, click on "Add License" to activate the license.
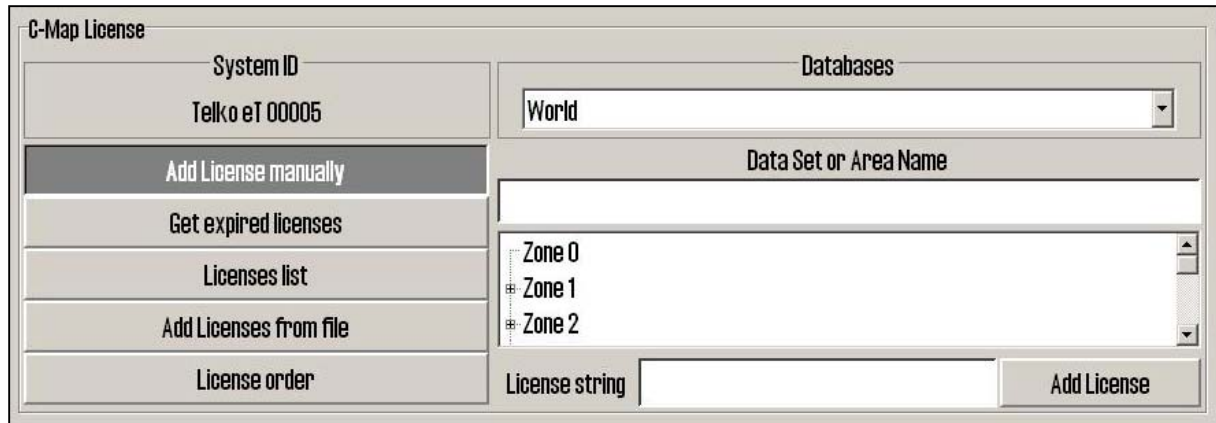
Add license from file: Use this option if you want to use a supplied password.usr file to activate chart licenses, browse to the location of this file and select it and press "OK". The licenses contained in the file will be automatically activated.
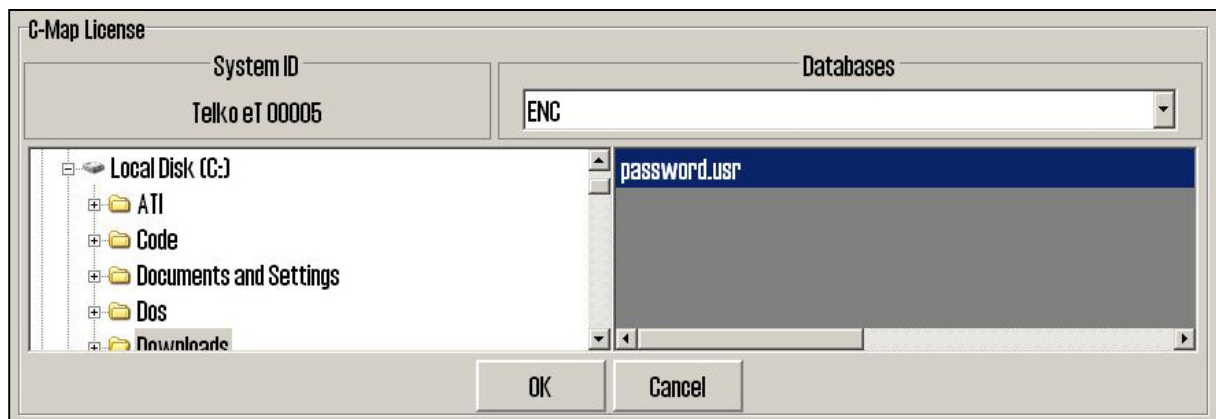
In this area, it is also possible to get a list of licenses that are expired and no longer valid ("Get expired licenses"), to see a list of all valid licenses ("Licenses list") and to generate an order file for new licenses ("License order").

3.6.3 __Dynamic Licensing__

TECDIS includes full support of Jeppesen Marine's Dynamic Licensing solution for ENC charts in C-MAP SENC format. Dynamic Licensing provides a cost-effective method for ensuring continual vessel ENC coverage with minimal overhead and administrative costs.

3.6.3.1 Traditional ENC Licensing

Previously, the only way to acquire ENC charts for paperless navigation has been to purchase subscriptions for all ENC charts required by the vessel in advance. Activating the ENC charts on the vessel requires license codes to be entered on the onboard ECDIS systems, both initially and each time the chart licenses expire. Typically, each required ENC chart is licensed for a 12 month period, regardless of whether the vessel actually makes use of the ENC chart or not.

3.6.3.2 What is Dynamic Licensing?

Dynamic Licensing is a subscription agreement between the vessel operator and Jeppesen Marine that gives the vessel immediate access to ENC charts within the subscription area. The subscription incurs no immediate costs to the operator. Once the subscription agreement is active, the vessel ECDIS systems will provide immediate access to any ENC charts required within the subscription area, either for planning or monitoring. There is no need to enter any license codes.

3.6.3.3 Credit Limit

To prevent uncontrolled licensing costs, the subscription agreement includes a yearly credit limit based on estimated yearly costs for the vessel. When an ENC chart is licensed by the ECDIS system, the licensing cost for the chart is subtracted and the credit limit is reduced accordingly. This credit limit can be extended whenever needed.

3.6.3.4 Automatic licensing

When the vessel requires access to a new ENC chart, the system immediately activates a 3 month license for the chart[2]. If the vessel again requires access to the same ENC chart after this period, a new 3 month license is activated. This means that an ENC chart subscription is only purchased at the time the vessel actually requires the chart, and the 3 month licensing period ensures that no subscription costs are incurred when the vessel has no need for the chart.

3.6.3.5 Reporting usage

The activated ENC chart licenses are automatically reported back to Jeppesen Marine whenever the vessel uses the C-MAP Update Service Online to download corrections to the ENC charts. Since the chart update process is required for paperless navigation, this does not require any additional work for the bridge personnel.

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[2] Some Hydrographic Offices requires 12 month subscription periods for all of their ENC charts. For these charts, 12 month licenses are generated.

3.6.3.6   Invoicing

Based on the reported actual ENC chart usage, Jeppesen Marine invoices the vessel operator for the licensing costs. This can either be done periodically, or whenever the total outstanding amount exceeds the maximum invoicing amount defined in the subscription agreement.

3.6.3.7   Benefits over traditional ENC chart licensing

Dynamic Licensing provides a clear cost advantage over traditional ENC licensing:

- Traditional ENC licensing requires predicting which ENC charts will be required by the vessel. Since ENC charts are only licensed when the vessel actually requires the chart with Dynamic Licensing, no charts not needed by the vessel are licensed.

- Traditional ENC licensing typically provides 12 month licenses for ENC charts. Since Dynamic Licensing generates 3 month licenses for ENC charts, licensing costs for charts that are only required periodically or for shorter periods are lowered significantly.

Dynamic Licensing provides a clear operational advantage over traditional ENC licensing:

- There is no need to predict future ENC chart requirements for the vessel, or to purchase chart licenses in advance.

- Activating new ENC licenses requires no chart licensing codes that need to be entered on the ECDIS systems.

- Usage reports are returned to Jeppesen Marine automatically during chart updating, an operation that is performed routinely regardless of licensing method.

To summarize, use of Dynamic Licensing ensures that ENC chart licensing costs are minimized, and administration of chart licenses is handled automatically by the system, reducing the workload both for bridge personnel and for vessel operators.

3.6.4   Using Dynamic Licensing in TECDIS

After a dynamic licensing agreement is made between Jeppesen Marine and the vessel operators, this feature is automatically activated in TECDIS the next time the C-MAP Update Service Online is used.

After activation, ENC charts will automatically be licensed for all required charts within a specified distance of the vessel[3]. This ensures that ENC coverage is always available for the vessel location, and that early route planning or spurious chart requests does not result in ENC licensing costs.
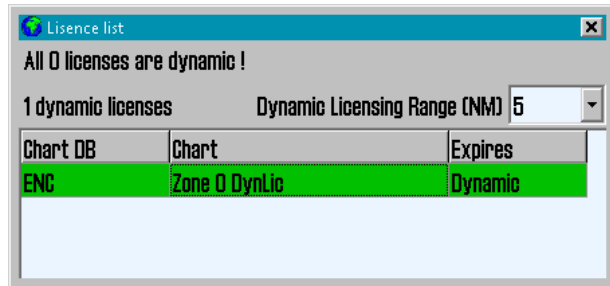
The current state of the dynamic licensing agreement (credit limit, last usage report and next reporting deadline) can be monitored by accessing the chart licenses interface in TECDIS and clicking on the dynamic license entry in the list (TECDIS Operators Guide chapter 3.2).

When the credit limit is lower than 200 credits or the next reporting deadline is within 3 days, this is reported to the operator as warnings in the alarm system. When the credit limit is exhausted or the reporting deadline has been exceeded, this is reported to the operator as alarms in the alarm system (TECDIS Operators Guide chapter 5.5).

Lists of dynamically licensed ENC charts (both reported and unreported) can be viewed in the C-Map Chart Manager, available in the "Chart Installation / Misc" folder in the TECDIS Setup program (TECDIS Operators Guide chapter 7.4).

3.6.4.1   Adjusting the distance limit for automatic ENC licensing

To adjust the distance limit for automatic ENC licensing, the TECDIS Service key is needed. When the TECDIS Service key is inserted, it is possible to adjust the distance limit in the chart licenses interface in TECDIS (See illustration above).

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[3] By default, all ENC charts requested within 5 nautical miles of the vessel are automatically licensed.

3.6.4.2   Route Planning using ENC charts

Since only charts within a specified distance are licensed automatically in standard mode, it is possible to plan a potential voyage in advance without incurring additional ENC chart licensing costs. Once it is decided that the voyage will take place, the voyage plan should be checked using ENC charts in order to comply with official requirements for paperless navigation.
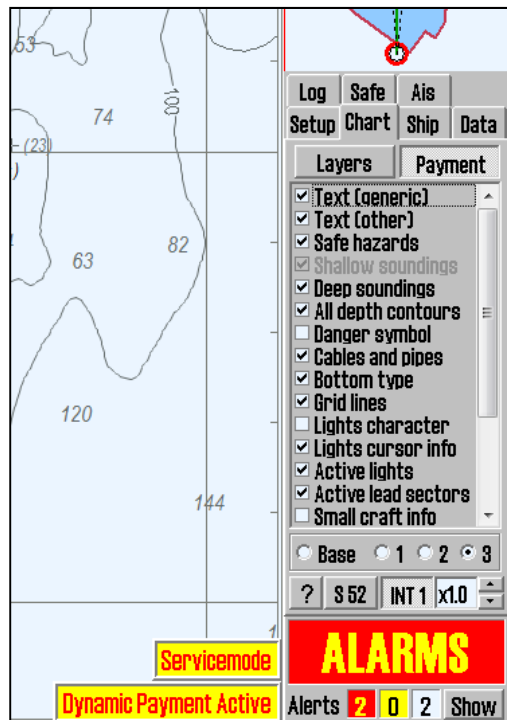
The TECDIS Service Key is needed to license charts outside the specified distance limit. When the TECDIS Service Key is inserted, a "Payment" button will be available in the "Chart" folder of the TECDIS menus. Pressing this button activates Payment Mode.

In Payment Mode, all requested ENC charts are licensed, disregarding the distance limit. A clear warning is displayed on screen, indicating that payment mode is active. A route check can now be performed and all dangers / cautions from the ENC charts will be displayed. The route can also be adjusted manually using ENC charts.

Once the voyage plan check is complete, Payment Mode is deactivated either by pressing the "Payment" button again, or by removing the TECDIS Service Key.

3.7 **Track Control**

On this tab, settings for connection to autopilots and Track Control can be set.

⚠️ **Refer to OEM Installation Manual for installation and configuration of the autopilot. NB: The autopilot and TECDIS must be supplied with the same heading and log sensor inputs!**

3.7.1 **Starting Requirements**

The values in this area specify the conditions needed before Track Control mode can be activated.

Max course deviation The maximum number of degrees the course over ground (COG) of the vessel can differ from the planned course.

Max lane deviation The maximum distance of the vessel position from the planned route leg, expressed as a multiplier of the planned route leg lane width. (For example, if the lane setting for the initial planned route leg is 100m, and 'max lane deviation' is set to x2, the vessel position can be up to 200m from the planned route leg when Track Control is activated.)

Min. speed The minimum speed of the vessel in knots.

3.7.2   Default values new route

The values in this area will be used as the default values for the parameters specified when planning a new route.

Speed kn   The default planned speed in knots for new route legs.

Lane x 0.01 NM   The default planned lane width for new route legs, expressed as hundredths of a nautical mile. (For example, if the value specified here is 10, the default lane width would be 0.1 NM.)

Turn radius x 0.1 NM The default planned turn radius for new route legs, expressed as tenths of a nautical mile. (For example, if the value specified here is 5, the default turn radius would be 0.5 NM.)

3.7.3   Other settings

Autopilot: In this field the type of autopilot should be selected. Only the type approved autopilots according to the certificate, should be installed and configured to work with the TECDIS. The selection made in this field is transferred to the "*NMEA*"-folder, where further configurations should be made.

Min. allowed turn radius x 0.01 NM
This setting specifies the minimum turn radius allowed, expressed as hundredths of a nautical mile. This value should be determined during vessel sea trials.

Max. allowed WOL distance x 0.01 NM
This setting specifies the maximum value allowed for operator selected Wheelover Line (WOL) distance, expressed as hundredths of a nautical mile.

Max Remote Control ROT
This setting specifies the maximum rate of turn (ROT) value allowed in the autopilot remote control panel in TECDIS, expressed as degrees per minute.

WP warning and alarm time
This setting controls how long before a waypoint warnings and alarms are generated.

Alarm limit difference primary and secondary heading
This setting controls the number of degrees the primary and secondary heading sensor values can differ before an alarm is generated. If the two heading sensors differ by more than this value, an alarm is generated in TECDIS.

Alarm limit difference primary and secondary position x 0.01 NM
This setting controls the distance allowed between the two position sensors before an alarm is generated, expressed in hundredths of a nautical mile. If the distance between the positions reported by the two position sensors is larger than this value, an alarm is generated in TECDIS.

3.8   Route Synchronization

TECDIS provides two alternative ways of transferring routes between the primary and secondary TECDIS units. Both solutions allow the operator to retrieve the planned route for the current voyage on the secondary TECDIS unit if the primary unit fails.

For this function to work correctly, the following must be observed:

1. The Setup field "Data export IP" must contain the correct address to the other TECDIS unit. (See section 3.3 Specification).
2. The TECDIS units must be connected using the specified LAN adapter ports.
3. The LAN adapter port used for connection between the TECDIS units should not be reconfigured to use an IP address outside the subnet (172.31.3).
4. (Replication) The TECDIS units must use unique license dongles (Telko eToken ID numbers must be different).

NOTE: The automatic method is activated by default in all TECDIS units produced after 1.November 2008.

3.8.1   Basic Method

When the basic route synchronization method is in use and a route is activated on either of the TECDIS units, a backup copy of the route is transferred to the other TECDIS. This backup is not automatically included in the route list on the receiving TECDIS unit, but it can be imported when needed.

The route is available for import from the following files in the *Data* subdirectory of the *TECIDS* directory (C:\Program Files\TECDIS\Data):

Primary Route   ReceivedPrimaryRoute.lst
Secondary Route   ReceivedSecondaryRoute.lst

3.8.2   Automatic Method (Replication)

When *Replication* is activated, all new routes entered, changes to existing routes and removal of routes is automatically reflected at the other TECDIS unit. In effect, the two TECDIS units will contain identical route databases.
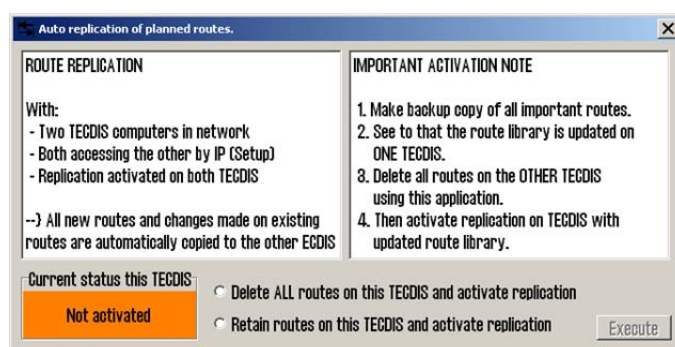
Activating Replication

Follow these steps to activate Replication:

1. Verify that the requirements for this feature listed above are met.
2. If routes are present on the TECDIS units, select one unit where all routes will be kept and one TECDIS unit where all routes will be removed.
3. On both TECDIS units, insert the Service Key and exit to Windows.
4. On both TECDIS units, run *C:\Program Files\TECDIS\Replication.exe*.
5. On the TECDIS unit where all routes should be kept, select ***"Retain routes on this TECDIS and activate replication"*** and press *Execute.*
6. On the TECDIS unit where all routes should be removed, select "***Delete ALL routes on this TECDIS and activate replication"*** and press *Execute.*
7. On both TECDIS units, remove the service dongle and reboot the system.

After both TECDIS units are again operational, all routes from the unit where routes were kept will be automatically transmitted to the other TECDIS. All further route changes are automatically reflected on the other TECDIS.

Deactivating Replication

If the replication feature needs to be deactivated, follow these steps:

1. On both TECDIS units, insert the Service Key and exit to Windows.
2. On both TECDIS units, *delete* the file *C:\Program Files\TECDIS\SetRtReplicateActive.txt*.
3. On both TECDIS units, remove the service dongle and reboot the system.

Chapter 4: Operational system settings

When pressing the menu folder button in the top menu bar, menu folders will open in the lower part of the side menu field. There are 7 different menu folders: *"Data"*, *"Log"*, *"Safe"*, *"Setup"*, *"Chart"*, *"Ship"* and *"AIS"*. The menus are separated in a folder system where of the folders is displayed at a time. Select the desired folder by pressing a folder title.

4.1   Setup

This folders contains.
1. Ship draught
2. Language selection
3. Time zone selection
4. Nmea input status
5. Nav. Position offset
6. Chart utilities
7. Chart library (installed chart databases)
8. Alarm volume (only shown when alarm sound is set to PC Speaker or Keyboard in TECDIS Setup)
9. Auxiliary
10. Hide/unhide tool tip.

Ship draught: minimum and maximum ship draught is defined in the setup program. When TECDIS starts, the maximum draught is used as default, but this can changed in the setup menu folder.

4.1.1   Nmea data inputs:

Displaying a list describing which ports the various sensor information is received from. Also displaying which Nmea sentences used and the data communication status. This is only a information window. Changes have to be made in TECDIS Setup. (see chapter 3).

Position fixing: Displays 2 sources for positioning. Primary and secondary can be selected. Primary and secondary can be displayed simultaneously on the chart display. If primary position fixing system falls out, the system automatically uses secondary. If both positioning systems drops out, change over to dead reckoning is executed. (Log+Gyro)

Nmea data inputs

sensor	port	id	describtion	status
Position 1	IP 1	GGA	Gps 1	OK !
Position 2	IP 1	GLL	Ais	OK !
COG/SOG 1	IP 1	VTG	Gps 1	OK !
COG/SOG 2	COM 4	VTG	Ais	no data
Heading 1	IP 1	HDT	Gyro	OK !
Heading 2	COM 11	HDT	Ais	OK !
Speed Log	IP 1	VHW	Log	OK !
Rd. Arpa 1	IP 1	TTM	Radar 1	no data
Rd. Arpa 2	COM 10	TTM	Radar 2	no data
Rd. curs.1	IP 1	RSD	Radar 1	OK !
Rd. curs.2	COM 11	RSD	Radar 2	OK !
AiS	IP 0	AIxx	Ais	OK !
Depth	IP 1	DPT	Dybde	OK !
Rel. wind	IP 1	MWV	Vind	OK !
Route	COM 10	RTE	DP	no data

Use Position 1 ▾ as primary position   OK

☐ Display both primary and secondary position

4.2   Operational parameters for the Ship

4.2.1   Own ship offcenter
Location of own ship on the screen. High value: Vessel is placed more offcenter. Low value: vessel is placed closer to screen centre. This function is only active when auto function is enabled.

4.2.2   Auto sensitivity
How often chart to be centered/shifted in Auto mode.

4.2.3   Show double circle
The boat symbol can be displayed with or without circles.

4.2.4   Show ship outline
This option allows the true vessel outline to be displayed in the chart.

4.2.5   Course vectors
Sets vector length on own ship and targets. (One cross line on vector is one minute).

4.2.6   Wheelover
Wheel over line distance from Waypoint. New command to track pilot and route monitoring.

Please verify these values with the vessel's **Master** before finalizing the installation. These parameters are not part of the setup program, but are included in the normal program.

4.3   Operational parameters for AIS

4.3.1   Display filter: Range and Track
AIS targets outside specified range are filtered from display. Track specifies length of AIS target tracks in minutes.

4.3.2   Display filter: All targets active
Allows all AIS targets to be shown with heading / COG vectors and tracks. In INT1 chart display mode, target names are displayed.

4.3.3   Display filter: Hide class B
Allows filtering display of class B AIS targets.

4.3.4   Display filter: Relative COG vectors
Allows display of COG vectors relative to own ship movement. Vectors are true if this option is not selected.

4.3.5   Lost active targets
AIS targets inside the specified range will be indicated with a black X over the target when it is lost. If *"Alarm when lost"* is activated, an alarm will be raised.

4.3.6   Danger CPA all targets
Specify time and distance limits for CPA alarms from all targets. "Show danger CPA" allows display of the CPA graphically in the chart.

If "Allow Standby Mode" is selected in TECDIS Setup (See chapter 3.3), it is possible to disable CPA alarms by unselecting "Raise CPA alarm". A prominent warning is displayed when CPA alarms are disabled.

4.4 <u>Chart library</u>

Chart library displays an overview of all chart in a database. Selecting a database from the drop down menu a list with all charts in the database appears, sorted by publisher. Highlight a chart in the list to display further information (middle field). When double clicking on a chart in the list, it will appear if license is present. When vessel is sailing, vessel is automatically centered. (if not auto function is disabled).

NB: Chart library only displays databases selected in setup menu folder.
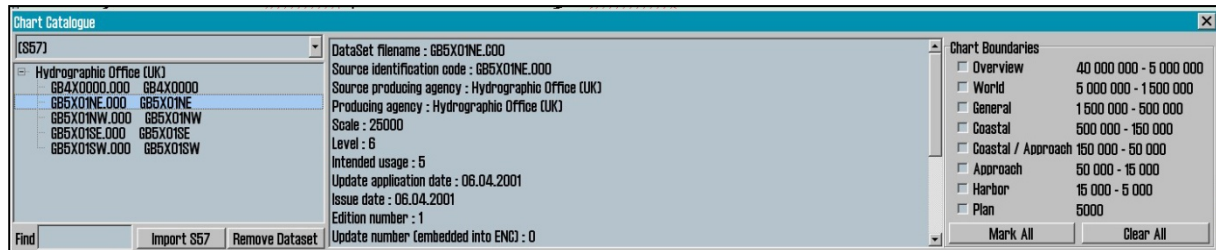
Chart boundaries: graphically presents coverage of all charts in the database at present level. (Levels comply with scale selected on the top menu bar) Licensed charts are displayed with magenta, non licensed charts are marked with black boundary. Chart names are presented in the bottom left hand corner of the square.
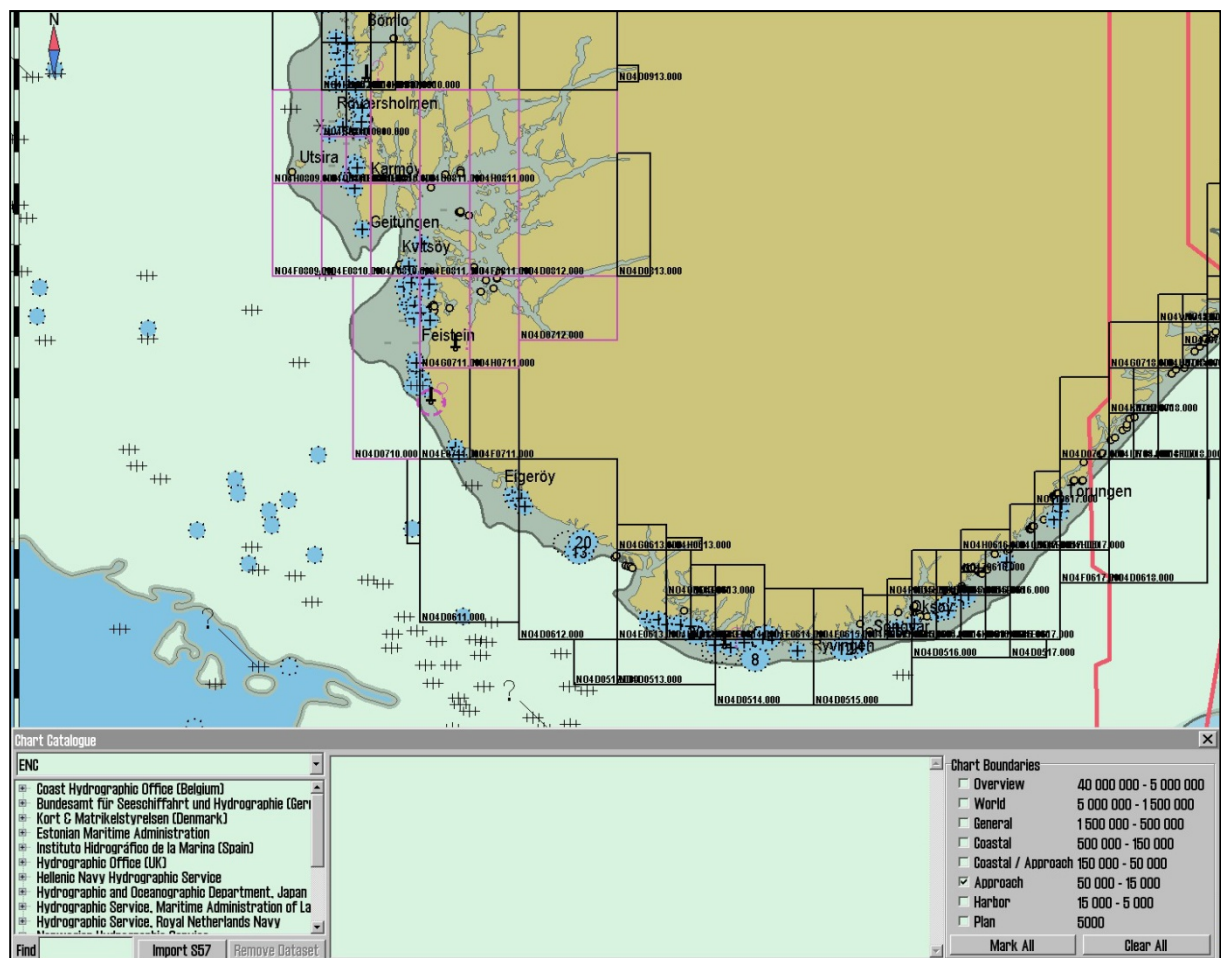
Remove dataset: If a database contains imported S57 data is selected in the drop down menu, the button" Remove Dataset" will delete selected chart.
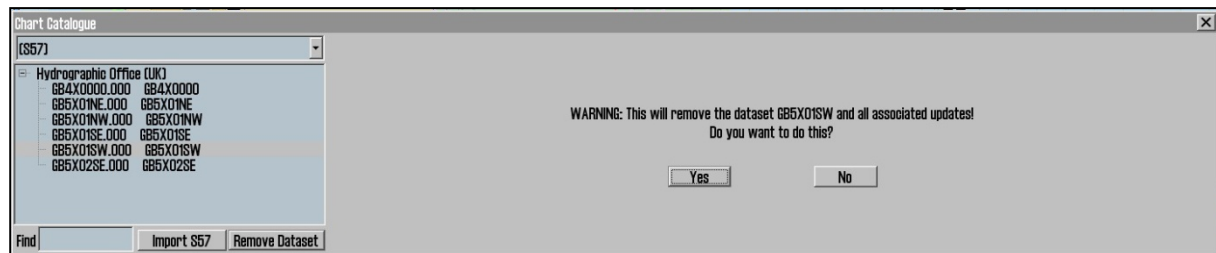
4.5   Import of S57 data

NB: When two ECDIS machines are connected, make sure to make the same updates in the second ECDIS.

Import of S57 data is done trough the chart library. Select database in the drop down menu and press "Import S57".

A database contains of datasets (charts). ENC data is sold as ENC cells in S57 format. Trough import to a database every ENC cell is converted to a dataset. This is a two step process: verification of data and conversion/compilation to a dataset.

To import data, select drive in the field "*Import S57 data from...*". Data is imported to a database which name begins with S57. However there are none S57 databases present, a new one

(S57) is created. Optional an own database can be created by pressing "create new database". S57 database is added automatically and can be highlighted for viewing in setup menu folder.
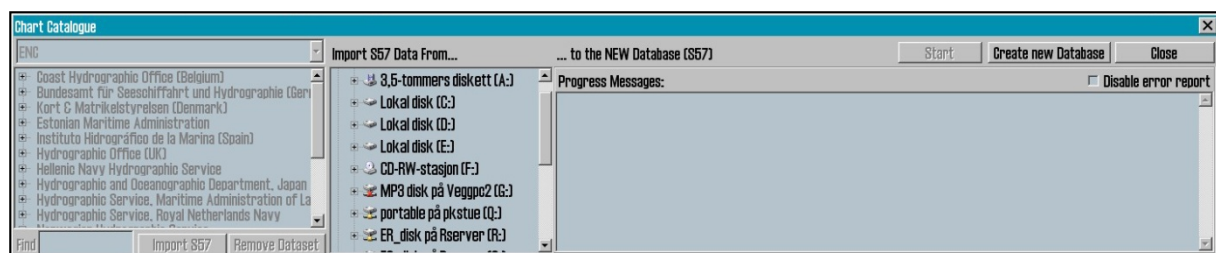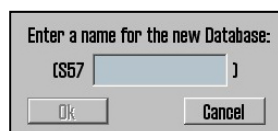
When drive is selected, the "start" button is activated. Press the button to commence import. Data is automatically verified.
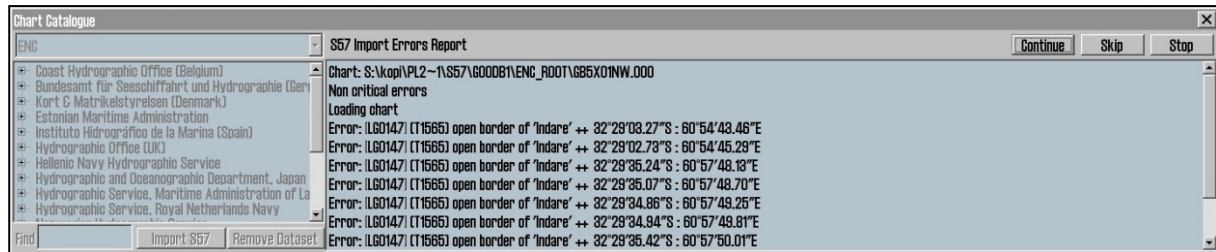
If errors are discovered a "**S57 Import ERROR report**" is shown. The error report contains name of import file and whether the error are critical or non-critical. Files including critical errors are not imported. If non-critical errors occurs, files can be imported or excluded by pressing "continue" or skip. If "stop" is pressed the import process is terminated.

Disable error report: If this option is selected prior to data import, the process will run automatically. S57 import files including critical errors will be excluded and files with non-critical errors are imported.

NB: When using "disable error report", it is impossible to view detailed information about the data import. Also errors reasoning ENC cells not to be imported due to critical errors, are not displayed.
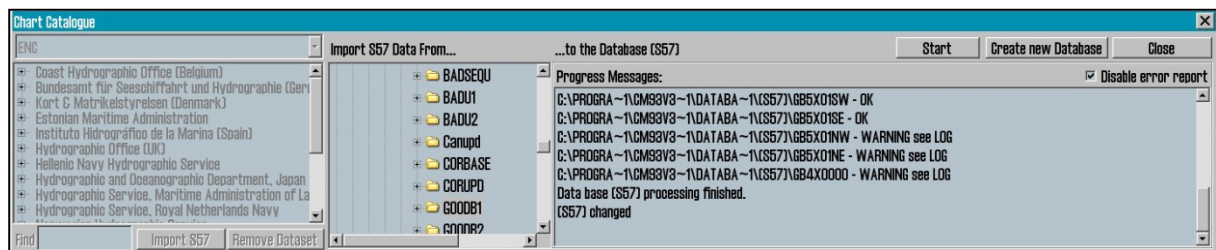
A import log will be created. This log can be viewed selecting actual dataset in the chart library, by scrolling down to S57 import log in the information field. If import of chart corrections are done in S57 format, those can be viewed in C-Map chart update.

By pressing the right mouse button in the message field, log files with information/history about file verifying and compilation are displayed. This is a overview, not a detailed report/log (not displaying any deleted datasets).

4.6   Import of S-63 chart data

For import of chart data in the S-63 format, refer to "S63 Loader User Guide", available for download from http://www.telko.no.

Chapter 5: Miscellaneous

5.1 <u>Error Messages</u>

TECDIS includes automatic error detection in most functions. If it is possible, corrective measures will be taken without requiring operator intervention. In case of critical errors, the operator is notified. In addition to the possible error situations listed here, both the Windows operating system and support routines may in some instances display error messages not listed. Common to these error messages is that corrective measures (if possible) are initiated by restarting the ECDIS. In the case of a system failure any error messages should therefore be noted. If the ECDIS is not responding or appear to be malfunctioning, try restarting the ECDIS. If this does not correct the error situation, notify your support contact.

10=Init required too much space	Memory full or error. Try restarting ECDIS.
11=Bad init parameters	System error, should not normally occur.
12=Data files not found	Old data file has been erased or destroyed. New (empty) data file is automatically generated.
13=Open db cannot determine type of file	Installation error, use of invalid data.
14=Data files appear to be corrupted	Try restarting ECDIS to generate new data file.
16=Could not create index file	Hard drive error or full, try erasing old data.
17=Could not create data file	Hard drive error or full, try erasing old data.
18=Tried to create existing index file	System error, should not normally occur.
19=Tried to create existing data file	System error, should not normally occur.
24=Could not close file	System error, probably memory error.
46=File number already in use	System error, should not normally occur.
47=c-tree has not been initialized	System error, should not normally occur.
101=C-Map system files not installed	Incorrect or incomplete installation.
102=No C-Map charts installed!	Incorrect or incomplete installation.
103=No chart database set as default!	Incorrect or incomplete installation.
104=g_manager->Init() failed	System error, should not normally occur.
105=g_map->Init() failed	System error, should not normally occur.
106=g_mini->Init() failed	System error, should not normally occur.
107=Update successfully completed	Update confirmation.
108=G_MAP->SETZOOM() FAILED	System error, should not normally occur.
109=g_map->SetScale() failed	System error, should not normally occur.
110=g_mini->SetScale() failed	System error, should not normally occur.
111=g_map->SetRotation() failed	System error, should not normally occur.
112=g_mini->SetRotation() failed	System error, should not normally occur.
113=g_map->AddBase() failed	System error, should not normally occur.
177=Not TECDIS dongle	License dongle found but not approved.
188=Error in periodic ID check	No license dongle found or approved.
189=File read failed	Error in license dongle.
190=Read of file length failed	Error in license dongle.

191=File number out of bounds	Error in license dongle.
192=Cmap init error	License dongle not C-Map approved.
193=Init has not been called	Error in communication with license dongle.
194=Error parsing system ID	Error in communication with license dongle.
195=Cmap registry error	Error in communication with license dongle.
196=Dongle is not Telko dongle	License dongle not approved.
197=No eToken dongle present	No license dongle found.
198=Cmap init error	Error in license dongle.
199=Init has not been called	Error in communication with license dongle.
200=Unknown error	Important! With errors relating to license dongle, try removing then reinserting the license dongle, or try moving it to another USB port. Then try restarting the ECDIS.

5.2 Monitor Calibration

All information in electronic chart displays must be highly visible. To ensure this monitor must be calibrated to display correct colors. This is very important, specially for night palettes, when monitor is dimmed.

ECDIS color test for monitor calibration is also placed in IHO presentation library. Open library by pressing Control + alt + shift + T, and select test diagram by pressing A – B – C- D- E or T on the keyboard.

Brightness check: Open test diagram E and verify that the grey box is clearly visible.

Check colors: Open test diagram T. All diagonal lines to clearly separate from background:
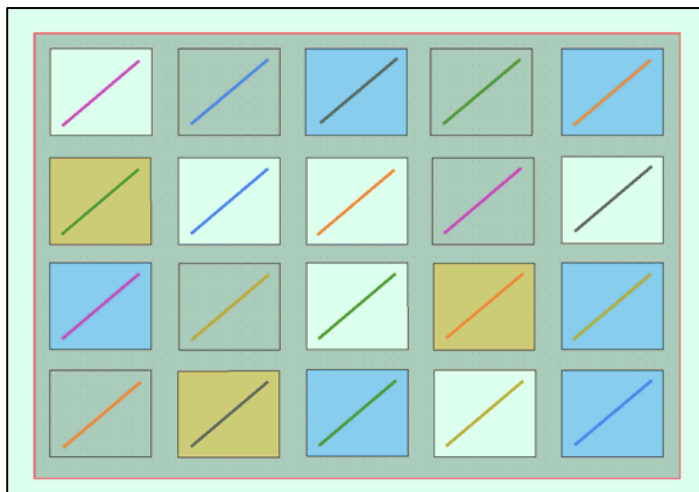
- 3 Yellow diagonal lines
- 4 orange diagonal lines
- 3 MAGENTA DIAGONAL LINES
- 4 green diagonal lines
- 3 blue diagonal lines
- 3 grey diagonal lines

Check visibility of each color in the diagrams (A-E). If the monitor fails the test, it no longer meets the minimum requirements for display performance. It should be evaluated by a qualified engineer and be repaired or replaced as necessary.

This test must be performed with all color palettes on the system (day/dusk/night).

NB. If monitor settings has been changed manually in the monitor menu, or to make sure correct settings are used, go to "setup" menu folder, press "Auxiliary" and select "recalibrate screen"

5.3   Internet/VSAT connection troubleshooting

For all problems with downloading weather data or chart updates, regardless of connection type used, your TECDIS supplier and/or Jeppesen Marine will be able to provide very useful assistance in tracking down the cause of weather download problems. Logs kept by Jeppesen Marine will show whether your weather download attempts reach the weather data servers and whether the requests are successful. They will also be able to verify that there are no problems with your subscriptions.

In order for Jeppesen Marine or your chart system supplier to help you, they will need your System ID number.

Before contacting anyone, at least some of the tests here should be attempted. Tests applicable to only weather overlay features are marked (Weather). Tests applicable to only chart updates are marked (Updates).

GENERAL TESTS

A. **Check your subscription**. Make sure that your subscription has not expired. Weather Overlay: Expiry information can be seen by opening the weather overlay, pressing 'Data', 'Download New' and then 'Show Subscription'.

B. **(Weather) Update your subscription.** Jeppesen Marine may make changes to the weather service that are not automatically reflected by in your subscription.

C. **Try another connection method.** If you use an internet connection, try downloading by email. If you use email already, try using another email account/system. If this is successful, you have verified that the problem is with your connection, not your chart system or a problem with the update / weather service.

D. **(Weather) Try a smaller download size.** The problem may be connected to downloading large files, especially if the connection is "noisy" and/or error prone.

E. **(Weather) Try another model.** The problem may be connected to downloading a specific forecast method. If a download of similar size using a different model is successful, the list of potential causes for the problem is significantly reduced.

F. **Try updating the chart software.** Telko AS provides software updates containing both bug fixes and new features free of charges at our website http://www.telko.no. Your problem may be due to a bug in the software that we have fixed in an update.

INTERNET CONNECTION

G. **Make sure that the internet connection is not turned off.** In a valid TECDIS installation with a direct internet connection, a switch has been installed so that the internet connection can be turned off when not in use.

H. **(Weahter) Try setting a higher Connection Timeout.** The download attempt may be timing out before the request can be completed. Refer to weather overlay documentation section 1.2 step 6 for details.

I. **Verify that you can reach the servers.** Exit the chart system (For TECIDS: insert the TECDIS Service Key first), open Internet Explorer and try the following addresses. If the reply does not match what is indicated in this table, you are not reaching the weather service servers.

http://distribution.c-map.no http://datacenter.c-map.no http://datacenter.jeppesen.com	Should show: Connection OK

J. **If test I failed, see if you can reach the servers using IP addresses.** Continue where you left off in the previous test. Try the following addresses and see if the replies match what is specified in the table.

http://80.239.21.75 http://80.239.21.103	Should show: Connection OK

If these tests succeed, the problem is with your DNS Settings. If you have not performed test F, do so now, then run the following file and see if the problem is fixed: C:\Program Files\TECDIS\AddCMapHosts.exe.

K. **If test J failed, have your network administrators check the firewall.** Make sure that the firewall in your internet setup is not blocking your weather data requests.

E-MAIL CONNECTION

L. **Check your spam folder.** Make sure that the replies to your request email from Jeppesen Marine are not being marked as spam.

M. **Try setting a lower Max Attachment Size.** Your email service may be having problems with the weather data attachments. Try lowering the Max Attachment Size value in the Configure Connection window.

N. **Make sure you are not using old request / reply files.** Delete all request and reply files from the USB memory stick so that you are sure you are not using the request or reply files from a previous download (or from the other TECDIS).

O. **Update only one TECDIS at a time.** If you send weather / update requests from both TECDIS systems at the same time, it is very easy to get the reply files mixed up.

Chapter 6:   Checklists regarding installation

6.1   Checklist prior to completion of TECDIS installation

Item:	Task to be performed:	OK:	Comments
1	Verify that all selected ports are receiving/transmitting data, and that ports have been given names on both main and back-up TECDIS. Names shall be according to the data they are receiving/transmitting.		
2	Verify that sensor data is correctly distributed between main and back-up TECDIS (NMEA server program).		
3	Verify that one single action do not result in loss of position on both main and back-up TECDIS.		
4	Verify that main and back-up TECDIS and respective equipment are connected to a proper UPS.		
5	Verify that boat size are correct compared to chart on both main and back-up TECDIS.		
6	Perform monitor color calibration on main and back-up TECDIS.		
7	Verify that alarm function on both main and back-up TECDIS is working properly.		
8	Check that TECDIS transmits alarm to external systems.		
9	If installed, verify generation of conning picture and correct display of sensor data on conning monitor (check against engine telegraph, speed repeaters, gyro repeaters etc)		
10	Verify audible signal from alarm speaker on TECDIS		
11	Verify sensor data (correct size of vessel etc) is filled in on main and back-up TECDIS.		
12	Verify that back-up of default setup values have been performed (save setup default values) on main and back-up TECDIS.		
13	Verify that installed charts have been correctly installed on both main and backup TECDIS (if installed), and that charts license matches.		
14	Unplug TECDIS USB-key, restart TECDIS to verify it starts up in normal mode (chart program starts automatically) and boat symbol and sensor data are displayed.		
15	If connected to internet, verify that a switch is available to disconnect TECDIS from internet when the connection is not in use.		
16	Fill in hardware/software fact sheet and file it in ships documents, in technician personal files and send a copy to Furuno Norway or Telko AS.		

Item:	Hardware	Model/type:	Serial no.
17	Keyboard Main		
18	Keyboard Back-up		
19	Processor Main		
20	Processor Back-up		
21	Telchart alarm interface		
22	Trackball Main		
23	Trackball Back-up		
24	Analog signal collector		
25	Monitor Main		
26	Monitor Back-up		
27	Conning monitor		
28	Conning monitor Back-Up		
29	Alarm loudspeaker		
30	MOXA interface		
31	AUTOPILOT		
32	Additional units		
33	Additional units		
Item:	**Software**	**Version:**	**Comments:**
34	TECDIS Main		
35	TECDIS Back-up		
36	AUTOPILOT		
37	Additional software		
38	Additional software		
Item:	**License**	**Number:**	**Comments:**
39	TECDIS license # Main		
40	TECDIS license # Back-up		
41	Sent TSZ-files tsz@tecdis.no		

Vessel Name / ID:	
Date of installation:	
Name of technician and company:	
Checklist performed (Sign):	

This checklist shall be filled in and signed for all TECDIS installations, in order to verify proper installation of the ECDIS system onboard.

6.2 Checklist prior to completion of TECDIS TCS and TECDIS AW installation

If installation includes Track Control functionality, the following tests must be performed.

TECDIS 1 and 2

No.	Function	Requirement	Results
		Harbor Acceptance Test (15 minutes)	
1	External data	Go to setup menu and verify NMEA inputs are valid. Check input values for position and course.	TECDIS 1: ☐Good ☐NG ☐N/A TECDIS 2: ☐Good ☐NG ☐N/A
2	External data	Verify that TECDIS receives valid sensor data from a minimum of: • Two independent positioning sensors • Two independent heading sensors • A speed sensor	TECDIS 1: ☐Good ☐NG ☐N/A TECDIS 2: ☐Good ☐NG ☐N/A
3	Alarm system	Verify that TECDIS is connected to a separate alarm system.	TECDIS 1: ☐Good ☐NG ☐N/A TECDIS 2: ☐Good ☐NG ☐N/A
4	System status	Check that no alarms/warnings are pending in alarm window.	TECDIS 1: ☐Good ☐NG ☐N/A TECDIS 2: ☐Good ☐NG ☐N/A
5	Chart database	1,Select setup menu, chart utilities, chart licenses 2,Verify that licenses are valid for intended voyage 3,Click C-Map chart update 4,Verify that charts are updated in update log	TECDIS 1: ☐Good ☐NG ☐N/A TECDIS 2: ☐Good ☐NG ☐N/A
		Sea Trial Test (15 minutes)	
6	AIS and ARPA Targets (If present)	1,Activate ARPA on radar and select a target. 2,Click the symbol button of [ARPA Targets]. 3,Click the symbol button of [AIS Targets]. AIS and ARPA Targets are displayed on the top of charts.	TECDIS 1: ☐Good ☐NG ☐N/A TECDIS 2: ☐Good ☐NG ☐N/A
7	Conning display (If present)	Correct indication is shown at the each configured window on the Conning Display. Verify that selected sensors used by heading, position is correctly indicated.	TECDIS 1: ☐Good ☐NG ☐N/A TECDIS 2: ☐Good ☐NG ☐N/A

8	Route Monitoring	Before start TEST, routes must be created or transferred from other TECDIS:
		1,Press the [Plan] key, icon with number 1 indicated is active.
		   This means primary route will be selected. Choose a route
		   with boathook icon.
		2,Press [YES] icon to activate route.
		3,Route is then shown on displayed charts.
		4,To display secondary route choose icon with button 2 indicated. Repeat procedure as for primary route.
		5 To exchange primary and secondary route, press icon with 1↔2 indicated.
		6. Observe that correct warnings is activated as appropriate.
		7. Click alarm icon for display of alarms and warnings on route.
		8. Test that activating track steering is successful.
			TECDIS 1:
			☐Good ☐NG ☐N/A
			TECDIS 2:
			☐Good ☐NG ☐N/A

9	Radar overlay (If present)	Check that radar overlay from radar is displayed on display after pressing radar overlay icon.	TECDIS 1: ☐Good ☐NG ☐N/A TECDIS 2: ☐Good ☐NG ☐N/A
10	Aids to navigation	Verify that TECDIS handle different functions like; 1. Disconnect position sensors and observe dead reckoning performance, verify that alarm is given: pos sensor ½ lost. 2. Activate track dialog and set past tracks visible by clicking on "show" icon. 3. Enter manual fix, by activating "bearing" icon. Click on center button on mouse when mouse is in position of visual object. Use observed gyro bearing to make a red line in chart towards estimated position. Repeat procedure to make two lines resulting in a cross bearing. 4. Update charts, enter chart utilities menu, choose C-Map charts update. Use semi-auto update. Create a update request file on memory stick. Send file to updates@c-map.no and load received file into TECDIS. Update loaded successfully shall be presented when update Is completed. 5. Activate a route in route menu. To alter at route underway, click on "Edit" icon in route menu. Modify route and click on "OK" icon. Route is now altered. When at track steering mode, 3 waypoints are not allowed to alter, last waypoint, next waypoint and waypoint after next. 6. Manual adjustment for position is available in setup menu, click on "nav. position offset" icon and a dialog box appear in top right corner of map. Enter offset values as appropriate.	TECDIS 1: ☐Good ☐NG ☐N/A TECDIS 2: ☐Good ☐NG ☐N/A

Autopilot type (tick one box only):

☐ Anschütz NP 2025 PLUS Adaptive Autopilot
☐ Furuno FAP 2000 Autopilot
☐ EMRI SEM 200 Autopilot

No.	Function	Requirement	Results
Harbor Acceptance Test (15 minutes)			
1	External data	Correct number is shown at each box of below. "Heading", "Speed"	☐Good ☐NG ☐N/A
2	Heading Control	1,[HEADING CONTROL] is activated when steering mode switch is set to "auto". Present heading is displayed in heading display and in preset heading display. Present heading is activated as set heading. 2. Verify parameter settings for rudder, yawing, counter rudder, rudder limit, ROT limit and radius value. Verify mode of heading change, radius or R.O.T. mode by observing key lamp. 3. Alter set course by either turn knob and push set button to acknowledge or push and turn knob. Observe correct rudder response. 4. Observe rudder movement. 5. Observe that max rudder limit is not exceeded.	☐Good ☐NG ☐N/A
3	Steering Control	1,Rudder moves to 10 degrees PORT when SET HEADING is set by 20 degrees below Gyro heading. 2,Confirm the actual rudder angle by rudder angle indicator.	☐Good ☐NG ☐N/A
4	Function	1. Change operating mode from hand to heading control at Track Control TECDIS , verify that correct mode is indicated on TECDIS and conning monitor also. 2. Shift from heading control to manual mode by switching steering mode selector. Verify that change to manual mode is possible from all modes with a single operator action.	☐Good ☐NG ☐N/A
5	Function	1. Change set course 50 deg to starboard, off-heading alarm not to be activated during setting of new course. Alarm is de-activated for a time period that is a function of present course and new desired course.	☐Good ☐NG ☐N/A
6	Function	Test override tiller in modes: hand, heading control and track control. Autopilot to go to hand	☐Good ☐NG ☐N/A
Sea trial test (240 minutes)			
1	Heading Control	Response and stability of "Heading Control" steering. 1,Observed overshooting should max 2 deg on 10 deg course change and max 5 deg on 60 deg course change. 2,Repeat another side course change with same value. Starboard 10 deg turn with NAV FULL speed (If available). Port 10 deg turn with NAV FULL speed (If available). Starboard 60 deg turn with NAV FULL speed. Port 60 deg turn with NAV FULL speed. Tests to be repeated with half speed ahead.	☐Good ☐NG ☐N/A
2	EMC	Testing of interference of radio transmissions while in heading control, observe system while: 1. Transmitting a call with FS-2570 2. Transmitting a call with VHF's 3. Transmitting a message with Felcom-15 1&2 4. Transmitting a call with Felcom-70	☐Good ☐NG ☐N/A
2	Track Control Steering	Steering function test should be performed as follow in the next lists "**Track Control Test** " and **"Fail to Safe Properties"**	☐Good ☐NG ☐N/A

Track Control System Test
Items to be checked during sea trial

No.	Item	Content	Result	Remarks
1		The following units have to be tested prior to the Track Control test: ECDIS AUTOPILOT STEERING GEAR		
2	Route	Create a test route for Track Control in keeping with the vessel maneuverability as per shown example attached (or import by file).		
3	Route monitoring	1. Enter route menu, check that icon "1" is activated (primary route). Use boathook to select route from previous test item. Click yes when asked to activate route. 2. Check that route monitoring parameters are shown in right menu (XTE, next waypoint info etc.)		
4	Track keeping	1. Check that ship follows the test route selected on ECDIS. *Recommend test speed is normal sea speed 2. Check performance according item 1 with speed reduction applied in one turn. 3. Check performance according item 1 with inducing current effect by using bow thruster during turn.		
5	Alarms	1. Set WP pre-warning and WP approach time on the ECDIS as per drawing below. Verify that WP approach Alarm is generated when the ship approaches the WP. 2. Verify that separate Alarm system activates back-up navigator alarm when WP pre-warning and WP alarm on ECDIS is not acknowledged. 3. Set alarm for gyro mismatch to minimum in TECDIS Setup program. Wait for alarm to be raised. 4. Activate route and use "Heading Control" mode on autopilot. Steer outside channel limit to generate XTE alarm. 5. Set "Heading off" alarm low and use bow thruster to provoke a heading drift. Verify that alarm is raised.		

Example of route for Track Control testing
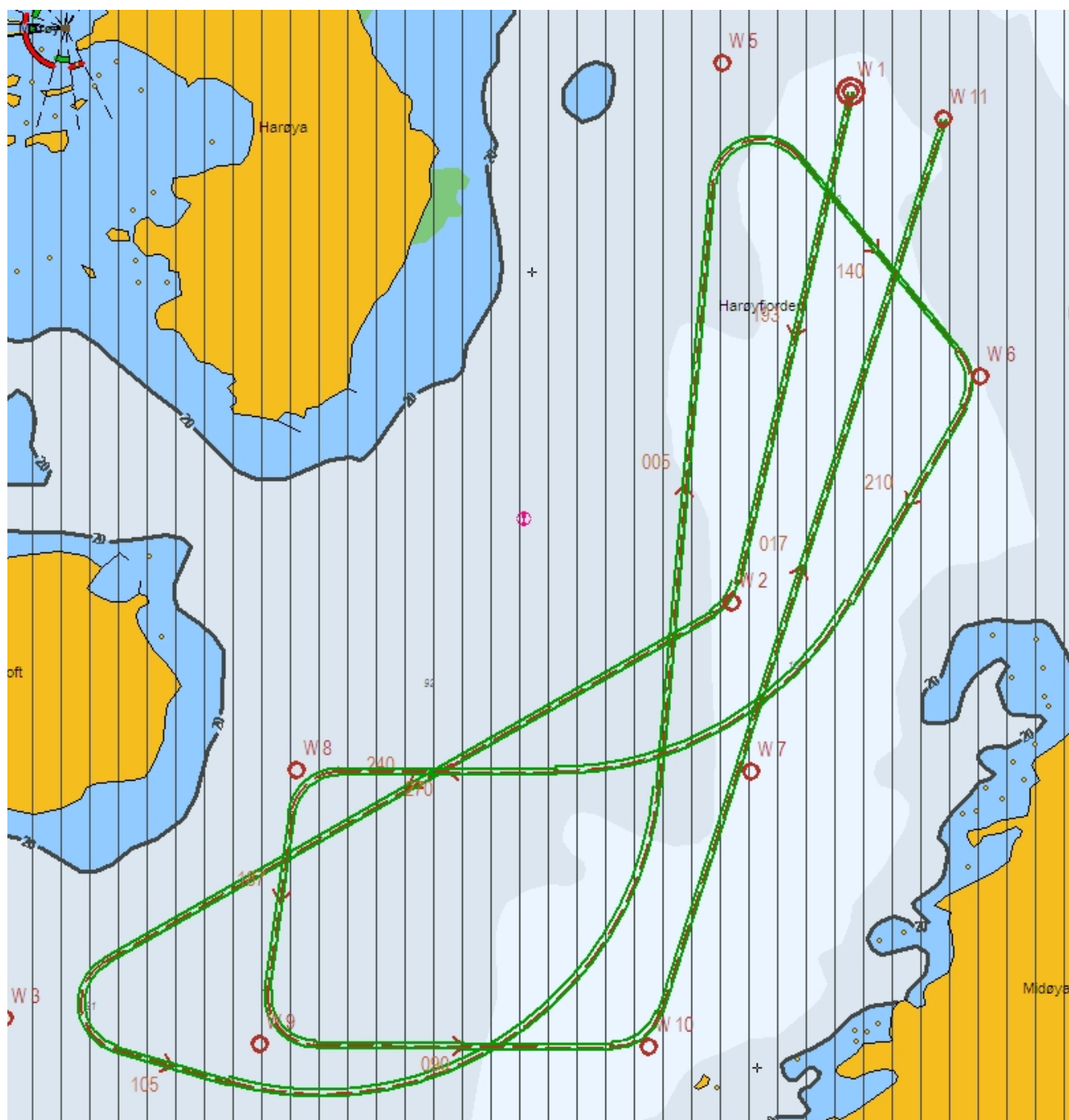
WPT 3: 135 deg turn port, WPT 5: 135 deg turn starboard (both with minimum radius*)
WPT 4: 60 deg turn port, WPT 7: 60 deg turn starboard (both with 2 NM radius)

* Minimum radius to be settled after calculations from yard.

*ECDIS Scheduled Track
Course 90 deg*

*AP Scheduled
Course 90 deg*

Wheel Over Point

*WP Approach alarm   30
sec before wop*

*Pre-Warning alarm
120sec before wop*

*Trial Speed
NSR*

Approach run

TCS Test 2)
Failure point
at straight leg

*Ship start turn from
wheel over point with 90
deg Angle*

Turn radius is
with 1.0NM

TCS Test3)
Failure point in turn.
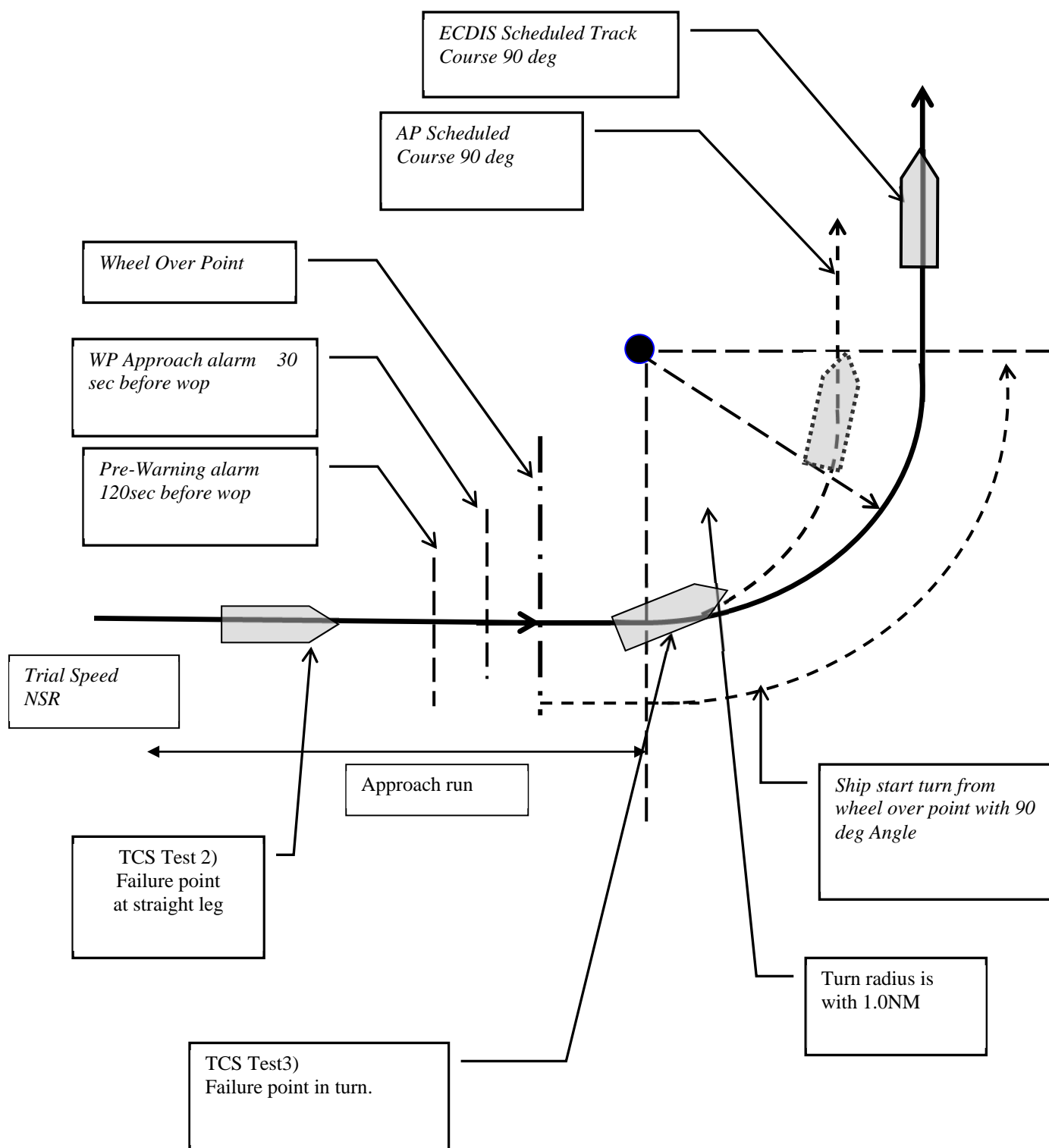
Fail to Safe Properties

Item	Fail	Track Control (TCS)	Test	Result
1	Position sensor antennas to be blinded off.	When either of position sensor acquisition stops, TCS emits alarm but continues to function utilizing acquired position from other position sensor, LOG, and GYRO. When both position sensor acquisition stops, TCS emits alarm but begins navigation utilizing estimated position made available by LOG and GYRO. Then it (after 10min) automatically switches to Radius mode and manual maneuver will be in effect.	Remove No.1 position sensor antenna Remove No.2 position sensor antenna	
2	Disconnect position sensor on a straight leg.	Same as above	Remove No.1/2 position sensor	
3	Disconnect position sensor during max radius turn.	Alarm will be emitted only from ECDIS which places no influence on TCS function.	Remove No.1 position sensor output connector during maximum radius turn.	
4	Turn Heading Control System rudder limit to min value during min radius turn.	Not available.	Adjustment of rudder limit is not available.	
5	Disconnect serial link to heading controller during straight leg.	Emits alarm and stops TCS function simultaneously. It automatically switches to Radius mode and manual maneuver will be in effect.	Remove Track Control connection from ECDIS while sailing straight ahead.	
6	Disconnect serial link to heading controller during turn.	Emits alarm and stops TCS function simultaneously. Automatically switches to Radius mode and manual maneuver will be in effect after turning to the pre-determined maximum degree.	Remove signal cable exclusively in use for Auto Pilot outputted from ECDIS while turning.	
7	Disconnect speed log during straight leg/ or turn.	Although emits alarm, two position sensor data inputted maintains the normal function.	Remove LOG input outputted to ECDIS while turning.	
8	Simulate failure in ECDIS.	Same as item 5 or 6.	Turn off ECDIS	
9	Simulate failure in conning display.	Not influential	Turn off Conning Display	
10	Disconnect rudder feedback.	Emits alarm by Alarm System. If the deviation between order rudder angle and actual rudder angle is 5deg or more, the Alarm System emits alarm and freezes the actual rudder angle at this time.	Remove rudder feedback input outputted to Alarm System while turning. *** This test is dangerous !**	
11	Simulate failure in Autopilot	Emits alarm by Alarm System and stops TCS function. Rudder angle is frozen at this time.	Remove power connection to autopilot while turning. *** This test is dangerous !**	
12	Simulate failure in No.1 gyro.	Not influential	Switches automatically from No.1 to No.2	
13	Check that second gyro is automatic applied in case of failure in the active gyro.	Not influential		

Checklists prior to completion of TECDIS TCS and TECDIS AW installation completed

Vessel Name / ID:	
Date of installation:	
Name of technician:	
Checklist performed (Sign):	

The checklists in section 6.2 shall be filled in and signed for all TECDIS installations where Track Control functionality is present (TECDIS TCS / TECDIS AW), in order to verify proper installation of the ECDIS system onboard.

6.3   Additional checklist prior to completion of TECDIS AW installation

No.	Item	Content	Result	Remarks
1	Conning	Verify that when one of the ECDIS processors lose sensor data on one serial line, display of sensor data (relevant according to failed serial line) on conning monitor is not affected.		
2	General	Verify that installation is done according to block diagram for TECDIS AW system.		
3	General	Verify that installation is done according to functional description given for TECDIS AW system.		
4	General	Verify that required conning info according to NAUT AW requirements is displayed correctly.		
5	Gyro	Verify that requirements set forth in section 1.7 are fulfilled.		

Additional checklist prior to completion of TECDIS AW installation completed

Vessel Name / ID:	
Date of installation:	
Name of technician:	
Checklist performed (Sign):	

The checklist in section 6.3 shall be filled in and signed for all TECDIS AW installations, in order to verify proper installation of the ECDIS system onboard.

6.4   <u>Installation Notes</u>

Revision History

Revision 1.0 (13.05.2005)
- Initial revision

Revision 1.1 (17.06.2005)
- Illustrations updated
- Wiring and signaling diagrams added
- Hardware installation for auxiliary components added
- Some updates to setup software description

Revision 1.2 (29.08.2005)
- Equipment list updated
- Compass safe distance instructions added

Revision 1.3 (05.01.2006)
- Updated chapter 3.4, size and sensors. New choices: "backward (gyro-180°)" and "Raise alarm if HDT1-HDT2 > 2.5°"
- Updated illustrations in chapter 4.1.

Revision 1.4 (04.08.2006)
- Chapter 3.2.1: Updated text. Port collision warning (case 69, 19.04.06)
- Chapter 3.4: Updated text and illustrations. New function: shiphandle mode (case 53, 30.03.06)
- Chapter 4.1: New function: time zone selection (case 98, 22.05.06)

Revision 1.5 (22.10.2006)
- Chapter 3.2: Updated illustration
- Chapter 3.2.6: Added description of RCU-018 ctrl field.
- Chapter 3.4: Updated illustration
- Chapter 3.5: Updated illustration
- Chapter 3.6: Updated illustration
- New Chapter 3.7 (Track Control)
- Compass Safe Distance table on page 1 updated
- Equipment Lists on page 5 updated
- Installation Overview illustration updated
- Specifications updated
- Updated mounting section
- Added mounting Chapter 1.3 Control Unit Furuno RCU-018
- Added Chapter 2.1, HT405P4 Wiring diagram
- Added Chapter 2.3, Processor connectors, HT405P4 TEL-A1
- Renumbered chapters following 2.1

Revision 1.6 (30.04.2007)
- Compass Safe Distances on page 1 updated
- Equipment List on page 5 updated
- Installation Overview illustration updated
- Specifications for HT 405P4 on page 7 updated
- Specifications for JH 23T02 on page 8 added

- Mounting dimensions for JH23T02 added to chapter 1.1 (page 17 and 18)
- New chapter: 1.6 Track Control: Anschütz NP 2025 PLUS

Revision 1.7 (17.10.2007)
- Section 2.5 Processor connectors, HT405P4 TEL-A1 on page 37 updated with information about ferrite placement.
- Section 3.2. NMEA data setup on page 41-44 updated with new illustration and information about status color coding.
- Section 3.5.1 Install, update or remove chart databases on page 49-50 updated with information about new function 'Remove Licenses'.

Revision 1.8 (15.11.2007)
- General introduction to the installation manual updated with new configuration data file.
- Section 1.6 updated with minimum sensor and other connection requirements for Track Control functionality, and requirements to ensure "freeze rudder" functionality.
- Section 6: Added checklists for Track Control system and installation notes

Revision 1.9 (16.04.2008)
- Changed heading for section 6.2 to include TECDIS AW
- Added new section 6.3 for additional TECDIS AW requirements checklist
- Old section 6.3 and 6.4 are now section 6.4 and 6.5
- New section 1.7 for NAUT AW gyro sensor input requirements

Revision 2.0 (20.01.2009)
- Updated to reflect changes in new software version 4.7.1
- Deprecated hardware options removed from equipment list, mounting and wiring chapters.

Revision 2.1 (17.11.2009)
- "General introduction to the installation manual" updated to include internet switch and installation checklist requirements.
- Section 2.3 Processor connectors, HT 405P4 TEL-A1 updated to include requirements for internet switch.
- Chapter 6 "Checklists regarding installation" updated.

Revision 2.2 (07.06.2010)
- "General introduction to the installation manual" updated to reflect that connection to UPS is no longer mandatory.
- Equipment list, Installation overview, specifications and Chapter 1 - Mounting sections expanded and updated to include new computer HT C01 TEL-A599, new display HD 19T03 and new flush mount keyboard/trackball options from Keytouch.
- Chapter 2 – Wiring and signal distribution updated with instructions for new computer HT C01 TEL-A599.
- Section 3.6.3 Dynamic Licensing expanded with information previously only found in separate documentation.
- New section 5.3 Internet/VSAT connection troubleshooting added.
- New section 2.4 Other notes regarding connectors and wiring added.

Revision 2.3 (28.10.2010)
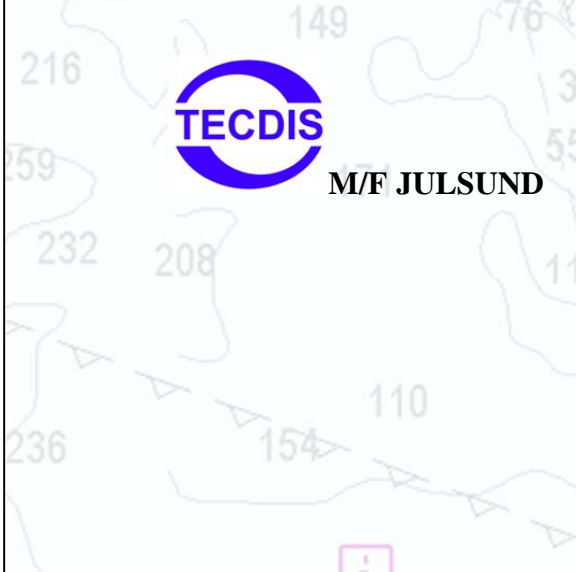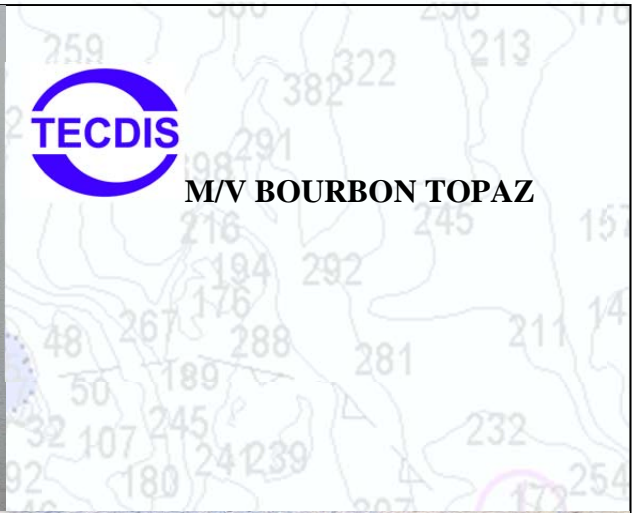- Compass safe distances for new equipment added to page 1.

- "General introduction to the installation manual" updated with reference to important installation instructions in Chapter 1 and Chapter 2.
- Equipment list, Installation overview, specifications and Chapter 1 - Mounting sections expanded and updated to include new computers HT C01 TEL-A596 and HT C01 TEL-D596, new displays JH 23T14 MMD, Furuno MU-201CE and Furuno MU-231CE and new keyboard Cherry G84-4100.
- Chapter 2 – Wiring and signal distribution updated with instructions for new computers HT C01 TEL-A596 and HT C01 TEL-D596.
- Section 3.2: NMEA Data updated with information on "Ex.input", "ALR/ACK" and "FLIR control".

Revision 2.4 (18.05.2012)
- New chapter 1.7 Track Control: Furuno FAP 2000- and EMRI SEM 200 Autopilot
- Reformatting all heading numbers and new Table of Contents
- Chapter 3.2 NMEA Data setup is rewritten to comply to new version of TECDIS Setup.
- Chapter 3.3 Specification is updated to describe the changes related to the "*Alarm*"-field and changes introduced by the functionality of the TSZ-files.
- Chapter 6.1, Checklist, requirement added for sending in TZS-files and added need for technician's company name to be filled in.
- Chapter 6.2, Checklist updated with two new Autopilot types, Furuno and EMRI

TECDIS

M/V BOURBON TOPAZ

TECDIS

M/F JULSUND